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	Engineering and Design	
	BEARING CAPACITY OF SOILS	
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DEPARTMENT OF THE ARMY U.S. Army Corps of Engineers Washington, DC 20314-1000

CECW-EG

Engineer Manual No. 1110-1-1905

30 October 1992

Engineering and Design BEARING CAPACITY OF SOILS

1. <u>Purpose</u>. The purpose of this manual is to provide guidelines for calculation of the bearing capacity of soil under shallow and deep foundations supporting various types of structures and embankments.

2. <u>Applicability</u>. This manual applies to HQUSACE/OCE elements, major subordinate commands, districts, laboratories, and field operating activities.

3. <u>General</u>. This manual is intended as a guide for determining allowable and ultimate bearing capacity. It is not intended to replace the judgment of the design engineer on a particular project.

FOR THE COMMANDER:

WILLIAM D. BROWN Colonel, Corps of Engineers Chief of Staff

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CHAPTER 1

INTRODUCTION

1-1. <u>Purpose and Scope.</u> This manual presents guidelines for calculation of the bearing capacity of soil under shallow and deep foundations supporting various types of structures and embankments. This information is generally applicable to foundation investigation and design conducted by Corps of Engineer agencies.

a. **Applicability.** Principles for evaluating bearing capacity presented in this manual are applicable to numerous types of structures such as buildings and houses, towers and storage tanks, fills, embankments and dams. These guidelines may be helpful in determining soils that will lead to bearing capacity failure or excessive settlements for given foundations and loads.

b. **Evaluation.** Bearing capacity evaluation is presented in Table 1-1. Consideration should be given to obtaining the services and advice of specialists and consultants in foundation design where foundation conditions are unusual or critical or structures are economically significant.

(1) Definitions, failure modes and factors that influence bearing capacity are given in Chapter 1.

(2) Evaluation of bearing capacity can be complicated by environmental and soil conditions. Some of these non-load related design considerations are given in Chapter 2.

(3) Laboratory and in situ methods of determining soil parameters required for analysis of bearing capacity are given in Chapter 3.

(4) Analysis of the bearing capacity of shallow foundations is given in Chapter 4 and of deep foundations is given in Chapter 5.

c. **Limitations.** This manual presents estimates of obtaining the bearing capacity of shallow and deep foundations for certain soil and foundation conditions using well-established, approximate solutions of bearing capacity.

(1) This manual excludes analysis of the bearing capacity of foundations in rock.

(2) This manual excludes analysis of bearing capacity influenced by seismic forces.

(3) Refer to EM 1110-2-1902, Stability of Earth and Rockfill Dams, for solution of the slope stability of embankments.

d. **References.** Standard references pertaining to this manual are listed in Appendix A, References. Each reference is identified in the text by the designated Government publication number or performing agency. Additional reading materials are listed in Appendix B, Bibliography.

TABLE 1-1

Bearing Capacity Evaluation

Step	Procedure
1	Evaluate the ultimate bearing capacity pressure q_u or bearing force Q_u using guidelines in this manual and Equation 1-1.
2	Determine a reasonable factor of safety FS based on available subsurface surface information, variability of the soil, soil layering and strengths, type and importance of the structure and past experience. FS will typically be between 2 and 4. Typical FS are given in Table 1-2.
3	Evaluate allowable bearing capacity q_a by dividing q_u by FS; i.e., $q_a = q_u/FS$, Equation 1-2a or $Q_a = Q_u/FS$, Equation 1-2b.
4	Perform settlement analysis when possible and adjust the bearing pressure until settlements are within tolerable limits. The resulting design bearing pressure q_d may be less than q_a . Settlement analysis is particularly needed when compressible layers are present beneath the depth of the zone of a potential bearing failure. Settlement analysis must be performed on important structures and those sensitive to settlement. Refer to EM 1110-1-1904 for settlement analysis of shallow foundations and embankments and EM 1110-2-2906, Reese and O'Neill (1988) and Vanikar (1986) for settlement of deep foundations.

1-2. **Definitions.**

a. Bearing Capacity. Bearing capacity is the ability of soil to safely carry the pressure placed on the soil from any engineered structure without undergoing a shear failure with accompanying large settlements. Applying a bearing pressure which is safe with respect to failure does not ensure that settlement of the foundation will be within acceptable limits. Therefore, settlement analysis should generally be performed since most structures are sensitive to excessive settlement.

(1) Ultimate Bearing Capacity. The generally accepted method of bearing capacity analysis is to assume that the soil below the foundation along a critical plane of failure (slip path) is on the verge of failure and to calculate the bearing pressure applied by the foundation required to cause this failure condition. This is the ultimate bearing capacity q_{u} . The general equation is

$$q_{u} = CN_{C}\zeta_{C} + \frac{1}{2}B\gamma_{H}'N_{\gamma}\zeta_{\gamma} + \sigma_{D}'N_{q}\zeta_{q}$$

$$Q_{u} = q_{u}BW$$
(1-1a)

(1-1b)

where

Q,,

= ultimate bearing capacity pressure, kips per square foot (ksf) \mathbf{q}_{u} = ultimate bearing capacity force, kips

С	= soil cohesion (or undrained shear strength C_{u}), ksf
В	= foundation width, ft
W	= foundation lateral length, ft
$\gamma_{\scriptscriptstyle m H}^{\prime}$	<pre>= effective unit weight beneath foundation base within failure zone, kips/ft³</pre>
σ_{D}'	= effective soil or surcharge pressure at the foundation depth D, $\gamma_{\text{D}}^{\prime} \cdot \text{D}, \ \text{ksf}$
γ_{D}'	= effective unit weight of surcharge soil within depth D, kips/ft ³
N_{c} , N_{γ} , N_{q}	= dimensionless bearing capacity factors for cohesion c, soil
	weight in the failure wedge, and surcharge q terms
ζ_{c} , ζ_{γ} , ζ_{q}	= dimensionless correction factors for cohesion, soil weight in

the failure wedge, and surcharge q terms accounting for foundation geometry and soil type

A description of factors that influence bearing capacity and calculation of γ'_{H} and γ'_{D} is given in section 1-4. Details for calculation of the dimensionless bearing capacity "N" and correction " ζ " factors are given in Chapter 4 for shallow foundations and in Chapter 5 for deep foundations.

(a) Bearing pressures exceeding the limiting shear resistance of the soil cause collapse of the structure which is usually accompanied by tilting. A bearing capacity failure results in very large downward movements of the structure, typically 0.5 ft to over 10 ft in magnitude. A bearing capacity failure of this type usually occurs within 1 day after the first full load is applied to the soil.

(b) Ultimate shear failure is seldom a controlling factor in design because few structures are able to tolerate the rather large deformations that occur in soil prior to failure. Excessive settlement and differential movement can cause distortion and cracking in structures, loss of freeboard and water retaining capacity of embankments and dams, misalignment of operating equipment, discomfort to occupants, and eventually structural failure. Therefore, settlement analyses must frequently be performed to establish the expected foundation settlement. Both total and differential settlement between critical parts of the structure must be compared with allowable values. Refer to EM 1110-1-1904 for further details.

(c) Calculation of the bearing pressure required for ultimate shear failure is useful where sufficient data are not available to perform a settlement analysis. A suitable safety factor can be applied to the calculated ultimate bearing pressure where sufficient experience and practice have established appropriate safety factors. Structures such as embankments and uniformly loaded tanks, silos, and mats founded on soft soils and designed to tolerate large settlements all may be susceptible to a base shear failure.

(2) Allowable Bearing Capacity. The allowable bearing capacity q_a is the ultimate bearing capacity q_u divided by an appropriate factor of safety FS,

$$q_a = \frac{q_u}{FS} \tag{1-2a}$$

$$Q_a = \frac{Q_u}{FS} \tag{1-2b}$$

FS is often determined to limit settlements to less than 1 inch and it is often in the range of 2 to 4.

(a) Settlement analysis should be performed to determine the maximum vertical foundation pressures which will keep settlements within the predetermined safe value for the given structure. The recommended design bearing pressure q_d or design bearing force Q_d could be less than q_a or Q_a due to settlement limitations.

(b) When practical, vertical pressures applied to supporting foundation soils which are preconsolidated should be kept less than the maximum past pressure (preconsolidation load) applied to the soil. This avoids the higher rate of settlement per unit pressure that occurs on the virgin consolidation settlement portion of the e-log p curve past the preconsolidation pressure. The e-log p curve and preconsolidation pressure are determined by performing laboratory consolidation tests, EM 1110-2-1906.

(3) **Factors of Safety.** Table 1-2 illustrates some factors of safety. These FS's are conservative and will generally limit settlement to acceptable values, but economy may be sacrificed in some cases.

(a) FS selected for design depends on the extent of information available on subsoil characteristics and their variability. A thorough and extensive subsoil investigation may permit use of smaller FS.

(b) FS should generally be ≥ 2.5 and never less than 2.

(c) FS in Table 1-2 for deep foundations are consistent with usual compression loads. Refer to EM 1110-2-2906 for FS to be used with other loads.

b. **Soil.** Soil is a mixture of irregularly shaped mineral particles of various sizes containing voids between particles. These voids may contain water if the soil is saturated, water and air if partly saturated, and air if dry. Under unusual conditions, such as sanitary landfills, gases other than air may be in the voids. The particles are a by-product of mechanical and chemical weathering of rock and described as gravels, sands, silts, and clays. Bearing capacity analysis requires a distinction between cohesive and cohesionless soils.

(1) **Cohesive Soil.** Cohesive soils are fine-grained materials consisting of silts, clays, and/or organic material. These soils exhibit low to high strength when unconfined and when air-dried depending on specific characteristics. Most cohesive soils are relatively impermeable compared with cohesionless soils. Some silts may have bonding agents between particles such as soluble salts or clay aggregates. Wetting of soluble agents bonding silt particles may cause settlement.

(2) **Cohesionless Soil.** Cohesionless soil is composed of granular or coarsegrained materials with visually detectable particle sizes and with little cohesion or adhesion between particles. These soils have little or no strength, particularly when dry, when unconfined and little or no cohesion when submerged. Strength occurs from internal friction when the material is confined. Apparent adhesion between particles in cohesionless soil may occur from capillary tension in the pore water. Cohesionless soils are usually relatively free-draining compared with cohesive soils.

1 - 4

TABLE 1-2

Structure		FS
Retaining Walls Temporary braced excavations	>	3 2
Bridges Railway Highway		4 3.5
Buildings Silos Warehouses Apartments, offices Light industrial, public		2.5 2.5* 3 3.5
Footings		3
Mats	>	3
Deep Foundations With load tests Driven piles with wave equation analysis calibrated to results of dynamic pile tests Without load tests Multilayer soils Groups		2 2.5 3 4 3

Typical Factors of Safety

*Modern warehouses often require superflat floors to accommodate modern transport equipment; these floors require extreme limitations to total and differential movements with FS > 3

c. **Foundations.** Foundations may be classified in terms of shallow and deep elements and retaining structures that distribute loads from structures to the underlying soil. Foundations must be designed to maintain soil pressures at all depths within the allowable bearing capacity of the soil and also must limit total and differential movements to within levels that can be tolerated by the structure.

(1) **Shallow Foundations.** Shallow foundations are usually placed within a depth D beneath the ground surface less than the minimum width B of the foundation. Shallow foundations consist of spread and continuous footings, wall footings and mats, Figure 1-1.

(a) A spread footing distributes column or other loads from the structure to the soil, Figure 1-1a, where $B \le W \le 10B$. A continuous footing is a spread footing where W > 10B.





a. SPREAD FOOTING

b. WALL FOOTING



c. FLAT MAT WITH d. RIBBED MAT MULTIPLE COLUMNS

Figure 1-1. Shallow Foundations

(b) A wall footing is a long load bearing footing, Figure 1-1b.

(c) A mat is continuous in two directions capable of supporting multiple columns, wall or floor loads. It has dimensions from 20 to 80 ft or more for houses and hundreds of feet for large structures such as multi-story hospitals and some warehouses, Figure 1-1c. Ribbed mats, Figure 1-1d, consisting of stiffening beams placed below a flat slab are useful in unstable soils such as expansive, collapsible or soft materials where differential movements can be significant (exceeding 0.5 inch).

(2) **Deep Foundations.** Deep foundations can be as short as 15 to 20 ft or as long as 200 ft or more and may consist of driven piles, drilled shafts or stone columns, Figure 1-2. A single drilled shaft often has greater load bearing capacity than a single pile. Deep foundations may be designed to carry superstructure loads

through poor soil (loose sands, soft clays, and collapsible materials) into competent bearing materials. Even when piles or drilled shafts are carried into competent materials, significant settlement can still occur if compressible soils are located below the tip of these deep foundations. Deep foundation support is usually more economical for depths less than 100 ft than mat foundations.

(a) A pile may consist of a timber pole, steel pipe section, H-beam, solid or hollow precast concrete section or other slender element driven into the ground using pile driving equipment, Figure 1-2a. Pile foundations are usually placed in groups often with spacings S of 3 to 3.5B where B is the pile diameter. Smaller spacings are often not desirable because of the potential for pile intersection and a reduction in load carrying capacity . A pile cap is necessary to spread vertical and horizontal loads and any overturning moments to all of the piles in the group. The cap of onshore structures usually consists of reinforced concrete cast on the ground, unless the soil is expansive. Offshore caps are often fabricated from steel.

(b) A drilled shaft is a bored hole carried down to a good bearing stratum and filled with concrete, Figure 1-2b. A drilled shaft often contains a cage of reinforcement steel to provide bending, tension, and compression resistance. Reinforcing steel is always needed if the shaft is subject to lateral or tensile loading. Drilled shaft foundations are often placed as single elements beneath a column with spacings greater than 8 times the width or diameter of the shaft. Other names for drilled shafts include bored and underreamed pile, pier and caisson. Auger-cast or auger-grout piles are included in this category because these are not driven, but installed by advancing a continous-flight hollow-stem auger to the required depth and filling the hole created by the auger with grout under pressure as the auger is withdrawn. Diameters may vary from 0.5 to 10 ft or more. Spacings > 8B lead to minimal interaction between adjacent drilled shafts so that bearing capacity of these foundations may be analyzed using equations for single shafts. Shafts bearing in rock (rock drilled piers) are often placed closer than 8 diameters.

(c) A stone column, Figure 1-2c, consists of granular (cohesionless) material of stone or sand often placed by vibroflotation in weak or soft subsurface soils with shear strengths from 0.2 to 1 ksf. The base of the column should rest on a dense stratum with adequate bearing capacity. The column is made by sinking the vibroflot or probe into the soil to the required depth using a water jet. While adding additional stone to backfill the cavity, the probe is raised and lowered to form a dense column. Stone columns usually are constructed to strengthen an area rather than to provide support for a limited size such as a single footing. Care is required when sensitive or peaty, organic soils are encountered. Construction should occur rapidly to limit vibration in sensitive soils. Peaty, organic soils may cause construction problems or poor performance. Stone columns are usually not as economical as piles or piers for supporting conventional type structures but are competitive when used to support embankments on soft soils, slopes, and remedial or new work for preventing liquefaction.

(d) The length L of a deep foundation may be placed at depths below ground surface such as for supporting basements where the pile length L \leq D, Figure 1-2a.



C. STONE COLUMNS

Figure 1-2. Deep foundations

(3) **Retaining Structures.** Any structure used to retain soil or other material in a shape or distribution different from that under the influence of gravity is a retaining structure. These structures may be permanent or temporary and consist of a variety of materials such as plain or reinforced concrete, reinforced soil, closely spaced piles or drilled shafts, and interlocking elments of wood, metal or concrete.

1-3. <u>Failure Modes.</u> The modes of potential failure caused by a footing of width B subject to a uniform pressure q develop the limiting soil shear strength τ_s at a given point along a slip path such as in Figure 1-3a



6. SHEAR IN SOFT OVER STIFF SOIL

Figure 1-3. General shear failure

$$\tau_{s} = c + \sigma_{n} \tan \phi \qquad (1-3)$$

where

 $\begin{aligned} \tau_{\rm s} &= \text{soil shear strength, ksf} \\ c &= \text{unit soil cohesion (undrained shear strength C_u), ksf} \\ \sigma_{\rm n} &= \text{normal stress on slip path, ksf} \\ \phi &= \text{friction angle of soil, deg} \end{aligned}$

From Figure 1-3a, the force on a unit width of footing causing shear is q_u times B, q_u 'B. The force resisting shear is τ_s times the length of the slip path 'abc' or τ_s 'abc'. The force resisting shear in a purely cohesive soil is c'abc' and in a purely friction soil $\sigma_n \tan \phi$ 'abc'. The length of the slip path 'abc' resisting failure increases in proportion to the width of footing B.

a. **General Shear.** Figure 1-3a illustrates right side rotation shear failure along a well defined and continuous slip path 'abc' which will result in bulging of the soil adjacent to the foundation. The wedge under the footing goes down and the soil is pushed to the side laterally and up. Surcharge above and outside the footing helps hold the block of soil down.

(1) **Description of Failure.** Most bearing capacity failures occur in general shear under stress controlled conditions and lead to tilting and sudden catastrophic type movement. For example, dense sands and saturated clays loaded rapidly are practically incompressible and may fail in general shear. After failure, a small increase in stress causes large additional settlement of the footing. The bulging of surface soil may be evident on the side of the foundation undergoing a shear failure. In relatively rare cases, some radial tension cracks may be present.

(a) Shear failure has been found to occur more frequently under shallow foundations supporting silos, tanks, and towers than under conventional buildings. Shear failure usually occurs on only one side because soils are not homogeneous and the load is often not concentric.

(b) Figure 1-3b illustrates shear failure in soft over rigid soil. The failure surface is squeezed by the rigid soil.

(2) **Depth of Failure.** Depth of shear zone H may be approximated by assuming that the maximum depth of shear failure occurs beneath the edge of the foundation, Figure 1-3a. If $\psi = 45 + \phi'/2$ (Vesic 1973), then

$$H = B \cdot \tan \psi \qquad (1-4a)$$

$$H = B \cdot \tan (45 + \frac{\Phi'}{2}) \qquad (1-4b)$$

where

The depth H for a shear failure will be 1.73B if $\phi' = 30^{\circ}$, a reasonable assumption for soils. H therefore should not usually be greater than 2B. If rigid material lies within 2B, then H will be < 2B and will not extend deeper than the depth of rigid material, Figure 1-3b. Refer to Leonards (1962) for an alternative method of determining the depth of failure.

(3) Horizontal Length of Failure. The length that the failure zone extends from the foundation perimeter at the foundation depth $L_{\rm sh}$, Figure 1-3a, may be approximated by

$$L_{sh} = (H+D) \operatorname{cot} \psi' = (H+D) \operatorname{tan} \psi$$
 (1-5a)

$$L_{sh} = (H+D)\tan(45 + \frac{\Phi'}{2})$$
 (1-5b)

where D is the depth of the foundation base beneath the ground surface and $\Psi' = 45 - \phi'/2$. $L_{\rm sh} \approx 1.73({\rm H} + {\rm D})$ if $\phi' = 30$ deg. The shear zone may extend horizontally about 3B from the foundation base. Refer to Leonards (1962) for an alternative method of determining the length of failure.

b. **Punching Shear.** Figure 1-4 illustrates punching shear failure along a wedge slip path 'abc'. Slip lines do not develop and little or no bulging occurs at the ground surface. Vertical movement associated with increased loads causes compression of the soil immediately beneath the foundation. Figure 1-4 also illustrates punching shear of stiff over soft soil.



Figure 1-4. Punching failure

(1) Vertical settlement may occur suddenly as a series of small movements without visible collapse or significant tilting. Punching failure is often associated with deep foundation elements, particularly in loose sands.

(2) Local shear is a punching-type failure and it is more likely to occur in loose sands, silty sands, and weak clays. Local shear failure is characterized by a slip path that is not well defined except immediately beneath the foundation. Failure is not catastrophic and tilting may be insignificant. Applied loads can continue to increase on the foundation soil following local shear failure.

c. Failure in Sand. The approximate limits of types of failure to be expected at relative depths D/B and relative density of sand D_R vary as shown in Figure 1-5. There is a critical relative depth below which only punching shear failure occurs. For circular foundations, this critical relative depth is about D/B = 4 and for long (L \approx 5B) rectangular foundations around D/B = 8. The limits of the types of failure depend upon the compressibility of the sand. More compressible materials will have lower critical depths (Vesic 1963).

1-4. **Factors Influencing Ultimate Bearing Capacity.** Principal factors that influence ultimate bearing capacities are type and strength of soil, foundation width and depth, soil weight in the shear zone, and surcharge. Structural rigidity and the contact stress distribution do not greatly influence bearing capacity. Bearing capacity analysis assumes a uniform contact pressure between the foundation and underlying soil.

a. **Soil Strength.** Many sedimentary soil deposits have an inherent anisotropic structure due to their common natural deposition in horizontal layers. Other soil deposits such as saprolites may also exhibit anisotropic properties. The undrained strength of cohesive soil and friction angle of cohesionless soil will be influenced by the direction of the major principal stress relative to the direction of deposition. This manual calculates bearing capacity using strength parameters determined when the major principal stress is applied in the direction of deposition.



Figure 1-5. Variation of the nature of bearing capacity failure in sand with relative density D_R and relative depth D/B (Vesic 1963). Reprinted by permission of the Transportation Research Board, Highway Research Record 39, "Bearing Capacity of Deep Foundations in Sands" by A. B. Vesic, p. 136

(1) Cohesive Soil. Bearing capacity of cohesive soil is proportional to soil cohesion c if the effective friction angle ϕ' is zero.

(2) Cohesionless Soil. Bearing capacity of cohesionless soil and mixed "c- ϕ " soils increases nonlinearly with increases in the effective friction angle.

b. Foundation Width. Foundation width influences ultimate bearing capacity in cohesionless soil. Foundation width also influences settlement, which is important in determining design loads. The theory of elasticity shows that, for an ideal soil whose properties do not change with stress level, settlement is proportional to foundation width.

(1) **Cohesive Soil.** The ultimate bearing capacity of cohesive soil of infinite depth and constant shear strength is independent of foundation width because c'abc'/B, Figure 1-3a, is constant.

(2) **Cohesionless Soil.** The ultimate bearing capacity of a footing placed at the surface of a cohesionless soil where soil shear strength largely depends on internal friction is directly proportional to the width of the bearing area.

c. **Foundation Depth.** Bearing capacity, particularly that of cohesionless soil, increases with foundation depth if the soil is uniform. Bearing capacity is reduced if the foundation is carried down to a weak stratum.

(1) The bearing capacity of larger footings with a slip path that intersects a rigid stratum will be greater than that of a smaller footing with a slip path that does not intersect a deeper rigid stratum, Figure 1-3.

(2) Foundations placed at depths where the structural weight equals the weight of displaced soil usually assures adequate bearing capacity and only recompression settlement. Exceptions include structures supported by underconsolidated soil and collapsible soil subject to wetting.

d. Soil Weight and Surcharge. Subsurface and surcharge soil weights contribute to bearing capacity as given in Equation 1-1. The depth to the water table influences the subsurface and surcharge soil weights, Figure 1-6. Water table depth can vary significantly with time.



Figure 1-6. Schematic of foundation system

(1) If the water table is below the depth of the failure surface, then the water table has no influence on the bearing capacity and effective unit weights γ'_{D} and γ'_{H} in Equation 1-1 are equal to the wet unit weight of the soils γ_{D} and γ_{H} .

(2) If the water table is above the failure surface and beneath the foundation base, then the effective unit weight $\gamma'_{\rm H}$ can be estimated as

$$\boldsymbol{\gamma}_{H}^{\prime} = \boldsymbol{\gamma}_{HSUB} + \frac{D_{GWT} - D}{H} \cdot \boldsymbol{\gamma}_{W}$$
(1-6)

where

(3) The water table should not be above the base of the foundation to avoid construction, seepage, and uplift problems. If the water table is above the base of the foundation, then the effective surcharge term $\sigma'_{\rm D}$ may be estimated by

$$\sigma'_D = \gamma'_D \cdot D \tag{1-7a}$$

$$\gamma_D' = \gamma_D - \frac{D - D_{GWT}}{D} \cdot \gamma_w \qquad (1 - 7b)$$

where

 $\begin{aligned} \sigma_{\scriptscriptstyle D}' &= \text{effective surcharge soil pressure at foundation depth D, ksf} \\ \gamma_{\scriptscriptstyle D} &= \text{unit wet weight of surcharge soil within depth D, kips/ft}^3 \\ D &= \text{depth of base below ground surface, ft} \end{aligned}$

(4) Refer to Figure 2, Chapter 4 in Department of the Navy (1982), for an alternative procedure of estimating depth of failure zone H and influence of groundwater on bearing capacity in cohesionless soil. The wet or saturated weight of soil above or below the water table is used in cohesive soil.

e. **Spacing Between Foundations.** Foundations on footings spaced sufficiently close together to intersect adjacent shear zones may decrease bearing capacity of each foundation. Spacings between footings should be at least 1.5B, to minimize any reduction in bearing capacity. Increases in settlement of existing facilities should be checked when placing new construction near existing facilities.

CHAPTER 2

NON-LOAD RELATED DESIGN CONSIDERATIONS

2-1. <u>General.</u> Special circumstances may complicate the evaluation of bearing capacity such as earthquake and dynamic motion, soil subject to frost action, subsurface voids, effects of expansive and collapsible soil, earth reinforcement, heave in cuts and scour and seepage erosion. This chapter briefly describes these applications. Coping with soil movements and ground improvement methods are discussed in TM 5-818-7, EM 1110-1-1904 and EM 1110-2-3506.

2-2. **Earthquake and Dynamic Motion.** Cyclic or repeated motion caused by seismic forces or earthquakes, vibrating machinery, and other disturbances such as vehicular traffic, blasting and pile driving may cause pore pressures to increase in foundation soil. As a result, bearing capacity will be reduced from the decreased soil strength. The foundation soil can liquify when pore pressures equal or exceed the soil confining stress reducing effective stress to zero and causes gross differential settlement of structures and loss of bearing capacity. Structures supported by shallow foundations can tilt and exhibit large differential movement and structural damage. Deep foundations lose lateral support as a result of liquefaction and horizontal shear forces lead to buckling and failure. The potential for soil liquefaction and structural damage may be reduced by various soil improvement methods.

a. **Corps of Engineer Method.** Methods of estimating bearing capacity of soil subject to dynamic action depend on methods of correcting for the change in soil shear strength caused by changes in pore pressure. Differential movements increase with increasing vibration and can cause substantial damage to structures. Department of the Navy (1983), "Soil Dynamics, Deep Stabilization, and Special Geotechnical Construction", describes evaluation of vibration induced settlement.

b. Cohesive Soil. Dynamic forces on conservatively designed foundations with $FS \ge 3$ will probably have little influence on performance of structures. Limited data indicate that strength reduction during cyclic loading will likely not exceed 20 percent in medium to stiff clays (Edinger 1989). However, vibration induced settlement should be estimated to be sure structural damages will not be significant.

c. **Cohesionless Soil.** Dynamic forces may significantly reduce bearing capacity in sand. Foundations conservatively designed to support static and earthquake forces will likely fail only during severe earthquakes and only when liquefaction occurs (Edinger 1989). Potential for settlement large enough to adversely influence foundation performance is most likely in deep beds of loose dry sand or saturated sand subject to liquefaction. Displacements leading to structural damage can occur in more compact sands, even with relative densities approaching 90 percent, if vibrations are sufficient. The potential for liquefaction should be analyzed as described in EM 1110-1-1904.

2-3. <u>Frost Action</u>. Frost heave in certain soils in contact with water and subject to freezing temperatures or loss of strength of frozen soil upon thawing can alter bearing capacity over time. Frost heave at below freezing temperatures occurs from

formation of ice lenses in frost susceptible soil. As water freezes to increase the volume of the ice lense the pore pressure of the remaining unfrozen water decreases and tends to draw additional warmer water from deeper depths. Soil below the depth of frost action tends to become dryer and consolidate, while soil within the depth of frost action tends to be wetter and contain fissures. The base of foundations should be below the depth of frost action. Refer to TM 5-852-4 and Lobacz (1986).

a. **Frost Susceptible Soils.** Soils most susceptible to frost action are low cohesion materials containing a high percentage of silt-sized particles. These soils have a network of pores and fissures that promote migration of water to the freezing front. Common frost susceptible soils include silts (ML, MH), silty sands (SM), and low plasticity clays (CL, CL-ML).

b. Depth of Frost Action. The depth of frost action depends on the air temperature below freezing and duration, surface cover, soil thermal conductivity and permeability and soil water content. Refer to TM 5-852-4 for methodology to estimate the depth of frost action in the United States from air-freezing index values. TM 5-852-6 provides calculation methods for determining freeze and thaw depths in soils. Figure 2-1 provides approximate frost-depth contours in the United States.

c. Control of Frost Action. Methods to reduce frost action are preferred if the depth and amount of frost heave is unpredictable.

(1) Replace frost-susceptible soils with materials unaffected by frost such as clean medium to coarse sands and clean gravels, if these are readily available.

(2) Pressure inject the soil with lime slurry or lime-flyash slurry to decrease the mass permeability.



Figure 2-1. Approximate frost-depth contours in the United States. Reprinted by permission of McGraw-Hill Book Company, "Foundation Analysis and Design", p. 305, 1988, by J. E. Bowles (3) Restrict the groundwater supply by increased drainage and/or an impervious layer of asphalt, plastic or clay.

(4) Place a layer of thermal insulation such as foamed plastic or glass.

2-4. **Subsurface Voids.** A subsurface void influences and decreases bearing capacity when located within a critical depth D_c beneath the foundation. The critical depth is that depth below which the influence of pressure in the soil from the foundation is negligible. Evaluation of D_c is described in section 3-3b.

a. **Voids.** Voids located beneath strip foundations at depth ratios $D_c/B > 4$ cause little influence on bearing capacity for strip footings. B is the foundation width. The critical depth ratio for square footings is about 2.

b. **Bearing Capacity.** The bearing capacity of a strip footing underlain by a centrally located void at ratios $D_c/B < 4$ decreases with increasing load eccentricity similar to that for footings without voids, but the void reduces the effect of load eccentricity. Although voids may not influence bearing capacity initially, these voids can gradually migrate upward with time in karst regions.

c. **Complication of Calculation.** Load eccentricity and load inclination complicate calculation of bearing capacity when the void is close to the footing. Refer to Wang, Yoo and Hsieh (1987) for further information.

2-5. **Expansive and Collapsible Soils.** These soils change volume from changes in water content leading to total and differential foundation movements. Seasonal wetting and drying cycles have caused soil movements that often lead to excessive long-term deterioration of structures with substantial accumulative damage. These soils can have large strengths and bearing capacity when relatively dry.

a. **Expansive Soil.** Expansive soils consist of plastic clays and clay shales that often contain colloidal clay minerals such as the montmorillonites. They include marls, clayey siltstone and sandstone, and saprolites. Some of these soils, especially dry residual clayey soil, may heave under low applied pressure but collapse under higher pressure. Other soils may collapse initially but heave later on. Estimates of the potential heave of these soils are necessary for consideration in the foundation design.

(1) **Identification.** Degrees of expansive potential may be indicated as follows (Snethen, Johnson, and Patrick 1977):

Degree of	Liquid	Plasticity	Natural Soil
Expansion	Limit, %	Index, 🗞	Suction, tsf
High	> 60	> 35	> 4.0
Marginal	50-60	25-35	1.5-4.0
Low	< 50	< 25	< 1.5

Soils with Liquid Limit (LL) < 35 and Plasticity Index (PI) < 12 have no potential for swell and need not be tested.

(2) **Potential Heave.** The potential heave of expansive soils should be determined from results of consolidometer tests, ASTM D 4546. These heave estimates should then be considered in determining preparation of foundation soils to reduce destructive differential movements and to provide a foundation of sufficient capacity to withstand or isolate the expected soil heave. Refer to TM 5-818-7 and EM 1110-1-1904 for further information on analysis and design of foundations on expansive soils.

b. **Collapsible Soil.** Collapsible soils will settle without any additional applied pressure when sufficient water becomes available to the soil. Water weakens or destroys bonding material between particles that can severely reduce the bearing capacity of the original soil. The collapse potential of these soils must be determined for consideration in the foundation design.

(1) **Identification.** Many collapsible soils are mudflow or windblown silt deposits of loess often found in arid or semiarid climates such as deserts, but dry climates are not necessary for collapsible soil. Typical collapsible soils are lightly colored, low in plasticity with LL < 45, PI < 25 and with relatively low densities between 65 and 105 lbs/ft³ (60 to 40 percent porosity). Collapse rarely occurs in soil with porosity less than 40 percent. Refer to EM 1110-1-1904 for methods of identifying collapsible soil.

(2) **Potential Collapse.** The potential for collapse should be determined from results of a consolidometer test as described in EM 1110-1-1904. The soil may then be modified as needed using soil improvement methods to reduce or eliminate the potential for collapse.

2-6. <u>Soil Reinforcement.</u> Soil reinforcement allows new construction to be placed in soils that were originally less than satisfactory. The bearing capacity of weak or soft soil may be substantially increased by placing various forms of reinforcement in the soil such as metal ties, strips, or grids, geotextile fabrics, or granular materials.

a. **Earth Reinforcement.** Earth reinforcement consists of a bed of granular soil strengthened with horizontal layers of flat metal strips, ties, or grids of high tensile strength material that develop a good frictional bond with the soil. The bed of reinforced soil must intersect the expected slip paths of shear failure, Figure 1-3a. The increase in bearing capacity is a function of the tensile load developed in any tie, breaking strength and pullout friction resistance of each tie and the stiffness of the soil and reinforcement materials.

(1) An example calculation of the design of a reinforced slab is provided in Binquet and Lee (1975).

(2) Slope stability package UTEXAS2 (Edris 1987) may be used to perform an analysis of the bearing capacity of either the unreinforced or reinforced soil beneath a foundation. A small slope of about 1 degree must be used to allow the computer program to operate. The program will calculate the bearing capacity of the weakest slip path, Figure 1-3a, of infinite length (wall) footings, foundations, or embankments.

b. Geotextile Horizontal Reinforcement. High strength geotextile fabrics placed on the surface under the proper conditions allow construction of embankments and other structures on soft foundation soils that normally will not otherwise support pedestrian traffic, vehicles, or conventional construction equipment. Without adequate soil reinforcement, the embankment may fail during or after construction by shallow or deep-seated sliding wedge or circular arc-type failures or by excessive subsidence caused by soil creep, consolidation or bearing capacity shear failure. Fabrics can contribute toward a solution to these problems. Refer to TM 5-800-08 for further information on analysis and design of embankment slope stability, embankment sliding, embankment spreading, embankment rotational displacement, and longitudinal fabric strength reinforcement.

(1) **Control of Horizontal Spreading.** Excessive horizontal sliding, splitting, and spreading of embankments and foundation soils may occur from large lateral earth pressures caused by embankment soils. Fabric reinforcement between a soft foundation soil and embankment fill materials provides forces that resist the tendency to spread horizontally. Failure of fabric reinforced embankments may occur by slippage between the fabric and fill material, fabric tensile failure, or excessive fabric elongation. These failure modes may be prevented by specifyng fabrics of required soil-fabric friction, tensile strength, and tensile modulus.

(2) **Control of Rotational Failure.** Rotational slope and/or foundation failures are resisted by the use of fabrics with adequate tensile strength and embankment materials with adequate shear strength. Rotational failure occurs through the embankment, foundation layer, and the fabric. The tensile strength of the fabric must be sufficiently high to control the large unbalanced rotational moments. Computer program UTEXAS2 (Edris 1987) may be used to determine slope stability analysis with and without reinforcement to aid in the analysis and design of embankments on soft soil.

(3) **Control of Bearing Capacity Failure.** Soft foundations supporting embankments may fail in bearing capacity during or soon after construction before consolidation of the foundation soil can occur. When consolidation does occur, settlement will be similar for either fabric reinforced or unreinforced embankments. Settlement of fabric reinforced embankments will often be more uniform than nonreinforced embankments.

(a) Fabric reinforcement helps to hold the embankment together while the foundation strength increases through consolidation.

(b) Large movements or center sag of embankments may be caused by improper construction such as working in the center of the embankment before the fabric edges are covered with fill material to provide a berm and fabric anchorage. Fabric tensile strength will not be mobilized and benefit will not be gained from the fabric if the fabric is not anchored.

(c) A bearing failure and center sag may occur when fabrics with insufficient tensile strength and modulus are used, when steep embankments are constructed, or when edge anchorage of fabrics is insufficient to control embankment splitting. If

the bearing capacity of the foundation soil is exceeded, the fabric must elongate to develop the required fabric stress to support the embankment load. The foundation soil will deform until the foundation is capable of carrying the excessive stresses that are not carried in the fabric. Complete failure occurs if the fabric breaks.

c. **Granular Column in Weak Soil.** A granular column supporting a shallow rectangular footing in loose sand or weak clay will increase the ultimate bearing capacity of the foundation.

(1) The maximum bearing capacity of the improved foundation of a granular column supporting a rectangular foundation of identical cross-section is given approximately by (Das 1987)

$$q_{u} = K_{p} [\gamma_{c} D + 2(1 + \frac{B}{L}) C_{u}]$$
(2-1)

where

 K_p = Rankine passive pressure coefficient, $\frac{1 + \sin \phi_g}{1 - \sin \phi_g}$ ϕ_g = friction angle of granular material, degrees γ_c = moist unit weight of weak clay, kip/ft³

 ${\tt D}$ = depth of the rectangle foundation below ground surface, ft

B = width of foundation, ft

L = length of foundation, ft

 $\rm C_{u}$ = undrained shear strength of weak clay, ksf

Equation 2-1 is based on the assumption of a bulging failure of the granular column.

(2) The minimum height of the granular column required to support the footing and to obtain the maximum increase in bearing capacity is 3B.

(3) Refer to Bachus and Barksdale (1989) and Barksdale and Bachus (1983) for further details on analysis of bearing capacity of stone columns.

2-7. <u>Heaving Failure in Cuts.</u> Open excavations in deep deposits of soft clay may fail by heaving because the weight of clay beside the cut pushes the underlying clay up into the cut, Figure 2-2 (Terzaghi and Peck 1967). This results in a loss of ground at the ground surface. The bearing capacity of the clay at the bottom of the cut is C_uN_c . The bearing capacity factor N_c depends on the shape of the cut. N_c may be taken equal to that for a footing of the same B/W and D/B ratios as provided by the chart in Figure 2-3, where B is the excavation width, W is the excavation length, and D is the excavation depth below ground surface.

a. **Factor of Safety.** FS against a heave failure is FS against a heave failure should be at least 1.5. FS resisting heave at the excavation bottom caused by seepage should be 1.5 to 2.0 (TM 5-818-5).

$$FS = \frac{C_u N_c}{\gamma D} > 1.5 \tag{2-2}$$



Figure 2-2. Heave failure in an excavation



Figure 2-3. Estimation of bearing capacity factor $\rm ~N_{c}$ for heave in an excavation (Data from Terzaghi and Peck 1967)

b. Minimizing Heave Failure. Extending continuous sheet pile beneath the bottom of the excavation will reduce the tendency for heave.

(1) Sheet pile, even if the clay depth is large, will reduce flow into the excavation compared with pile and lagging support.

(2) Driving the sheet pile into a hard underlying stratum below the excavation greatly reduces the tendency for a heave failure.

2-8. <u>Soil Erosion and Seepage</u>. Erosion of soil around and under foundations and seepage can reduce bearing capacity and can cause foundation failure.

a. **Scour.** Foundations such as drilled shafts and piles constructed in flowing water will cause the flow to divert around the foundation. The velocity of flow will increase around the foundation and can cause the flow to separate from the foundation. A wake develops behind the foundation and turbulence can occur. Eddy currents contrary to the stream flow is the basic scour mechanism. The foundation must be constructed at a sufficient depth beneath the maximum scour depth to provide sufficient bearing capacity.

(1) Scour Around Drilled Shafts or Piles in Seawater. The scour depth may be estimated from empirical and experimental studies. Refer to Herbich, Schiller and Dunlap (1984) for further information.

(a) The maximum scour depth to wave height ratio is \leq 0.2 for a medium to fine sand.

(b) The maximum depth of scour $\,S_u\,$ as a function of Reynolds number $\,R_e\,$ is (Herbich, Schiller and Dunlap 1984)

$$S_{u} = 0.00073R_{e}^{0.619}$$
 (2-3)

where S_u is in feet.

(2) **Scour Around Pipelines.** Currents near pipelines strong enough to cause scour will gradually erode away the soil causing the pipeline to lose support. The maximum scour hole depth may be estimated using methodology in Herbich, Schiller, and Dunlap (1984).

(3) **Mitigation of Scour.** Rock-fill or riprap probably provides the easiest and most economical scour protection.

b. **Seepage.** Considerable damage can occur to structures when hydrostatic uplift pressure beneath foundations and behind retaining walls becomes too large. The uplift pressure head is the height of the free water table when there is no seepage. If seepage occurs, flow nets may be used to estimate uplift pressure. Uplift pressures are subtracted from total soil pressure to evaluate effective stresses. Effective stresses should be used in all bearing capacity calculations.

(1) Displacement piles penetrating into a confined hydrostatic head will be subject to uplift and may raise the piles from their end bearing.

(2) Seepage around piles can reduce skin friction. Skin friction resistance can become less than the hydrostatic uplift pressure and can substantially reduce bearing capacity. Redriving piles or performing load tests after a waiting period following construction can determine if bearing capacity is sufficient.

CHAPTER 3

SOIL PARAMETERS

3-1. <u>Methodology</u>. A site investigation and soil exploration program of the proposed construction area should be initially completed to obtain data required for analysis of bearing capacity. Estimates of ultimate and allowable bearing capacity using analytical equations that model the shear failure of the structure along slip surfaces in the soil and methods for analyzing in situ test results that model the bearing pressures of the full size structure in the soil may then be carried out as described in Chapter 4 for shallow foundations and Chapter 5 for deep foundations. The scope of the analysis depends on the magnitude of the project and on how critical the bearing capacity of the soil is to the performance of the structure.

a. Soil Parameters. The natural variability of soil profiles requires realistic assessment of soil parameters by soil exploration and testing. Soil parameters required for analysis of bearing capacity are shear strength, depth to groundwater or the pore water pressure profile, and the distribution of total vertical overburden pressure with depth. The shear strength parameters required are the undrained shear strength C_u of cohesive soils, the effective angle of internal friction ϕ' for cohesionless soils, and the effective cohesion c' and angle of internal friction ϕ' for mixed soils that exhibit both cohesion and friction.

b. **Use of Judgment.** Judgment is required to characterize the foundation soils into one or a few layers with idealized parameters. The potential for longterm consolidation and settlement must be determined, especially where soft, compressible soil layers are present beneath the foundation. Assumptions made by the designer may significantly influence recommendations of the foundation design.

c. Acceptability of Analysis. Acceptability of the bearing pressures applied to the foundation soil is usually judged by factors of safety applied to the ultimate bearing capacity and estimates made of potential settlement for the bearing pressures allowed on the foundation soil. The dimensions of the foundation or footing may subsequently be adjusted if required.

3-2. <u>Site Investigation.</u> Initially, the behavior of existing structures supported on similar soil in the same locality should be determined as well as the applied bearing pressures. These findings should be incorporated, using judgment, into the foundation design. A detailed subsurface exploration including disturbed and undisturbed samples for laboratory strength tests should then be carried out. Bearing capacity estimates may also be made from results of in situ soil tests. Refer to EM 1110-1-1804 for further information on site investigations.

a. **Examination of Existing Records.** A study of available service records and, where practical, a field inspection of structures supported by similar foundations in the bearing soil will furnish a valuable guide to probable bearing capacities.

(1) **Local Building Codes.** Local building codes may give presumptive allowable bearing pressures based on past experience. This information should only be used to supplement the findings of in situ tests and analyses using one or more

methods discussed subsequently because actual field conditions, and hence bearing pressures, are rarely identical with those conditions used to determine the presumptive allowable bearing pressures.

(2) Soil Exploration Records. Existing records of previous site investigations near the proposed construction area should be examined to determine the general subsurface condition including the types of soils likely to be present, probable depths to groundwater level and changes in groundwater level, shear strength parameters, and compressibility characteristics.

b. **Site Characteristics.** The proposed construction site should be examined for plasticity and fissures of surface soils, type of vegetation, and drainage pattern.

(1) **Desiccation Cracking.** Numerous desiccation cracks, fissures, and even slickensides can develop in plastic, expansive soils within the depth subject to seasonal moisture changes, the active zone depth Z_a , due to the volume change that occurs during repeated cycles of wetting and drying (desiccation). These volume changes can cause foundation movements that control the foundation design.

(2) **Vegetation.** Vegetation desiccates the foundation soil from transpiration through leaves. Heavy vegetation such as trees and shrubs can desiccate foundation soil to substantial depths exceeding 50 or 60 ft. Removal of substantial vegetation in the proposed construction area may lead to significantly higher water tables after construction is complete and may influence bearing capacity.

(3) **Drainage.** The ground surface should be sloped to provide adequate runoff of surface and rainwater from the construction area to promote trafficability and to minimize future changes in ground moisture and soil strength. Minimum slope should be 1 percent.

(4) **Performance of Adjacent Structures.** Distortion and cracking patterns in nearby structures indicate soil deformation and the possible presence of expansive or collapsible soils.

c. In Situ Soil Tests. In the absence of laboratory shear strength tests, soil strength parameters required for bearing capacity analysis may be estimated from results of in situ tests using empirical correlation factors. Empirical correlation factors should be verified by comparing estimated values with shear strengths determined from laboratory tests. The effective angle of internal friction ϕ' of cohesionless soil is frequently estimated from field test results because of difficulty in obtaining undisturbed cohesionless soil samples for laboratory soil tests.

(1) **Relative Density and Gradation.** Relative density and gradation can be used to estimate the friction angle of cohesionless soils, Table 3-1a. Relative density is a measure of how dense a sand is compared with its maximum density.

TABLE 3-1

Angle of Internal Friction of Sands, ϕ'

Relative Density	Fine	e Grained	Mediu	um Grained	Coars	se Grained
-	Uniform	Well-graded	Uniform	Well-graded	Uniform	Well-graded
40	34	36	36	38	38	41
60	36	38	38	41	41	43
80	39	41	41	43	43	44
100	42	43	43	44	44	46

a. Relative Density and Gradation (Data from Schmertmann 1978)

b. Relative Density and In Situ Soil Tests

		Standard	Cone	Frict	tion Angle ϕ' ,	deg
Soil Type	Relative Density	Penetration Resistance	Penetration Resistance	Meyerhof	Peck, Hanson	Meyerhof
	D _r ,	N ₆₀ (Terzaghi	q_{c} , ksf	(1974)	and Thornburn	(1974)
	Percent	and Peck 1967)	(Meyerhof 1974)		(1974)	
Very Loose	< 20	< 4		< 30	< 29	< 30
Loose	20 - 40	4 - 10	0 - 100	30 - 35	29 - 30	30 - 35
Medium	40 - 60	10 - 30	100 - 300	35 - 38	30 - 36	35 - 40
Dense	60 - 80	30 - 50	300 - 500	38 - 41	36 - 41	40 - 45
Very Dense	> 80	> 50	500 - 800	41 - 44	> 41	> 45

(a) ASTM D 653 defines relative density as the ratio of the difference in void ratio of a cohesionless soil in the loosest state at any given void ratio to the difference between the void ratios in the loosest and in the densest states. A very loose sand has a relative density of 0 percent and 100 percent in the densest possible state. Extremely loose honeycombed sands may have a negative relative density.

(b) Relative density may be calculated using standard test methods ASTM D 4254 and the void ratio of the in situ cohesionless soil,

$$D_{r} = \frac{e_{\max} - e}{e_{\max} - e_{\min}} \cdot 100$$
 (3-1a)

$$e = \frac{G}{\gamma_d} \cdot \gamma_w - 1 \tag{3-1b}$$

where

The specific gravity of the mineral solids may be determined using standard test method ASTM D 854. The dry density of soils that may be excavated can be determined in situ using standard test method ASTM D 1556.

(2) Standard Penetration Test (SPT). The standard penetration resistance value $N_{\rm SPT}$, often referred to as the blowcount, is frequently used to estimate the relative density of cohesionless soil. $N_{\rm SPT}$ is the number of blows required to drive a standard splitspoon sampler (1.42" I.D., 2.00" O.D.) 1 ft. The split spoon sampler is driven by a 140-lb hammer falling 30 inches. The sampler is driven 18 inches and blows counted for the last 12 inches. $N_{\rm SPT}$ may be determined using standard method ASTM D 1586.

(a) The $\,N_{_{\rm SPT}}\,$ value may be normalized to an effective energy delivered to the drill rod at 60 percent of theoretical free-fall energy

$$N_{60} = C_{RR} \cdot C_N \cdot N_{SPT} \tag{3-2}$$

where

 N_{60} = penetration resistance normalized to an effective energy delivered to the drill rod at 60 percent of theoretical free-fall energy, blows/ft C_{ER} = rod energy correction factor, Table 3-2a C_{N} = overburden correction factor, Table 3-2b

 $\rm N_{\rm SPT}~$ may have an effective energy delivered to the drill rod 50 to 55 percent of theoretical free fall energy.

(b) Table 3-1 illustrates some relative density and N_{60} correlations with the angle of internal friction. Relative density may also be related with N_{60} through Table 3-2c.

(c) The relative density of sands may be estimated from the $\rm N_{spt}$ by (Data from Gibbs and Holtz 1957)

 $D_r \approx 100 \left(\frac{N_{SPT}}{12\sigma'_{vo} + 17} \right)^{0.5}$ (3-3a)

where $D_{\rm r}$ is in percent and $\sigma'_{_{\rm VO}}$ is the effective vertical overburden pressure, ksf.

(d) The relative density of sands may also be estimated from N_{60} by (Jamiolkowski et al. 1988, Skempton 1986)

 $D_r \approx 100 \left(\frac{N_{60}}{60}\right)^{0.5}$ (3-3b)

where $D_{\rm r} \geq 35$ percent. N_{60} should be multiplied by 0.92 for coarse sands and 1.08 for fine sands.

(e) The undrained shear strength C_u in ksf may be estimated (Bowles 1988)

$$C_{u} \approx 0.12 N_{SPT} \tag{3-4}$$

TABLE 3-2

Relative Density and N₆₀

a. Rod Energy Correction Factor C_{ER} (Data from Tokimatsu and Seed 1987)

Country	Hammer	Hammer Release	C_{ER}
Japan	Donut Donut	Free-Fall Rope and Pulley	1.3 1.12*
	Donac	with special throw release	1.12
USA	Safety	Rope and Pulley	1.00*
	Donut	Rope and Pulley	0.75
Europe	Donut	Free-Fall	1.00*
China	Donut	Free-Fall	1.00*
	Donut	Rope and Pulley	0.83

*Methods used in USA

b. Correction Factor $C_{\!\scriptscriptstyle N}$ (Data from Tokimatsu and Seed 1984)

C _N	$\sigma_{\rm vo}^{\prime}^{\star}$, ksf
1.6	0.6
1.3	1.0
1.0	2.0
0.7	4.0
0.55	6.0
0.50	8.0

 $\ast \sigma_{\scriptscriptstyle \mathrm{vo}}^{\,\prime}$ = effective overburden pressure

c. Relative Density versus $\rm N_{60}$ (Data from Jamiolkowski et al. 1988)

Sand	$\rm D_{r}$, Percent	N ₆₀
Very Loose Loose Medium Dense Very Dense	$\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$	$\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$

(3) **Cone penetration test (CPT).** The CPT may be used to estimate both relative density of cohesionless soil and undrained strength of cohesive soils through empirical correlations. The CPT is especially suitable for sands and preferable to the SPT. The CPT may be performed using ASTM D 3441.

(a) The relative density of several different sands can be estimated by (Jamiolkowski et al. 1988)

$$D_r = -74 + 66 \cdot \log_{10} \frac{q_c}{(\sigma'_{vo})^{0.5}}$$
(3-5)

where the cone penetration resistance q_c and effective vertical overburden pressure σ'_{vo} are in units of ksf. The effective angle of internal friction ϕ' can be estimated from D_r using Table 3-1a. Table 3-1b provides a direct correlation of q_c with ϕ' .

(b) The effective angle of internal friction decreases with increasing for a given q_c as approximately shown in Figure 3-1. Increasing confining pressure reduces ϕ' for a given q_c because the Mohr-Coulomb shear strength envelope is nonlinear and has a smaller slope with increasing confining pressure.



Figure 3-1. Approximate correlation between cone penetration resistance, peak effective friction angle and vertical effective overburden pressure for uncemented quartz sand (After Robertson and Campanella 1983)

(c) The undrained strength $\,C_{\!u}\,$ of cohesive soils can be estimated from (Schmertmann 1978)

$$C_u = \frac{\boldsymbol{q}_c - \boldsymbol{\sigma}_{vo}}{N_k} \tag{3-6}$$

where C_u , q_c , and the total vertical overburden pressure σ_{vo} are in ksf units. The cone factor N_k should be determined using comparisons of C_u from laboratory undrained strength tests with the corresponding value of q_c obtained from the CPT. Equation 3-6 is useful to determine the distribution of undrained strength with depth when only a few laboratory undrained strength tests have been performed. N_k often varies from 14 to 20.

(4) **Dilatometer Test (DMT).** The DMT can be used to estimate the overconsolidation ratio (OCR) distribution in the foundation soil. The OCR can be used in estimating the undrained strength. The OCR is estimated from the horizontal stress index K_p by (Baldi et al 1986; Jamiolkowski et al 1988)

$$OCR = (0.5K_p)^{1.56} \quad if \ I_p \le 1.2$$
 (3-7a)

$$K_{D} = \frac{\mathcal{P}_{o} - \mathcal{U}_{W}}{\sigma'_{VO}} \tag{3-7b}$$

$$I_{D} = \frac{P_{1} - P_{o}}{P_{1} - u_{w}}$$
(3-7c)

where

- \mathbf{p}_{o} = internal pressure causing lift-off of the dilatometeter membrane, ksf
- \mathbf{u}_{w} = in situ hydrostatic pore pressure, ksf
- ${\rm p_1}$ = internal pressure required to expand the central point of the dilatometer membrane by \approx 1.1 millimeters
- K_{D} = horizontal stress index
- I_{D} = material deposit index

The OCR typically varies from 1 to 3 for lightly overconsolidated soil and 6 to 8 for heavily overconsolidated soil.

(5) **Pressuremeter Test (PMT).** The PMT can be used to estimate the undrained strength and the OCR. The PMT may be performed using ASTM D 4719.

(a) The limit pressure $\,p_{\rm \scriptscriptstyle L}\,$ estimated from the PMT can be used to estimate the undrained strength by (Mair and Wood 1987)

$$C_u = \frac{\mathbf{p}_L - \mathbf{\sigma}_{ho}}{N_p} \tag{3-8a}$$

$$N_p = 1 + \ln \frac{G_s}{C_n} \tag{3-8b}$$

where

 p_L , σ_{ho} , and G_s are found from results of the PMT. Equation 3-8b requires an estimate of the shear strength to solve for N_p . N_p may be initially estimated as some integer value from 3 to 8 such as 6. The undrained strength is then determined from Equation 3-8a and the result substituted into Equation 3-8b. One or two iterations should be sufficient to evaluate C_p .

(b) $\sigma_{\rm ho}$ can be used to estimate the OCR from $\sigma'_{\rm ho}/\sigma'_{\rm vo}$ if the pore water pressure and total vertical pressure distribution with depth are known or estimated.

(6) Field Vane Shear Test (FVT). The FVT is commonly used to estimate the in situ undrained shear strength C_u of soft to firm cohesive soils. This test should be used with other tests when evaluating the soil shear strength. The test may be performed by hand or may be completed using sophisticated equipment. Details of the test are provided in ASTM D 2573.

(a) The undrained shear strength C_u in ksf units is

$$C_u = \frac{T_v}{K_v} \tag{3-9}$$

where

 $T_{\rm v}$ = vane torque, kips ft $K_{\rm v}$ = constant depending on the dimensions and shape of the vane, ft 3

(b) The constant $\,K_{\!_{\rm v}}\,$ may be estimated for a rectangular vane causing a cylinder in a cohesive soil of uniform shear strength by

$$K_{v} = \frac{\pi}{1728} \cdot \frac{d_{v}^{2}h_{v}}{2} \cdot \left[1 + \frac{d_{v}}{3h_{v}}\right]$$
(3-10a)

where

 d_v = measured diameter of the vane, in. h_v = heasured height of the vane, in.

 K_v for a tapered vane is

$$K_{v} = \frac{1}{1728} \cdot \left[\pi d_{v}^{3} + 0.37 \left(2d_{v}^{3} - d_{r}^{3} \right) \right]$$
 (3-10b)

where d_r is the rod diameter, in.

(c) Anisotropy can significantly influence the torque measured by the vane.

d. **Water Table.** Depth to the water table and pore water pressure distributions should be known to determine the influence of soil weight and surcharge on the bearing capacity as discussed in 1-4d, Chapter 1.

(1) **Evaluation of Groundwater Table (GWT).** The GWT may be estimated in sands, silty sands, and sandy silts by measuring the depth to the water level in an augered hole at the time of boring and 24 hours thereafter. A 3/8 or 1/2 inch diameter plastic tube may be inserted in the hole for long-term measurements. Accurate measurements of the water table and pore water pressure distribution may be determined from piezometers placed at different depths. Placement depth should be within twice the proposed width of the foundation.

(2) **Fluctuations in GWT.** Large seasonal fluctuations in GWT can adversely influence bearing capacity. Rising water tables reduce the effective stress in cohesionless soil and reduce the ultimate bearing capacity calculated using Equation 1-1.

3-3. <u>Soil Exploration</u>. Soil classification and index tests such as Atterberg Limit, gradations, and water content should be performed on disturbed soil and results plotted as a function of depth to characterize the types of soil in the profile. The distribution of shear strength with depth and the lateral variation of shear strength across the construction site should be determined from laboratory strength tests on undisturbed boring samples. Soil classifications and strengths may be checked and correlated with results of in situ tests. Refer to EM 1110-2-1907 and EM 1110-1-1804 for further information.

a. Lateral Distribution of Field Tests. Soil sampling, test pits, and in situ tests should be performed at different locations on the proposed site that may be most suitable for construction of the structure.

(1) Accessibility. Accessibility of equipment to the construction site and obstacles in the construction area should be considered. It is not unusual to shift the location of the proposed structure on the construction site during soil exploration and design to accommodate features revealed by soil exploration and to achieve the functional requirements of the structure.

(2) Location of Borings. Optimum locations for soil exploration may be near the center, edges, and corners of the proposed structure. A sufficient number of borings should be performed within the areas of proposed construction for laboratory tests to define shear strength parameters C_u and ϕ of each soil layer and any significant lateral variation in soil strength parameters for bearing capacity analysis and consolidation and compressibility characteristics for settlement analysis. These boring holes may also be used to measure water table depths and pore pressures for determination of effective stresses required in bearing capacity analysis.

(a) Preliminary exploration should require two or three borings within each of several potential building locations. Air photos and geological conditions assist in determining location and spacings of borings along the alignment of proposed levees. Initial spacings usually vary from 200 to 1000 ft along the alignment of levees.

(b) Detailed exploration depends on the results of the preliminary exploration. Eight to ten test borings within the proposed building area for typical structures are often required. Large and complex facilities may require more borings to properly define subsurface soil parameters. Refer to TM 5-818-1 for further information on soil exploration for buildings and EM 1110-2-1913 for levees.

b. Depth of Soil Exploration. The depth of exploration depends on the size and type of the proposed structure and should be sufficient to assure that the soil supporting the foundation has adequate bearing capacity. Borings should penetrate all deposits which are unsuitable for foundation purposes such as unconsolidated fill, peat, loose sands, and soft or compressible clays.

(1) 10 Percent Rule. The depth of soil exploration for at least one test boring should be at the depth where the increase in vertical stress caused by the structure is equal to 10 percent of the initial effective vertical overburden stress beneath the foundation, Figure 3-2. Critical depth for bearing capacity analysis D_c should be at least twice the minimum width of shallow square foundations or at least 4 times the minimum width of infinitely long footings or embankments. The depth of additional borings may be less if soil exploration in the immediate vicinity or the general stratigraphy of the area indicate that the proposed bearing strata have adequate thickness or are underlain by stronger formations.



Figure 3-2. Estimation of the critical depth of soil exploration

(2) **Depth to Primary Formation.** Depth of exploration need not exceed the depth of the primary formation where rock or soil of exceptional bearing capacity is located.

(a) If the foundation is to be in soil or rock of exceptional bearing capacity, then at least one boring (or rock core) should be extended 10 or 20 ft into the stratum of exceptional bearing capacity to assure that bedrock and not boulders have been encountered.

(b) For a building foundation carried to rock 3 to 5 rock corings are usually required to determine whether piles or drilled shafts should be used. The percent recovery and rock quality designation (RQD) value should be determined for each rock core. Drilled shafts are often preferred in stiff bearing soil and rock of good quality.

(3) **Selection of Foundation Depth.** The type of foundation, whether shallow or deep, and the depth of undercutting for an embankment depends on the depths to acceptable bearing strata as well as on the type of structure to be supported.

(a) Dense sands and gravels and firm to stiff clays with low potential for volume change provide the best bearing strata for foundations.

(b) Standard penetration resistance values from the SPT and cone resistance from the CPT should be determined at a number of different lateral locations within the construction site. These tests should be performed to depths of about twice the minimum width of the proposed foundation.
(c) Minimum depth requirements should be determined by such factors as depth of frost action, potential scour and erosion, settlement limitations, and bearing capacity.

c. Selection of Shear Strength Parameters. Test data such as undrained shear strength C_u for cohesive soils and the effective angle of internal friction ϕ' for cohesionless sands and gravels should be plotted as a function of depth to determine the distribution of shear strength in the soil. Measurements or estimates of undrained shear strength of cohesive soils C_u are usually characteristic of the worst temporal case in which pore pressures build up in impervious foundation soil immediately following placement of structural loads. Soil consolidates with time under the applied foundation loads causing C_u to increase. Bearing capacity therefore increases with time.

(1) **Evaluation from Laboratory Tests.** Undrained triaxial tests should be performed on specimens from undisturbed samples whenever possible to estimate strength parameters. The confining stresses of cohesive soils should be similar to that which will occur near potential failure planes in situ.

(a) Effective stress parameters c', ϕ' may be evaluated from consolidated-undrained triaxial strength tests with pore pressure measurements (R) performed on undisturbed specimens according to EM 1110-2-1906. These specimens must be saturated.

(b) The undrained shear strength C_u of cohesive foundation soils may be estimated from results of unconsolidated-undrained (Q) triaxial tests according to EM 1110-2-1906 or standard test method ASTM D 2850. These tests should be performed on undrained undisturbed cohesive soil specimens at isotropic confining pressure similar to the total overburden pressure of the soil. Specimens should be taken from the center of undisturbed samples.

(2) **Estimates from Correlations.** Strength parameters may be estimated by correlations with other data such as relative density, OCR, or the maximum past pressure.

(a) The effective friction angle $\,\phi\,'\,$ of cohesionless soil may be estimated from in situ tests as described in section 3-2c.

(b) The distribution of undrained shear strength of cohesive soils may be roughly estimated from maximum past pressure soil data using the procedure outlined in Table 3-3. Pressure contributed by the foundation and structure are not included in this table, which increases conservatism of the shear strengths and avoids unnecessary complication of this approximate analysis. σ_{v_0} refers to the total vertical pressure in the soil excluding pressure from any structural loads. σ'_{v_0} is the effective vertical pressure found by subtracting the pore water pressure.

TABLE 3-3

Estimating Shear Strength of Soil From Maximum Past Pressure (Refer to Figure 3-3)

Step	Description
1	Estimate the distribution of total vertical soil overburden pressure $\sigma_{_{\rm VO}}$ with depth and make a plot as illustrated in Figure 3-3a.
2	Estimate depth to groundwater table and plot the distribution of pore water pressure $\gamma_{\rm w}$ with depth, Figure 3-3a.
3	Subtract pore water pressure distribution from the $\sigma_{_{VO}}$ distribution to determine the effective vertical soil pressure distribution $\sigma_{_{VO}}'$ and plot with depth, Figure 3-3a.
4	Determine the maximum past pressure $\sigma_{\rm p}'$ from results of laboratory consolidation tests, in situ pressuremeter or other tests and plot with depth, Figure 3-3b.
5	Calculate the overconsolidation ratio (OCR), $\sigma_{\rm p}'/\sigma_{\rm vo}',$ and plot with depth, Figure 3-3c.
6	Estimate C_u/σ'_{vo} from
	$\frac{C_{u}}{\sigma'_{vo}} = 0.25 (OCR)^{0.8} $ (3-11)
	where C_u = undrained shear strength and plot with depth, Figure 3-3c.
7	Calculate C_u by multiplying the ratio C_u/σ_{vo}' by σ_{vo}' and plot with depth, Figure 3-3d.
8	An alternative approximation is $C_u \approx 0.2\sigma_p'$. For normally consolidated soils, $C_u/\sigma_p' = 0.11 + 0.0037 \cdot PI$ where PI is the plasticity index, percent (Terzaghi and Peck 1967)

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CHAPTER 4

SHALLOW FOUNDATIONS

4-1. **Basic Considerations.** Shallow foundations may consist of spread footings supporting isolated columns, combined footings for supporting loads from several columns, strip footings for supporting walls, and mats for supporting the entire structure.

a. Significance and Use. These foundations may be used where there is a suitable bearing stratum near the ground surface and settlement from compression or consolidation of underlying soil is acceptable. Potential heave of expansive foundation soils should also be acceptable. Deep foundations should be considered if a suitable shallow bearing stratum is not present or if the shallow bearing stratum is underlain by weak, compressible soil.

b. Settlement Limitations. Settlement limitation requirements in most cases control the pressure which can be applied to the soil by the footing. Acceptable limits for total downward settlement or heave are often 1 to 2 inches or less. Refer to EM 1110-1-1904 for evaluation of settlement or heave.

(1) **Total Settlement.** Total settlement should be limited to avoid damage with connections in structures to outside utilities, to maintain adequate drainage and serviceability, and to maintain adequate freeboard of embankments. A typical allowable settlement for structures is 1 inch.

(2) **Differential Settlement.** Differential settlement nearly always occurs with total settlement and must be limited to avoid cracking and other damage in structures. A typical allowable differential/span length ratio Δ/L for steel and concrete frame structures is 1/500 where Δ is the differential movement within span length L.

c. **Bearing Capacity.** The ultimate bearing capacity should be evaluated using results from a detailed in situ and laboratory study with suitable theoretical analyses given in 4-2. Design and allowable bearing capacities are subsequently determined according to Table 1-1.

4-2. <u>Solution of Bearing Capacity.</u> Shallow foundations such as footings or mats may undergo either a general or local shear failure. Local shear occurs in loose sands which undergo large strains without complete failure. Local shear may also occur for foundations in sensitive soils with high ratios of peak to residual strength. The failure pattern for general shear is modeled by Figure 1-3. Solutions of the general equation are provided using the Terzaghi, Meyerhof, Hansen and Vesic models. Each of these models have different capabilities for considering foundation geometry and soil conditions. Two or more models should be used for each design case when practical to increase confidence in the bearing capacity analyses.

a. **General Equation.** The ultimate bearing capacity of the foundation shown in Figure 1-6 can be determined using the general bearing capacity Equation 1-1

$$\boldsymbol{q}_{u} = CN_{c}\boldsymbol{\zeta}_{c} + \frac{1}{2}\boldsymbol{B}\boldsymbol{\gamma}_{H}\boldsymbol{N}_{\gamma}\boldsymbol{\zeta}_{\gamma} + \boldsymbol{\sigma}_{D}\boldsymbol{N}_{q}\boldsymbol{\zeta}_{q} \qquad (4-1)$$

where

\mathbf{q}^{n}	= ultimate bearing capacity, ksf
C	= unit soil cohesion, ksf
В′	= minimum effective width of foundation B - $2e_{_B}$, ft
e _B	= eccentricity parallel with foundation width B, $M_{_{\rm B}}/Q$, ft
M _B	= bending moment parallel with width B, kips-ft
Q	= vertical load applied on foundation, kips
γ'_{H}	= effective unit weight beneath foundation base within the failure zone, kips/ft ³
σ′ _D	= effective soil or surcharge pressure at the foundation depth D, γ'_{D} .D, ksf
γ′ _D	<pre>= effective unit weight of soil from ground surface to foundation depth, kips/ft³</pre>
D	= foundation depth, ft
$\rm N_{c}$, $\rm N_{\gamma}$, $\rm N_{q}$	<pre>= dimensionless bearing capacity factors of cohesion c, soil weight in the failure wedge, and surcharge q terms</pre>
$\zeta_{c}, \zeta_{v}, \zeta_{a}$	= dimensionless correction factors of cohesion c, soil weight
	in the failure wedge, and surcharge q accounting for
	foundation geometry and soil type

(1) Net Bearing Capacity. The net ultimate bearing capacity q'_u is the maximum pressure that may be applied to the base of the foundation without undergoing a shear failure that is in addition to the overburden pressure at depth D.

$$q'_{U} = q_{U} - \gamma_{D} D \qquad (4-2)$$

(2) **Bearing Capacity Factors.** The dimensionless bearing capacity factors N_c , N_q , and N_γ are functions of the effective friction angle ϕ' and depend on the model selected for solution of Equation 4-1.

(3) **Correction Factors.** The dimensionless correction factors ζ consider a variety of options for modeling actual soil and foundation conditions and depend on the model selected for solution of the ultimate bearing capacity. These options are foundation shape with eccentricity, inclined loading, foundation depth, foundation base on a slope, and a tilted foundation base.

b. **Terzaghi Model.** An early approximate solution to bearing capacity was defined as general shear failure (Terzaghi 1943). The Terzaghi model is applicable to level strip footings placed on or near a level ground surface where foundation depth D is less than the minimum width B. Assumptions include use of a surface footing on soil at plastic equilibrium and a failure surface similar to Figure 1-3a. Shear resistance of soil above the base of an embedded foundation is not included in the solution.

(1) Bearing Capacity Factors. The Terzaghi bearing capacity factors $\,N_{_{\! C}}\,$ and $N_{_{\! G}}\,$ for general shear are shown in Table 4-1 and may be calculated by

TABLE 4-1

Terzaqhi	Dimensionless	Bearing	Capacity	Factors	(after	Bowles	1988)

φ ′	Nq	N _c	N_{γ}	(O' N _q	N_c	\mathbf{N}_{γ}
28	17.81	31.61	15.7	() 1.	00 5.70	0.0
30	22.46	37.16	19.7		2 1.	22 6.30	0.2
32	28.52	44.04	27.9	4	l 1.	49 6.97	0.4
34	36.50	52.64	36.0	6	5 1.	81 7.73	0.6
35	41.44	57.75	42.4	8	3 2.	21 8.60	0.9
36	47.16	63.53	52.0	10) 2.	69 9.60	1.2
38	61.55	77.50	80.0	12	3.	29 10.76	1.7
40	81.27	95.66	100.4	14	4.	02 12.11	2.3
42	108.75	119.67	180.0	16	5 4.	92 13.68	3.0
44	147.74	151.95	257.0	18	6.	04 15.52	3.9
45	173.29	172.29	297.5	20) 7.	44 17.69	4.9
46	204.19	196.22	420.0	22	9.	19 20.27	5.8
48	287.85	258.29	780.1	24	11.	40 23.36	7.8
50	415.15	347.51	1153.2	26	5 14.	21 27.09	11.7

$$N_{\sigma} = (N_{\sigma} - 1) \cot \mathbf{\dot{\phi}}' \tag{4-3a}$$

$$N_{q} = \frac{e^{\frac{270-\phi'}{180}\pi \tan \phi'}}{2\cos^{2}(45+\phi'/2)}$$
(4-3b)

Factor N_{γ} depends largely on the assumption of the angle ψ in Figure 1-3a. N_{γ} varies from minimum values using Hansen's solution to maximum values using the original Terzaghi solution. N_{γ} shown in Table 4-1, was backfigured from the original Terzaghi values assuming $\psi = \phi'$ (Bowles 1988).

(2) Correction Factors. The Terzaghi correction factors ζ_c and ζ_{γ} consider foundation shape only and are given in Table 4-2. ζ_q = 1.0 (Bowles 1988).

TABLE	4-	2
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Terzaghi Correction Factors ζ_c and ζ_γ

Factor	Strip	Square	Circular
ζ _c	1.0	1.3	1.3
ζ _γ	1.0		0.6

c. **Meyerhof Model.** This solution considers correction factors for eccentricity, load inclination, and foundation depth. The influence of the shear strength of soil above the base of the foundation is considered in this solution. Therefore, beneficial effects of the foundation depth can be included in the analysis. Assumptions include use of a shape factor ζ_q for surcharge, soil at plastic equilibrium, and a log spiral failure surface that includes shear above the base of the foundation. The angle $\psi = 45 + \phi/2$ was used for determination of N_{γ} . Table 4-3 illustrates the Meyerhof dimensionless bearing capacity and correction factors required for solution of Equation 4-1 (Meyerhof 1963).

(1) **Bearing Capacity Factors.** Table 4-4 provides the bearing capacity factors in 2-degree intervals.

(2) Correction Factors. Correction factors are given by

 $\begin{array}{rcl} \text{Cohesion:} & \zeta_{c} &=& \zeta_{cs} \cdot \zeta_{ci} \cdot \zeta_{cd} \\ \text{Wedge:} & \zeta_{\gamma} &=& \zeta_{\gamma s} \cdot \zeta_{\gamma i} \cdot \zeta_{\gamma d} \\ \text{Surcharge:} & \zeta_{q} &=& \zeta_{qs} \cdot \zeta_{qi} \cdot \zeta_{qd} \end{array}$

where subscript s indicates shape with eccentricity, subscript i indicates inclined loading, and d indicates foundation depth.

(3) **Eccentricity.** The influence of bending moments on bearing capacity can be estimated by converting bending moments to an equivalent eccentricity e. Footing dimensions are then reduced to consider the adverse effect of eccentricity.

(a) Effective footing dimensions may be given by

$$B' = B - 2e_B \tag{4-4a}$$

$$W' = W - 2e_W \tag{4-4b}$$

$$e_{B} = \frac{M_{B}}{Q} \qquad (4-4c)$$

$$\boldsymbol{e}_{W} = \frac{M_{W}}{Q} \tag{4-4d}$$

where

 M_{B} = bending moment parallel with foundation width B, kips-ft M_{W} = bending moment parallel with foundation length W, kips-ft

Orientation of axes, eccentricities, and bending moments are shown in Table 4-3.

(b) The ultimate load applied to footings to cause a bearing failure is

$$Q_{u} = q_{u} A_{\theta} \qquad (4-5)$$

where

TABLE 4-3

	FACTOR		COHESION (c)	WEDGE (Y)	SURCHARGE (Q)	DIAGRAM
BEARING			۴ _c	Ny	^{ki} q	
CAPACITY		# = 0	5.14	0.00	1.00	
N		ø > 0	(N _q -1)cot ¢	(N _q -1)tan(1.4¢)	N _é e ^{ntan é}	
			۲ _{cs}	۲ _{γs}	۲ _{qs}	
	FOUNDATION SHAPE WITH ECCENTRICITY	¢ = 0	1 + 0.2N _d <mark>B'</mark>	1.0	1.0	
	s	# >10	48	1 + 0.1N _# B'	1 + 0.1H _# <mark>B</mark> '	ee - 1
		0<¢≤10	••	Linear Interpolation Between $\phi = 0$ and $\phi = 10$ Degrees		
			۲ _{ci}	۲ _{γi}	۲ _{qi}	R D
		\$ = 0	$\left[1 - \frac{6}{90}\right]$	1.0	[1 - 6]	
ζ.	LQAD ING i	\$ > 0	$\left[1 - \frac{6}{90}\right]^2$	$\theta \leq \phi \left[1 - \frac{\theta}{\phi}\right]^2$	$\left[1 - \frac{\theta}{90}\right]^2$	
				θ×¢ 0.0		k→
			۲ _{cd}	۲ _{yd}	۲ _{qd}	
	FOUNDATION DEPTH d	# = 0	$1 + 0.2(N_{\phi})^{1/2} \cdot \frac{D}{B}$	1.0	1.0	
		ø > 0	0 1	$1/2 \frac{1}{B}$ 1 + 0.1(N _{\$\phi}) $\frac{1}{B}$	$1 + 0.1(N_{\phi})^{1/2} + \frac{D}{B}$	
		0<¢≤10	¢(Linear Interpol		

Meyerhof Dimensionless Bearing Capacity and Correction Factors (Data from Meyerhof 1953; Meyerhof 1963)

Note: Eccentricity and inclined loading correction factors may not be used simultaneously; factors not used are unity Nomenclature: ϕ = angle of internal friction, degrees W_{μ} = tan²(45 + $\phi/2$) B^{2} = effective width of foundation, δ - 2e_g, ft W^{2} = effective lateral length of foundation, W - 2e_g, ft R = effective lateral length of foundation, W - 2e_g, ft

- B = foundation width, ft
 W = foundation lateral length, ft
- D
- = foundation depth, ft = vertical load on foundation, q8W, kips ۵

TABLE 4-4

					N_{γ}	
¢	\mathbf{N}_{ϕ}	N_c	N_q	Meyerhof	Hansen	Vesic
0	1.00	5.14	1.00	0.00	0.00	0.00
2	1.07	5.63	1.20	0.01	0.01	0.15
4	1.15	6.18	1.43	0.04	0.05	0.34
6	1.23	6.81	1.72	0.11	0.11	0.57
8	1.32	7.53	2.06	0.21	0.22	0.86
10	1.42	8.34	2.47	0.37	0.39	1.22
12	1.52	9.28	2.97	0.60	0.63	1.69
14	1.64	10.37	3.59	0.92	0.97	2.29
16	1.76	11.63	4.34	1.37	1.43	3.06
18	1.89	13.10	5.26	2.00	2.08	4.07
20	2.04	14.83	6.40	2.87	2.95	5.39
22	2.20	16.88	7.82	4.07	4.13	7.13
24	2.37	19.32	9.60	5.72	5.75	9.44
26	2.56	22.25	11.85	8.00	7.94	12.54
28	2.77	25.80	14.72	11.19	10.94	16.72
30	3.00	30.14	18.40	15.67	15.07	22.40
32	3.25	35.49	23.18	22.02	20.79	30.21
34	3.54	42.16	29.44	31.15	28.77	41.06
36	3.85	50.59	37.75	44.43	40.05	56.31
38	4.20	61.35	48.93	64.07	56.17	78.02
40	4.60	75.31	64.19	93.69	79.54	109.41
42	5.04	93.71	85.37	139.32	113.95	155.54
44	5.55	118.37	115.31	211.41	165.58	224.63
46	6.13	152.10	158.50	328.73	244.64	330.33
48	6.79	199.26	222.30	526.44	368.88	495.99
50	7.55	266.88	319.05	873.84	568.56	762.85

Meyerhof, Hansen, and Vesic Dimensionless Bearing Capacity Factors

(c) The bearing capacity of eccentric loaded foundations may also be estimated by (Meyerhof 1953) $\,$

$$\boldsymbol{q}_{\boldsymbol{u}\boldsymbol{e}} = \boldsymbol{q}_{\boldsymbol{u}} \cdot \boldsymbol{R}_{\boldsymbol{e}} \tag{4-6}$$

where $\ensuremath{\,R_e}$ is defined for cohesive soil by

$$R_e = 1 - 2 \cdot \frac{e}{B} \tag{4-7a}$$

and for cohesionless soil (0 < e/B < 0.3) by

$$R_{e} = 1 - \sqrt{\frac{e}{B}} \tag{4-7b}$$

where

q_u = ultimate capacity of a centrally loaded foundation found from Equation 4-1 ignoring bending moments, ksf e = eccentricity from Equations 4-4c and 4-4d, ft

d. Hansen Model. The Hansen model considers tilted bases and slopes in addition to foundation shape and eccentricity, load inclination, and foundation depth. Assumptions are based on an extension of Meyerhof's work to include tilting of the base and construction on a slope. Any D/B ratio may be used permitting bearing capacity analysis of both shallow and deep foundations. Bearing capacity factors N_c and N_q are the same as Meyerhof's factors. N_γ is calculated assuming $\psi = 45 + \phi/2$. These values of N_γ are least of the methods. Correction factors ζ_c , ζ_γ , and ζ_q in Equation 4-1 are

Cohesion:	$\zeta_{ m c}$	=	$\zeta_{cs} \cdot \zeta_{ci} \cdot \zeta_{cd} \cdot \zeta_{c\beta} \cdot \zeta_{c\delta}$	(4-8a)
Wedge:	ζ _γ	=	$\zeta_{\gamma s} \cdot \zeta_{\gamma i} \cdot \zeta_{\gamma d} \cdot \zeta_{\gamma \beta} \cdot \zeta_{\gamma \delta}$	(4-8b)
Surcharge:	ζ_{q}	=	$\zeta_{qs} \cdot \zeta_{qi} \cdot \zeta_{qd} \cdot \zeta_{q\beta} \cdot \zeta_{q\delta}$	(4-8c)

where subscripts s, i, d, β , and δ indicate shape with eccentricity, inclined loading, foundation depth, ground slope, and base tilt, respectively. Table 4-5 illustrates the Hansen dimensionless bearing capacity and correction factors for solution of Equation 4-1.

(1) **Restrictions.** Foundation shape with eccentricity ζ_{cs} , $\zeta_{\gamma s}$, and ζ_{qs} and inclined loading ζ_{ci} , $\zeta_{\gamma i}$, and ζ_{qi} correction factors may not be used simultaneously. Correction factors not used are unity.

(2) **Eccentricity.** Influence of bending moments is evaluated as in the Meyerhof model.

(3) **Inclined loads.** The B component in Equation 4-1 should be width B if horizontal load T is parallel with B or should be W if T is parallel with length W.

e. **Vesic Model.** Table 4-6 illustrates the Vesic dimensionless bearing capacity and correction factors for solution of Equation 4-1.

(1) Bearing Capacity Factors. $N_{\rm c}$ and $N_{\rm q}$ are identical with Meyerhof's and Hansen's factors. N_{γ} was taken from an analysis by Caquot and Kerisel (1953) using ψ = 45 + $\varphi/2$.

(2) Local Shear. A conservative estimate of N_{α} may be given by

$$N_{q} = (1 + \tan \phi') \cdot e^{\tan \phi'} \cdot \tan^{2} \left[45 + \frac{\phi'}{2} \right]$$
(4-9)

Equation 4-9 assumes a local shear failure and leads to a lower bound estimate of q_u . N_q from Equation 4-9 may also be used to calculate N_c and N_γ by the equations given in Table 4-6.

TABLE 4-5

	FACTOR		COMESION (c)	WEDGE (y)	SURCHARGE (q)	DIAGRAM
BEARING	* *		N _C	Ny	мq	
CAPACITY		$\phi = 0$	5.14	0,00	1.00	
N		¢ > 0	(N _q -1)cot ø	1.5(N _q -1)tan φ	N _é e ^{ri} tan ¢	
			fes	۶ ₇ ۶	۶qs	
	FOUNDATION SHAPE WITH	¢ = 0	Strip: 1.0 0.2• <mark>8</mark> 4	1.0	1.0	
	ECCENTRICITY S	φ-v		1.0	1.0	
		\$ > 0	1 + <mark>NgB'</mark> NgW'	1 - 0.4• <mark>8</mark> '	1 + <mark>g</mark> itan ø	
			^s ci	٢ ₇ i	۶qi	Q
CORRECTION	INCLINED LOADING i	∲ = 0 ¢ > 0	$\frac{1 - \left[1 - \frac{T}{A_e C_e}\right]^{\frac{1}{2}}}{2}$ $\int_{a_1} - \frac{1 - \int_{a_1} c_1}{\frac{1 - \int_{a_1} $	$\delta = 0 \left[1 - \frac{0.7T}{Q + A_{e}c_{a}\cot \phi} \right]^{5}$ $\delta > 0 \left[1 - \frac{(0.7 - \delta/450)T}{Q + A_{e}c_{a}\cot \phi} \right]^{5}$	$\left[1 - \frac{0.51}{Q + A_{e}c_{a} \cot \phi}\right]^{5}$	
	FOUNDATION DEPTH	φ = 0		ι.0	fqd 1.0	⊭B¥∕ ?u';
	d	¢ > 0	1 + 0.4k	1.0	1 + 2tan¢(1-sin¢) ² k	°_ T
	BASE ON SLOPE	φ = 0	$\frac{\varsigma_{\beta}}{1 - \frac{\beta}{147.3}}$	ς,β.	ζφθ	B B
	ß	\$ > 0	$\mathbf{\hat{s}_{q\beta}} = \frac{1 - \hat{\mathbf{s}}_{q\beta}}{147.3}$	(1 - 0,5tan¢) ⁵	(1 = 0.5tanβ) ⁵	β+δ≤90°
			Ses.	\$yā	٢qó	` <i>₿</i> <¢
	TILTED BASE δ	φ = 0 φ > 0	$1 = \frac{\delta}{147}$ $S_{q\delta} = \frac{1 - S_{q\delta}}{147.3}$	e 6,0475tanø	e ^{−0.0358tan¢}	

Hansen Dimensionless Bearing Capacity and Correction Factors (Data from Hansen 1970)

Note: Eccentricity and inclined loading correction factors may not be used simultaneously; factors not used are unity NomericLature:

- ϕ = angle of internal friction, degrees N_{d} = tan²(45 + $\phi/2$) B¹ = effective width of foundation, B 2eg, ft W¹ = effective length of foundation, W 2eg, ft (1) = effective length of foundation, W 2eg, ft

- W = 6 foundation width, ft W = 6 foundation length, ft $e_B = eccentricity parallel with B, M_B/0$

- $e_B = eccentricity parameter with <math>w_1 = w_{B/2}$ $e_W = eccentricity parallel with <math>W_1 = W_1/Q$ $M_B = bending moment parallel with <math>W_1$ kips-ft $M_W = bending moment parallel with <math>W_1$ kips-ft

- $\phi_{\rm d}$ = friction angle between base and soil $\approx \phi$, degrees $c_{\rm d}$ = adhesion of soil to base $\leq c$, ksf c = soil cohesion or undrained shear strength $C_{\rm U}$, ksf δ = base tilt from horizontal, upward +, degrees β = slope of ground from base, downward +, degrees k = D/8 if D/8 \leq 1 OR tan⁻¹(D/8) if D/8 \geq 1 (in radians) D = fourdering double (1)
- k = D/8 if D/8 ≤ 1 OR tan⁻¹(D/8) if D/8 > 1 (D = foundation depth, ft Q = vertical load on foundation, kips · T = horizontal load ≤ Qtan¢ + $A_{g}c_{g}$, right +, kips A_{g} = effective area of foundation S⁴W⁴, ft²

TABLE 4-6

	FACTOR		CORESION (c)	WEDGE (7)	SURCHARGE (q)	DIAGRAM
BEARING			N _C	N.7	Na Na	
CAPACITY		φ = 0	5.14	0.00 OR -2sin# if #>0	1,00	
N		¢ > 0	(N _q -1)cot ø	2(W _q +1)tan ¢	N _φ e ^{πtan} φ	
			fcs	ິ _{ວຣ}	٢qs	
	FOUNDATION SHAPE WITH ECCENTRICITY	\$ = 0	Strip: 1,0 0.2+ <mark>8</mark> '	1.0	1.0	
	5	\$ > 0	1 + <mark>NgB'</mark> NcW'	1 − 0.4• <mark>8</mark> ' (1.0 if strip)	$1 + \frac{B^{\dagger}}{U} tand$ (1.0 if strip)	
			fci	çγi	çdi	
CORRECTION	JNCLINED LOADING i		$\frac{1 - \frac{mT}{A_e c_a N_c}}{2}$	$\left[1 - \frac{T}{Q + A_e c_a \cot \phi}\right]^{m+1} > 0$	$\left[1 - \frac{1}{0 + A_{g}c_{a}\cot\phi}\right]^{m}$	
\$	FOUNDATION DEPTN d		۲cd	۶ ₇ d	٩d	μθν ε _μ . τ. μθν
		¢ = 0	1 + 0.4K	1.0	1,0	0 (7
		¢ ≻ 0	1 + 0.4k	1.0	1 + 2tan¢(1-sin¢) ² k	
			^с ся	۹۳۶	r as	
	BASE ON Slope β	φ = 0 d > 0	$1 = \frac{\beta}{147.3}$ $S_{q\beta} = \frac{1 - S_{q\beta}}{147.3}$	(1 − tan¢) ²	(1 - tanβ) ²	
			⁴ G ^β 147,3	ς _{7δ}	ξqs	$\beta + \delta \leq 90^*$ $\beta < \phi$
	TILTED BASE ໒		$1 \sim \frac{\delta}{147}$ $\varsigma_{q\delta} = \frac{1 - \varsigma_{q\delta}}{147.3}$	(1 – 0.017átanø) ²	(1 ~ 0.017stan¢) ²	

Vesic Dimensionless Bearing Capacity and Correction Factors (Data from Vesic 1973; Vesic 1975)

Note: Eccentricity and inclined loading correction factors may not be used simultaneously; factors not used are unity Nomenclature:

- = angle of internal friction, degrees
- $N_{\rm g} \approx \tan^2(45 + \phi/2)$ B^4 = effective width of foundation, B 2e_B, ft
- W' = effective length of foundation, $W = 2e_W$, ft
- B = foundation width, ft
- W = foundation length, ft e_B = eccentricity parallel with B, Mg/Q
- $B_{\rm g}$ = eccentricity parallel with U, $M_{\rm U}/Q$ $M_{\rm B}$ = bending moment parallel with B, kips-ft $M_{\rm U}$ = bending moment parallel with U, kips-ft M_B Mu
- ϕ_{a} = friction angle between base and soil = ϕ , degrees

- \$\phi_a\$ = friction angle between base and soil ≈ \$\phi\$, degrees
 \$\vec{a}\$ = adhesion of soil to base \$\vec{s}\$ c, ksf
 \$\vec{a}\$ = soil cohesion or undrained shear strength \$\vec{C}\$\$, ksf
 \$\vec{b}\$ base tilt from horizontal, upward +, degrees
 \$\vec{b}\$\$ slope of ground from base, downward +, degrees
 \$\vec{b}\$\$ 0/8 if \$\vec{D}\$\$ / 8 \$\vec{s}\$\$ 1 OR \$\vec{tan}^{-1}(D/8)\$ if \$\vec{D}\$\$ / 8 \$\vec{b}\$\$ 1 (in radians)
 \$\vec{b}\$\$ foundation depth, ft
 \$\vec{b}\$\$ vertical load \$\vec{c}\$\$ of any \$\vec{b}\$\$ + \$\vec{A}_{e}c_{2}\$\$, right +, kips
 \$\vec{b}\$\$ and \$\vec{b}\$\$ and \$\vec{b}\$\$ of foundation \$\vec{b}\$\$ # \$\vec{b}\$\$ and \$\vec{b}\$ and \$\vec{b}\$\$ and \$\vec{b}\$\$ and \$\vec{b}\$\$ and \$\vec{b}\$\$ and \$\vec{b}\$ and \$\vec{b}\$\$ and \$\vec{b}\$\$ and \$\vec{b}\$ a

- $m = \frac{2 + R_{BW}}{1 + R_{BW}}, \quad R_{BW} = B/W \text{ if } T \text{ parallel to } W$

f. **Computer Solutions.** Analyses by computer programs provide effective methods of estimating ultimate and allowable bearing capacities.

(1) **Program CBEAR.** Program CBEAR (Mosher and Pace 1982) can be used to calculate the bearing capacity of shallow strip, rectangular, square, or circular footings on one or two soil layers. This program uses the Meyerhof and Vesic bearing capacity factors and correction factors.

(2) **Program UTEXAS2.** UTEXAS2 is a slope stability program that can be used to calculate factors of safety for long wall footings and embankments consisting of multilayered soils (Edris 1987). Foundation loads are applied as surface pressures on flat surfaces or slopes. Circular or noncircular failure surfaces may be assumed. Noncircular failure surfaces may be straight lines and include wedges. Shear surfaces are directed to the left of applied surface loading on horizontal slopes or in the direction in which gravity would produce sliding on nonhorizontal slopes (e.g., from high toward low elevation points). This program can also consider the beneficial effect of internal reinforcement in the slope. q_{ij} calculated by UTEXAS2 may be different from that calculated by CBEAR partly because the FS is defined in UTEXAS2 as the available shear strength divided by the shear stress on the failure surface. The assumed failure surfaces in CBEAR are not the same as the minimum FS surface found in UTEXAS2 by trial and error. FS in Table 1-2 are typical for CBEAR. Program UTEXAS2 calculates factors of safety, but these FS have not been validated with field experience. UTEXAS2 is recommended as a supplement to the Terzaghi, Meyerhof, Hansen, and Vesic models until FS determined by UTEXAS2 have been validated.

g. **Multilayer Soils.** Foundations are often supported by multilayer soils. Multiple soil layers influence the depth of the failure surface and the calculated bearing capacity. Solutions of bearing capacity for a footing in a strong layer that is overlying a weak clay layer, Figure 4-1, are given below. These solutions are valid for a punching shear failure. The use of more than two soil layers to model the subsurface soils is usually not necessary.



Figure 4-1. Schematic of a multilayer foundation-soil system

(1) Depth of Analysis. The maximum depth of the soil profile analyzed need not be much greater than the depth to the failure surface, which is approximately 2B for uniform soil. A deeper depth may be required for settlement analyses.

(a) If the soil immediately beneath the foundation is weaker than deeper soil, the critical failure surface may be at a depth less than 2B.

(b) If the soil is weaker at depths greater than 2B, then the critical failure surface may extend to depths greater than 2B.

(2) **Dense Sand Over Soft Clay.** The ultimate bearing capacity of a footing in a dense sand over soft clay can be calculated assuming a punching shear failure using a circular slip path (Hanna and Meyerhof 1980; Meyerhof 1974)

Wall Footing:

$$\boldsymbol{q}_{u} = \boldsymbol{q}_{u,\boldsymbol{b}} + \frac{2\gamma_{sand}H_{t}^{2}}{B}\left(1 + \frac{2D}{H_{t}}\right)K_{\boldsymbol{p}s} \tan \boldsymbol{\phi}_{sand} - \gamma_{sand}H_{t} \leq \boldsymbol{q}_{ut}$$
(4-10a)

Circular Footing:

$$\boldsymbol{q}_{u} = \boldsymbol{q}_{u,\boldsymbol{b}} + \frac{2\gamma_{sand}H_{t}^{2}}{\boldsymbol{B}}\left(1 + \frac{2D}{H_{t}}\right)S_{s}K_{\boldsymbol{p}s} \tan \boldsymbol{\phi}_{sand} - \gamma_{sand}H_{t} \leq \boldsymbol{q}_{ut}$$
(4-10b)

where

 $q_{u,b}$ = ultimate bearing capacity on a very thick bed of the bottom soft clay layer, ksf γ_{sand} = wet unit weight of the upper dense sand, kips/ft³ H_t = depth below footing base to soft clay, ft D = depth of footing base below ground surface, ft K_{ps} = punching shear coefficient, Figure 4-2a,4-2b, and 4-2c ϕ_{sand} = angle of internal friction of upper dense sand, degrees S_s = shape factor q_{ut} = ultimate bearing capacity of upper dense sand, ksf

The punching shear coefficient k_{ps} can be found from the charts in Figure 4-2 using the undrained shear strength of the lower soft clay and a punching shear parameter C_{ps} . C_{ps} , ratio of ζ/ϕ_{sand} where ζ is the average mobilized angle of shearing resistance on the assumed failure plane, is found from Figure 4-2d using ϕ_{sand} and the bearing capacity ratio R_{bc} . R_{bc} = $0.5\gamma_{sand}BN_{\gamma}/(C_{u}N_{c})$. B is the diameter of a circular footing or width of a wall footing. The shape factor S_{s} , which varies from 1.1 to 1.27, may be assumed unity for conservative design.

(3) **Stiff Over Soft Clay.** Punching shear failure is assumed for stiff over soft clay.

(a) D = 0.0. The ultimate bearing capacity can be calculated for a footing on the ground surface by (Brown and Meyerhof 1969)



Figure 4-2. Charts for calculation of ultimate bearing capacity of dense sand over soft clay (Data from Hanna and Meyerhof 1980)

(4-12b)

Wall Footing:

$$q_u = C_{u, upper} N_{cw, 0} \tag{4-11a}$$

$$N_{CW,0} = 1.5 \frac{H_t}{B_{dia}} + 5.14 \frac{C_{u,lower}}{C_{u,vpper}} \le 5.14$$
(4-11b)

$$= C_{u, upper} N_{cc, 0}$$
 (4-11c)

Circular Footing:

$$N_{cc,0} = 3.0 \frac{H_t}{B_{dia}} + 6.05 \frac{C_{u,lower}}{C_{u,vpper}} \le 6.05$$
(4-11d)

where

 q_u

A rectangular footing may be converted to a circular footing by $B_{dia} = 2(BW/\pi)^{1/2}$ where B = width and W = length of the footing. Factors $N_{cw,0}$ and $N_{cc,0}$ will overestimate bearing capacity by about 10 percent if $C_{u,lower}/C_{u,upper} \ge 0.7$. Refer to Brown and Meyerhof (1969) for charts of $N_{cw,0}$ and $N_{cc,0}$.

(b) D > 0.0. The ultimate bearing capacity can be calculated for a footing placed at depth D by

Wall Footing:
$$q_u = C_{u, upper} N_{CW, D} + \gamma D$$
 (4-12a)

 $q_u = C_{u, upper} N_{cc, D} + \gamma D$

Circular Footing:

where

$$\begin{split} N_{cw,D} &= \text{ bearing capacity factor of wall footing with } D > 0.0 \\ N_{cc,D} &= \text{ bearing capacity factor of rectangular footing with } D > 0.0 \\ &= N_{cw,D} [1 + 0.2(B/W)] \\ \gamma &= \text{ wet unit soil weight of upper soil, kips/ft}^3 \\ D &= \text{ depth of footing, ft} \end{split}$$

 $N_{_{\rm CW,D}}\,$ may be found using Table 4-7 and $N_{_{\rm CW,0}}\,$ from Equation 4-11b. Refer to Department of the Navy (1982) for charts that can be used to calculate bearing capacities in two layer soils.

(4) **Computer Analysis.** The bearing capacity of multilayer soils may be estimated from computer solutions using program CBEAR (Mosher and Pace 1982). Program UTEXAS2 (Edris 1987) calculates FS for wall footings and embankments, which have not been validated with field experience. UTEXAS2 is recommended as a supplement to CBEAR until FS have been validated.

TABLE 4-7

Influence of	Fo	oting	g Dep	th	D
(Department	of	the	Navy	198	2)
D/B		N	$N_{\rm CW}$	1	
0.0		,	1.00	-	
0.5			1.15		
1.0			1.24		
2.0			1.36		
3.0			1.43		
4.0			1.46		

h. Correction for Large Footings and Mats. Bearing capacity, obtained using Equation 4-1 and the bearing capacity factors, gives capacities that are too large for widths B > 6 ft. This is apparently because the $0.5 \cdot B' \gamma'_{\rm H} N_{\gamma} \zeta_{\gamma}$ term becomes too large (DeBeer 1965; Vesic 1969).

(1) Settlement usually controls the design and loading of large dimensioned structures because the foundation soil is stressed by the applied loads to deep depths.

(2) Bearing capacity may be corrected for large footings or mats by multiplying the surcharge term $0.5\cdot\text{B}'\gamma_{\text{H}}N_{\gamma}\zeta_{\gamma}$ by a reduction factor (Bowles 1988)

$$r_{\gamma} = 1 - 0.25 \log_{10} \frac{B}{6} \tag{4-13}$$

where B > 6 ft.

i. **Presumptive Bearing Capacity.** Refer to Table 4-8 for typical presumptive allowable bearing pressures q_{na} . Presumptive allowable pressures should only be used with caution for spread footings supporting small or temporary structures and verified, if practical, by performance of nearby structures. Further details are given in Chapter 4 of Department of the Navy (1982).

(1) Bearing pressures produced by eccentric loads that include dead plus normal live loads plus permanent lateral loads should not exceed q_{na} pressures of Table 4-8.

(2) Transient live loads from wind and earthquakes may exceed the allowable bearing pressure by up to one-third.

(3) For footings of width B<3 ft in least lateral dimension the allowable bearing pressures is B times 1/3 of $q_{\rm na}\,$ given in Table 4-8.

TABLE 4-8

Presumptive Allowable Bearing Pressures for Spread Footings (Data from Department of the Navy 1982, Table 1, Chapter 4)

Bearing Material	In Place Consistency	Nominal Allowable Bearing Pressure q, ksf
Massive crystalline igneous and metamorphic rock: granite, diorite, basalt, gneiss, thoroughly cemented conglomerate (sound condition allows minor cracks)	Hard sound rock	160
Foliated metamorphic rock: slate, schist (sound condition allows minor cracks)	Medium hard sound rock	70
Sedimentary rock; hard cemented shales, siltstone, sandstone, limestone without cavities	Medium hard sound rock	40
Weathered or broken bed rock of any kind except highly argillaceousrock (shale); Rock Quality Designation less than 25	Soft rock	20
Compaction shale or other highly argillaceous rock in sound condition	Soft rock	20
Well-graded mixture of fine and coarse-grained soil: glacial till, hardpan, boulder clay (GW-GC, GC, SC)	Very compact	20
Gravel, gravel-sand mixtures, boulder gravel mixtures (SW, SP, SW, SP)	Very compact Medium to compact Loose	14 10 6
Coarse to medium sand, sand with little gravel (SW, SP)	Very compact Medium to compact Loose	8 6 3
Fine to medium sand, silty or clayey medium to coarse sand (SW, SM, SC)	Very compact Medium to compact Loose	6 5 3
Homogeneous inorganic clay, sandy or silty clay (CL, CH)	Very stiff to hard Medium to stiff Soft	8 4 1
Inorganic silt, sandy or clayey silt, varved silt-clay-fine sand	Very stiff to hard Medium to stiff Soft	6 3 1

(4) For a bearing stratum underlain by weaker material, pressure on the weak stratum should be less than the nominal allowable bearing pressure given in Table 4-8

$$\frac{Q}{(B+1.16H_t)\cdot(W+1.16H_t)} \leq q_{na} \tag{4-14}$$

where

Q = vertical load on foundation, kips B = foundation width, ft W = foundation lateral length, ft H_t = depth to weak stratum beneath bottom of foundation, ft q_{na} = nominal allowable bearing pressure, ksf (5) Resistance to uplift force Q_{up} should be

 $W_{ au}$.

$$\frac{W_T}{\mathcal{Q}_{\nu p}} > 2 \tag{4-15}$$

where W'_{τ} is the total effective weight of soil and foundation resisting uplift.

4-3. Retaining Walls.

a. **Ultimate Bearing Capacity.** Ultimate bearing capacity of retaining walls may be estimated by Equation 4-1 with dimensionless factors provided by the Meyerhof, Hansen, or Vesic methods described in Tables 4-3, 4-5, and 4-6, respectively. The dimensionless correction factors need consider only depth and load inclination for retaining walls. Equation 4-1 may be rewritten

$$\boldsymbol{q}_{u} = CN_{c}\boldsymbol{\zeta}_{cd}\boldsymbol{\zeta}_{ci} + \frac{1}{2}\boldsymbol{B}\boldsymbol{\gamma}_{H}N_{\gamma}\boldsymbol{\zeta}_{\gamma d}\boldsymbol{\zeta}_{\gamma i} + \boldsymbol{\sigma}_{D}N_{q}\boldsymbol{\zeta}_{qd}\boldsymbol{\zeta}_{qi} \qquad (4-16)$$

where N_c, N_γ, N_q and $\zeta_c, \zeta_\gamma, \zeta_q$ are given in Tables 4-3, 4-4, 4-5, or 4-6. If Hansen's model is used, then the exponent for $\zeta_{\gamma i}$ and $\zeta_{q i}$ in Table 4-5 should be changed from 5 to 2 (Bowles 1988).

b. Allowable Bearing Capacity. The allowable bearing capacity may be estimated from Equations 1-2 using FS = 2 for cohesionless soils and FS = 3 for cohesive soils.

4-4. In Situ Modeling of Bearing Pressures. In situ load tests of the full size foundation are not usually done, except for load testing of piles and drilled shafts. Full scale testing is usually not performed because required loads are usually large and as a result these tests are expensive. The most common method is to estimate the bearing capacity of the soil from the results of relatively simple, less expensive in situ tests such as plate bearing, standard penetration, cone penetration, and vane shear tests.

a. **Plate Bearing Test.** Loading small plates 12 to 30 inches in diameter or width B_p are quite useful, particularly in sands, for estimating the bearing capacity of foundations. The soil strata within a depth 4B beneath the foundation must be similar to the strata beneath the plate. Details of this test are described in standard method ASTM D 1194. A large vehicle can be used to provide reaction for the applied pressures.

(1) **Constant Strength.** The ultimate bearing capacity of the foundation in cohesive soil of constant shear strength may be estimated by

$$B < 4B_p: \quad q_v = q_{v,p} \tag{4-17a}$$

where

(2) **Strength Increasing Linearly With Depth.** The ultimate bearing capacity of the foundation in cohesionless or cohesive soil with strength increasing linearly with depth may be estimated by

$$B < 4B_p; \qquad q_u = q_{u,p} \frac{B}{B_p}$$
(4-17b)

(3) **Extrapolation of Settlement Test Results in Sands.** The soil pressure q_1 may be estimated using a modified Terzaghi and Peck approximation (Peck and Bazarra 1969; Peck, Hanson, and Thornburn 1974)

$$q_1 = \frac{q}{1.5 \rho_i} \tag{4-18}$$

where

 q_1 = soil pressure per inch of settlement, ksf/in.

- q = average pressure applied on plate, ksf
- ρ_i = immediate settlement of plate, in.

The results of the plate load test should indicate that q/ρ_i is essentially constant. q_1 and plate diameter B_p can then be input into the Terzaghi and Peck chart for the appropriate D/B ratio, which is 1, 0.5 or 0.25 (see Figure 3-3, EM 1110-1-1904). The actual footing dimension B is subsequently input into the same chart to indicate the allowable foundation bearing pressure.

(4) **Extrapolation of Test Results.** Load tests performed using several plate sizes may allow extrapolation of test results to foundations up to 6 times the plate diameter provided the soil is similar. Other in situ test results using standard penetration or cone penetration data are recommended for large foundation diameters and depths more than $4B_p$.

b. **Standard Penetration Test (SPT).** The SPT may be used to directly obtain the allowable bearing capacity of soils for specific amounts of settlement based on past correlations.

(1) **Footings.** Meyerhof's equations (Meyerhof 1956; Meyerhof 1974) are modified to increase bearing capacity by 50 percent (Bowles 1988)

$$B \le 4 \ ft: \quad Q_{a,1} = \frac{N_n}{F_1} K_d$$
 (4-19a)

$$B > 4 \ ft: \quad q_{a,1} = \frac{N_n}{F_2} \left[\frac{B + F_3}{B} \right]^2$$
 (4-19b)

where

 $q_{a,1}$ = allowable bearing capacity for 1 inch of settlement, ksf $K_d = 1 + 0.33(D/B) \le 1.33$ N_n = standard penetration resistance corrected to n percent energy

 \mathbf{n}_{n} - Standard penetration resistance corrected to in percent che

Equation 4-19b may be used for footings up to 15 ft wide.

(a) F factors depend on the energy of the blows. n is approximately 55 percent for uncorrected penetration resistance and $F_1 = 2.5$, $F_2 = 4$, and $F_3 = 1$. F factors corrected to n = 70 percent energy are $F_1 = 2$, $F_2 = 3.2$ and $F_3 = 1$.

(b) Figure 3-3 of EM 1110-1-1904 provides charts for estimating q_a for 1 inch of settlement from SPT data using modified Terzaghi and Peck approximations.

(2) Mats. For mat foundations

$$Q_{a,1} = \frac{N_n}{F_2} K_d$$
 (4-20a)

where $q_{a,1}$ is the allowable bearing capacity for limiting settlement to 1 inch. The allowable bearing capacity for any settlement q_a may be linearly related to the allowable settlement for 1 inch obtained from Equations 4-19 assuming settlement varies in proportion to pressure

$$q_a = \rho \cdot q_{a,1} \tag{4-20b}$$

where

 ρ = settlement, inches $q_{a,1}$ = allowable bearing capacity for 1 inch settlement, ksf

c. Cone Penetration Test (CPT). Bearing capacity has been correlated with cone tip resistance q_c for shallow foundations with D/B \leq 1.5 (Schmertmann 1978).

(1) The ultimate bearing capacity of cohesionless soils is given by

Strip: $q_u = 28 - 0.0052 (300 - q_c)^{1.5}$ (4-21a) Square: $q_u = 48 - 0.0090 (300 - q_c)^{1.5}$ (4-21b)

where q_{u} and q_{c} are in units of tsf or $kg/cm^{2}.$

(2) The ultimate bearing capacity of cohesive soils is

Strip: $q_u = 2 + 0.28q_c$ (4-22a)

Square:
$$q_u = 5 + 0.34q_c$$
 (4-22b)

Units are also in tsf or kg/cm². Table 4-9 using Figure 4-3 provides a procedure for estimating q_u for footings up to B = 8 ft in width.

d. **Vane Shear Test.** The vane shear is suitable for cohesive soil because bearing capacity is governed by short-term, undrained loading which is simulated by this test. Bearing capacity can be estimated by (Canadian Geotechnical Society 1985)

$$\boldsymbol{q}_{u} = 5 \cdot \boldsymbol{R}_{v} \cdot \boldsymbol{\tau}_{u} \left[1 + 0 \cdot 2 \cdot \frac{\boldsymbol{D}}{\boldsymbol{B}} \right] \left[1 + 0 \cdot 2 \cdot \frac{\boldsymbol{B}}{\boldsymbol{L}} \right] + \boldsymbol{\sigma}_{vo} \qquad (4-24)$$

where

 R_v = strength reduction factor, Figure 4-4

- $\tau_{\rm u}~$ = field vane undrained shear strength measured during the test, ksf
- D = depth of foundation, ft
- B = width of foundation, ft
- L = length of foundation, ft
- $\sigma_{_{vo}}$ = total vertical soil overburden pressure at the foundation level, ksf

4-5. **Examples.** Estimation of the bearing capacity is given below for (1) a wall footing placed on the ground surface subjected to a vertical load, (2) a rectangular footing placed below the ground surface and subjected to an inclined load, and (3) a tilted, rectangular footing on a slope and subjected to an eccentric load. Additional examples are provided in the user manual for CBEAR (Mosher and Pace 1982). The slope stability analysis of embankments is described in the user manual for UTEXAS2 (Edris 1987). Bearing capacity analyses should be performed using at least three methods where practical.

TABLE 4-9

<u>CPT Procedure for Estimating Bearing Capacity</u> of Footings on Cohesive Soil (Data from Tand, Funegard, and Briaud 1986)

Step	Procedure	
<u></u>		
1	Determine equivalent $ { m q}_{ m c} $ from footing base to 1.5B below base by	
	$\overline{q}_{c} = (q_{cbi}; q_{cbi})^{0.5} $ $(4-23)$	2)
	where	a)
	q_c = equivalent cone tip bearing pressure below footing, ksf q_{cb1} = average tip resistance from 0.0 to 0.5B, ksf q_{cb2} = average cone tip resistance from 0.5B to 1.5B, ksf	
2	Determine equivalent depth of embedment $D_{\rm e}$, ft, to account for effect of strong or weak soil above the bearing elevation	
	where $D_{e} = \sum_{i=1}^{n} \Delta z_{i} \frac{q_{ci}}{q_{c}} $ (4-23)	b)
	n = number of depth increments to depth D D = unadjusted (actual) depth of embedment, ft Δz_i = depth increment i, ft q_{ei} = cone tip resistance of depth increment i, ksf q_c = equivalent cone tip bearing pressure below footing, ksf	
3	Determine ratio of equivalent embedment depth to footing width	
	$R_d = \frac{D_e}{B} \tag{4-23}$	C)
4	Estimate bearing ratio R_k from Figure 4-3 using R_d . The lower bound curv is applicable to fissured or slickensided clays. The average curve is applicable to all other clays unless load tests verify the upper bound curve for intact clay.	

5 Estimate total overburden pressure $\sigma_{_{vo}}$, then calculate

$$q_{va} = R_k (\overline{q_c} - \sigma_{vo}) + \sigma_{vo}$$
(4-23d)

where q_{ua} = ultimate bearing capacity of axially loaded square or round footings with horizontal ground surface and base. Adjust q_{ua} obtained from Equation 4-23d for shape, eccentric loads, sloping ground or tilted base using Hansen's factors for cohesion, Table 4-5, to obtain the ultimate capacity

$$\boldsymbol{q}_{\boldsymbol{u}} = \boldsymbol{\zeta}_{\boldsymbol{C}} \cdot \boldsymbol{q}_{\boldsymbol{u}\boldsymbol{a}} \tag{4-23e}$$

where $\zeta_{\rm c}$ is defined by Equation 4-8a.



Figure 4-3. Bearing ratio $R_{\rm k}$ for axially loaded square and round footings (Data from Tand, Funegard, and Briaud 1986)



Figure 4-4. Strength reduction factor for field vane shear (Data from Bjerrum 1973)

a. Wall Footing. A wall footing 3 ft wide with a load Q = 12 kips/ft (bearing pressure q = 4 ksf) is proposed to support a portion of a structure in a selected construction site. The footing is assumed to be placed on or near the ground surface for this analysis such that D = 0.0 ft, Figure 4-5, and $\sigma'_{\rm D}$ = 0.0. Depth H is expected to be < 2B or < 6 ft.

(1) **Soil Exploration.** Soil exploration indicated a laterally uniform cohesive soil in the proposed site. Undrained triaxial compression test results were performed on specimens of undisturbed soil samples to determine the undrained shear strength. Confining pressures on these specimens were equal to the total vertical overburden pressure applied to these specimens when in the field. Results of these tests indicated the distribution of shear strength with depth shown in Figure 4-6. The minimum shear strength $c = C_u$ of 1.4 ksf observed 5 to 7 ft below ground surface is selected for the analysis. The friction angle is $\phi = 0.0$ deg and the wet unit weight is 120 psf.

(2) Ultimate Bearing Capacity

(a) Terzaghi Method. Table 4-1 indicates $\,N_c$ = 5.7, N_q = 1.0 and N_γ = 0.00. The total ultimate capacity $\,q_u\,$ is

$$q_{u} = cN_{c} = 1.4.5.7 = 8.0 \ ksf$$

The Terzaghi method indicates an ultimate bearing capacity $q_u = 8$ ksf.

(b) Meyerhof Method. The ultimate bearing capacity of this wall footing using program CBEAR yields q_u = 7.196 ksf. The Hansen and Vesic solutions will be similar.

(3) Allowable Bearing Capacity. FS for this problem from Table 1-2 is 3.0. Therefore, q_a using Equation 1-2a is $q_u/FS = 8.000/3 = 2.7$ ksf from the Terzaghi solution and 7.196/3 = 2.4 ksf from CBEAR. The solution using program UTEXAS2 gives a minimum FS = 2.2 for a circular failure surface of radius 3 ft with its center at the left edge of the footing.

(4) **Recommendation.** q_a ranges from 2.4 to 2.7 while the proposed design pressure q_d is 4 ksf. q_d should be reduced to 2.4 ksf $\leq q_a$.

b. Rectangular Footing With Inclined Load. A rectangular footing with B = 3 ft, W = 6 ft, D = 2 ft, similar to Figure 1-6, is to be placed in cohesionless soil on a horizontal surface (β = 0.0) and without base tilt (δ = 0.0). The effective friction angle ϕ' = 30 deg and cohesion c = c_u = 0.0. The surcharge soil has a wet (moist) unit weight $\gamma_{\rm D}$ = 0.120 kip/ft³ (120 pcf), subsurface soil has a wet (moist) unit weight $\gamma_{\rm H}$ = 0.130 kip/ft³ (130 pcf), and depth to groundwater is D_{GWT} = 3 ft. The saturated unit weight is assumed the same as the wet unit weight. The applied vertical load on the foundation is Q = 10 kips and the horizontal load T = +2 kips to the right.



Figure 4-5. Example wall footing bearing capacity analysis



Figure 4-6. Example undrained shear strength distribution with depth

(1) **Effective Stress Adjustment.** Adjust the unit soil weights due to the water table using Equation 1-6

From Equation 1-7a, $\sigma'_{\text{D}} = \sigma_{\text{D}} = \gamma_{\text{D}} \cdot \text{D} = 0.120 \cdot 2.00 = 0.24 \text{ ksf}$

(2) Meyerhof Method. For ϕ' = 30 deg, $N_{\rm q}$ = 18.40, N_{γ} = 15.67, and N_{ϕ} = 3.00 from Table 4-4. $N_{\rm c}$ is not needed since c = 0.0. From Table 4-3,

(a) Wedge correction factor $\zeta_{\gamma} = \zeta_{\gamma s} \cdot \zeta_{\gamma i} \cdot \zeta_{\gamma d}$

(b) Surcharge correction factor $\zeta_{q} = \zeta_{qs} \cdot \zeta_{qi} \cdot \zeta_{qd}$

(c) Total ultimate bearing capacity from Equation 4-1 is

 $\begin{array}{rcl} q_{u} &=& 0.5 \cdot B \cdot \gamma_{\text{H}}' N_{\gamma} \cdot \zeta_{\gamma} &+& \sigma_{D}' \cdot N_{q} \cdot \zeta_{q} \\ &=& 0.5 \cdot 3.00 \cdot 0.08 \cdot 15.67 \cdot 0.49 &+& 0.24 \cdot 18.40 \cdot 0.98 \\ &=& 0.92 &+& 4.33 &=& 5.25 \text{ ksf} \end{array}$

(3) Hansen Method. For ϕ' = 30 deg, N_q = 18.40, N_γ = 15.07, and N_ϕ = 3.00 from Table 4-4. N_c is not needed since c = 0.0. From Table 4-5,

(a) Wedge correction factor $\zeta_{\gamma} = \zeta_{\gamma s} \cdot \zeta_{\gamma i} \cdot \zeta_{\gamma d} \cdot \zeta_{\gamma \beta} \cdot \zeta_{\gamma \delta}$ where $\zeta_{\gamma \beta} = \zeta_{\gamma \delta} = 1.00$

(b) Surcharge correction factor $\zeta_{q} = \zeta_{qs} \cdot \zeta_{qi} \cdot \zeta_{qd} \cdot \zeta_{q\beta} \cdot \zeta_{q\delta}$ where $\zeta_{q\beta} = \zeta_{q\delta} = 1.00$

$$\begin{split} \zeta_{\rm qs} &= 1 + (B/W) \cdot \tan \phi = 1 + (3/6) \cdot 0.577 = 1.289 \\ \zeta_{\rm qi} &= [1 - (0.5T/Q)]^5 = [1 - (0.5 \cdot 2/10)]^5 = 0.59 \\ k &= D/B = 2/3 \\ \zeta_{\rm qd} &= 1 + 2 \cdot \tan \phi' \cdot (1 - \sin \phi')^2 \cdot k = 1 + 2 \cdot 0.577 \cdot (1 - 0.5)^2 \cdot 2/3 \\ &= 1.192 \\ \zeta_{\rm q} &= 1.289 \cdot 0.59 \cdot 1.192 = 0.907 \end{split}$$

(c) Total ultimate bearing capacity from Equation 4-1 is

 $\begin{array}{rcl} q_{\rm u} &=& 0.5 \cdot {\rm B} \cdot \, \gamma_{\rm H}' \cdot {\rm N}_{\gamma} \cdot \, \zeta_{\gamma} & + & \sigma_{\rm D}' \cdot {\rm N}_{\rm q} \cdot \, \zeta_{\rm q} \\ &=& 0.5 \cdot 3.00 \cdot 0.08 \cdot 15.07 \cdot 0.376 & + & 0.24 \cdot 18.40 \cdot 0.907 \\ &=& & 0.68 & + & 4.01 & = 4.69 \ {\rm ksf} \end{array}$

(4) **Vesic Method.** For ϕ' = 30 deg, N_q = 18.40, N_γ = 22.40, and N_ϕ = 3.00 from Table 4-4. N_c is not needed. From Table 4-6,

(a) Wedge correction factor $\zeta_{\gamma} = \zeta_{\gamma s} \cdot \zeta_{\gamma 1} \cdot \zeta_{\gamma a} \cdot \zeta_{\gamma \beta} \cdot \zeta_{\gamma \delta}$ where $\zeta_{\gamma \beta} = \zeta_{\gamma \delta} = 1.00$ $\zeta_{\gamma s} = 1 - 0.4 \cdot B/W = 1 - 0.4 \cdot 3/6 = 0.80$ $R_{BW} = B/W = 3/6 = 0.5$ $m = (2 + R_{BW})/(1 + R_{BW}) = (2 + 0.5)/(1 + 0.5) = 1.67$ $\zeta_{\gamma 1} = [(1 - (T/Q)]^{m+1} = [1 - (2/10)]^{1.67+1} = 0.551$ $\zeta_{\gamma} = 0.80 \cdot 0.551 \cdot 1.00 = 0.441$ (b) Surcharge correction factor $\zeta_{q} = \zeta_{qs} \cdot \zeta_{q1} \cdot \zeta_{qd} \cdot \zeta_{q\beta} \cdot \zeta_{q\delta}$ where $\zeta_{q\beta} = \zeta_{q\delta} = 1.00$ $\zeta_{qs} = 1 + (B/W) \cdot \tan \phi = 1 + 3/6 \cdot 0.577 = 1.289$ $\zeta_{qd} = 1 + 2 \cdot \tan \phi' \cdot (1 - \sin \phi')^{2} \cdot k = 1 + 2 \cdot 0.577 \cdot (1 - 0.5) \cdot 2/3$ = 1.192 $\zeta_{q} = 1.289 \cdot 0.689 \cdot 1.192 = 1.058$ (c) Total ultimate bearing capacity from Equation 3-1a is

 $\begin{array}{rcl} q_{u} &=& 0.5 \cdot B \cdot \gamma_{H}^{\prime} \cdot N_{\gamma} \cdot \zeta_{\gamma} & + & \sigma_{D}^{\prime} \cdot N_{q} \cdot \zeta_{q} \\ &=& 0.5 \cdot 3.00 \cdot 0.08 \cdot 22.40 \cdot 0.441 & + & 0.24 \cdot 18.40 \cdot 1.058 \\ &=& 1.19 & + & 4.67 & = 5.86 \ \mathrm{ksf} \end{array}$

(5) **Program CBEAR.** Zero elevation for this problem is defined 3 ft below the foundation base. Input to this program is as follows (refer to Figure 1-6):

(a) Foundation coordinates: $x_1 = 10.00$, $y_1 = 3.00$ $x_2 = 13.00$, $y_2 = 3.00$ Length of footing: = 6.00

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(b)	Soil Coordinates: $x_1 = x_{s1} = 10.00$, $y_1 = y_{s1} = 3.00$ (top elevation of $x_2 = x_{s2} = 13.00$, $y_2 = y_{s2} = 3.00$ subsurface soil)
(c)	$\begin{array}{llllllllllllllllllllllllllllllllllll$
(d)	Options: <u>One surcharge</u> y coordinate of top of <u>layer</u> surcharge = 5.00 ft moist unit weight = 120 pounds/ft ³ saturated unit weight = 120 pounds/ft ³
	Water tabley coordinate of top ofdescriptionwater table= 2.00 ftunit weight of water= 62.5 pounds/ft3
	Applied loadapplied load (R)= 10.2 kipsdescriptionx coordinate of baseapplication point= 11.5 ftz coordinate of baseapplication point= 3.00 ftinclination of load clockwisefrom vertical= 11.4 deg
(e)	CBEAR calculates $q_u = 5.34 \text{ ksf}$

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(f) Comparison of methods indicates bearing capacities

Method	Total q _u , ksf	Net q'', ksf
Meyerhof	5.25	5.01
Hansen Vesic	4.69 5.86	4.45 5.62
Program CBEAR	5.34	5.10

The net bearing capacity is found by subtracting $\gamma_{\rm D} \cdot {\rm D} = 0.12 \cdot 2 = 0.24$ ksf from ${\rm q}_{\rm u}$, Equation 4-2. The resultant applied pressure on the footing is ${\rm q}_{\rm r} = {\rm R}/({\rm BW}) = 10.2/(3\cdot 6) = 0.57$ ksf. The factor of safety of all of the above methods with respect to the net bearing capacity is on the order of ${\rm q}_{\rm u}'/{\rm q}_{\rm r} \approx 9$. The Hansen method is most conservative. c. Rectangular Footing With Eccentricity, Base Tilt, and Ground Slope. A rectangular footing, B = 3 ft and W = 5 ft, is placed in a cohesionless soil with base tilt δ = 5 deg and ground slope β = 15 deg as illustrated in Table 4-5 and Figure 4-7. ϕ' = 26 deg and c = c_a = 0.0. Soil wet unit weight $\gamma_{\rm D}$ = 120 lbs/ft³, subsurface soil wet unit weight $\gamma_{\rm H}$ = 130 lbs/ft³, and depth to groundwater D_{GWT} = 3 ft. Vertical applied load Q = 10 kips and horizontal load T = 0 kips, but M_B = 5 kips-ft and M_W = 10 kips-ft.



--- ZERO ELEVATION

Figure 4-7. Shallow foundation with slope and base tilt

(1) **Coordinate Adjustment.** δ = 5 deg indicates right side elevation of the base is 3 sin 5 deg = 0.26 ft higher than the left side. β = 15 deg indicates right side foundation elevation at the ground surface is 3 sin 15 deg = 0.78 ft higher than the left side.

(2) Effective Stress Adjustment. Average $D_{GWT} = 3 + 0.78/2 = 3.39$ ft. Average D = 2 + 0.78/2 - 0.26/2 = 2.26 ft. Adjustment of soil unit wet weight for the water table from Equation 1-6 is

(3) **Eccentricity Adjustment.** Bending moments lead to eccentricities from Equations 4-4c and 4-4d

$$e_{B} = M_{B}/Q = 5/10 = 0.5 \text{ ft}$$

 $e_{W} = M_{W}/Q = 10/10 = 1.0 \text{ ft}$

Effective dimensions from Equations 4-4a and 4-4b are

B' = B - $2e_B = 3 - 2 \cdot 0.5 = 2$ ft W' = W - $2e_W = 5 - 2 \cdot 1.0 = 3$ ft

EM 1110-1-1905 30 Oct 92 (4) Hansen Method. For $\phi' = 26 \text{ deg}$, $N_q = 11.85 \text{ and } N_{\gamma} = 7.94 \text{ from Table}$ N_c is not needed since c = 0.0. From Table 4-5, 4-4. (a) Wedge correction factor $\zeta_{\gamma} = \zeta_{\gamma s} \cdot \zeta_{\gamma i} \cdot \zeta_{\gamma d} \cdot \zeta_{\gamma \beta} \cdot \zeta_{\gamma \delta}$ where $\zeta_{\gamma i} = 1.00$
$$\begin{split} \zeta_{\gamma\beta} &= (1 - 0.5 \cdot \tan \beta)^5 = (1 - 0.5 \cdot \tan 15)^5 = 0.487 \\ \zeta_{\gamma\delta} &= e^{-0.047 \cdot \delta \cdot \tan \phi'} = e^{-0.047 \cdot 5 \cdot \tan 26} = 0.892 \end{split}$$
 $\zeta_{\gamma} = 0.733 \cdot 1.000 \cdot 0.487 \cdot 0.892 = 0.318$ Surcharge correction factor $\zeta_q = \zeta_{qs} \cdot \zeta_{qi} \cdot \zeta_{qd} \cdot \zeta_{q\beta} \cdot \zeta_{q\delta}$ where $\zeta_{qi} = 1.00$ (b) $\zeta_{qs} = 1 + (B'/W') \cdot \tan \phi = 1 + (2/3) \cdot 0.488 = 1.325$ k = D/B = 2.26/3 = 0.753 $\zeta_{\rm qd} = 1 + 2 \cdot \tan \phi' \cdot (1 - \sin \phi')^2 \cdot k = 1 + 2 \cdot 0.488 \cdot (1 - 0.438) \cdot 0.753$ $\zeta_{\rm qd} = 1.232$ $\begin{aligned} \zeta_{q\beta}^{-} &= \zeta_{\gamma\beta} = 0.487 \\ \zeta_{q\delta}^{-} &= e^{-0.035\cdot\delta\cdot\tan\,\phi'} = e^{-0.035\cdot5\cdot\tan\,26} = 0.918 \end{aligned}$ $\zeta_{\rm q} = 1.325 \cdot 1.232 \cdot 0.487 \cdot 0.918 = 0.730$ (c) Total ultimate bearing capacity from Equation 4-1 is $q_u = 0.5 \cdot B \cdot \gamma'_H \cdot N_{\gamma} \cdot \zeta_{\gamma}$ + $\sigma'_{D} \cdot N_{q} \cdot \zeta_{q}$ $= 0.5 \cdot 2.00 \cdot 0.081 \cdot 7.942 \cdot 0.318 + 0.27 \cdot 11.85 \cdot 0.730$ 2.335 = 2.54 ksf 0.205 + (5) Vesic Method. For ϕ' = 26 deg, N_q = 11.85 and N_γ = 12.54 from Table 4-4. N_c is not needed. From Table 4-6, (a) Wedge correction factor $\zeta_{\gamma} = \zeta_{\gamma s} \cdot \zeta_{\gamma i} \cdot \zeta_{\gamma d} \cdot \zeta_{\gamma \beta} \cdot \zeta_{\gamma \delta}$ where $\zeta_{\gamma i} = 1.00$ = 1.00 $\zeta_{\gamma_{B}} = 1 - 0.4 \cdot B/W = 1 - 0.4 \cdot 2/3 = 0.733$ $\zeta_{\gamma d} = 1.00$ $\begin{aligned} &\zeta_{\gamma\beta} = (1 - \tan \beta)^2 = (1 - \tan 15)^2 = 0.536 \\ &\zeta_{\gamma\delta} = (1 - 0.017 \cdot \delta \cdot \tan \phi')^2 = (1 - 0.017 \cdot 5 \cdot \tan 26)^2 = 0.919 \end{aligned}$ $\zeta_{\gamma} = 0.733 \cdot 1.00 \cdot 0.536 \cdot 0.919 = 0.361$ Surcharge correction factor $\zeta_{q} = \zeta_{qs} \cdot \zeta_{qi} \cdot \zeta_{qd} \cdot \zeta_{q\beta} \cdot \zeta_{q\delta}$ where $\zeta_{qi} = \zeta_{a\delta}$ (b) = 1.00 $\zeta_{qs} = 1 + (B/W) \cdot \tan \phi = 1 + 2/3 \cdot 0.488 = 1.325$ $\zeta_{\rm qd} = 1 + 2 \cdot \tan \phi' \cdot (1 - \sin \phi')^2 \cdot k$ $\zeta_{\text{ad}}^{\text{a}}$ = 1 + 2.0.488 (1 - 0.438)² 0.753 = 1.232 $\zeta_{\rm q\beta} = \zeta_{\gamma\beta} = 0.536$ $\vec{\zeta}_{q\delta}^{ar} = \vec{\zeta}_{\gamma\delta}^{r} = 0.919$ $\vec{\zeta}_{q} = 1.325 \cdot 1.232 \cdot 0.536 \cdot 0.919 = 0.804$

(c) Total ultimate bearing capacity from Equation 4-1 is $q_u = 0.5 \cdot B \cdot \gamma'_H \cdot N_{\gamma} \cdot \zeta_{\gamma}$ + $\sigma_{D}' \cdot N_{q} \cdot \zeta_{q}$ $= 0.5 \cdot 2.00 \cdot 0.081 \cdot 12.54 \cdot 0.361 + 0.27 \cdot 11.85 \cdot 0.804$ = 2.572 = 2.94 ksf 0.367 + (6) Program CBEAR. Input is as follows (refer to Figure 4-7): (a) Foundation coordinates: $x_1 = 10.00$, $y_1 = 3.00$ $x_2 = 13.00, y_2 = 3.26$ Length of footing: = 5.00 (b) Soil Coordinates: $x_{s1} = 10.00, y_{s1} = 5.00$ $x_{s2} = 13.00, y_{s2} = 5.78$ (c) Soil Properties: moist (wet) unit weight $\gamma_{\rm H}~$ = 120 pounds/ft 3 saturated unit weight = $\gamma_{\rm H}$ = 26 deg friction angle cohesion = 0.00 (d) Options: <u>One surcharge</u> y coordinate of top of subsurface soil = 3.00 ft
moist unit weight = 130 pounds/ft³ layer saturated unit weight = 130 pounds/ft^3 friction angle = 26 degrees cohesion = 0.0 <u>Water table</u> y coordinate of top of description water table = 2.00 ft unit weight of water = 62.5 pounds/ft^3 <u>Applied load</u> applied load (R) = 10.0 kips description x coordinate of base application point = 11.0 ftz coordinate of base application point = 2.00 ft inclination of load clockwise from vertical = 0.0 deg (e) CBEAR calculates $q_u = 2.21 \text{ ksf}$

(f) Comparison of methods indicates bearing capacities

Method	Total q _u , ksf	Net q' _u , ksf
Hansen Vesic Program CBEAR	2.55 3.94 2.21	2.28 2.67 1.94

Net bearing capacity is found by subtracting $\gamma_{\rm D} \cdot D = 0.12 \cdot (2 + 2.78)/2 = 0.27$ ksf from $q_{\rm u}$, Equation 4-2. The resultant applied pressure on the footing is $q_{\rm r} = Q/(B'W') = 10/(2\cdot3) = 1.67$ ksf. The factors of safety of all of the above methods are $q'_{\rm u}/q_{\rm r} < 2$. The footing is too small for the applied load and bending moments. Program CBEAR is most conservative. CBEAR ignores subsoil data if the soil is sloping and calculates bearing capacity for the footing on the soil layer only.

CHAPTER 5

DEEP FOUNDATIONS

5-1. <u>Basic Considerations.</u> Deep foundations transfer loads from structures to acceptable bearing strata at some distance below the ground surface. These foundations are used when the required bearing capacity of shallow foundations cannot be obtained, settlement of shallow foundations is excessive, and shallow foundations are not economical. Deep foundations are also used to anchor structures against uplift forces and to assist in resisting lateral and overturning forces. Deep foundations may also be required for special situations such as expansive or collapsible soil and soil subject to erosion or scour.

a. **Description.** Bearing capacity analyses are performed to determine the diameter or cross-section, length, and number of drilled shafts or driven piles required to support the structure.

(1) **Drilled Shafts.** Drilled shafts are nondisplacement reinforced concrete deep foundation elements constructed in dry, cased, or slurry-filled boreholes. A properly constructed drilled shaft will not cause any heave or loss of ground near the shaft and will minimize vibration and soil disturbance. Dry holes may often be bored within 30 minutes leading to a rapidly constructed, economical foundation. Single drilled shafts may be built with large diameters and can extend to deep depths to support large loads. Analysis of the bearing capacity of drilled shafts is given in Section I.

(a) Lateral expansion and rebound of adjacent soil into the bored hole may decrease pore pressures. Heavily overconsolidated clays and shales may weaken and transfer some load to the shaft base where pore pressures may be positive. Methods presented in Section I for calculating bearing capacity in clays may be slightly unconservative, but the FS's should provide an adequate margin of safety against overload.

(b) Rebound of soil at the bottom of the excavation and water collecting at the bottom of an open bore hole may reduce end bearing capacity and may require construction using slurry.

(c) Drilled shafts tend to be preferred to driven piles as the soil becomes harder, pile driving becomes difficult, and driving vibrations affect nearby structures. Good information concerning rock is required when drilled shafts are carried to rock. Rock that is more weathered or of lesser quality than expected may require shaft bases to be placed deeper than expected. Cost overruns can be significant unless good information is available.

(2) **Driven Piles.** Driven piles are displacement deep foundation elements driven into the ground causing the soil to be displaced and disturbed or remolded. Driving often temporarily increases pore pressures and reduces short term bearing capacity, but may increase long term bearing capacity. Driven piles are often constructed in groups to provide adequate bearing capacity. Analysis of the bearing capacity of driven piles and groups of driven piles is given in Section II.

(a) Driven piles are frequently used to support hydraulic structures such as locks and retaining walls and to support bridges and highway overpasses. Piles are also useful in flood areas with unreliable soils.

(b) Pile driving causes vibration with considerable noise and may interfere with the performance of nearby structures and operations. A preconstruction survey of nearby structures may be required.

(c) The cross-section and length of individual piles are restricted by the capacity of equipment to drive piles into the ground.

(d) Driven piles tend to densify cohesionless soils and may cause settlement of the surface, particularly if the soil is loose.

(e) Heave may occur at the surface when piles are driven into clay, but a net settlement may occur over the longterm. Soil heave will be greater in the direction toward which piles are placed and driven. The lateral extent of ground heave is approximately equal to the depth of the bottom of the clay layer.

(3) **Structural capacity.** Stresses applied to deep foundations during driving or by structural loads should be compared with the allowable stresses of materials carrying the load.

b. **Design Responsibility.** Selection of appropriate design and construction methods requires geotechnical and structural engineering skills. Knowledge of how a deep foundation interacts with the superstructure is provided by the structural engineer with soil response information provided by the geotechnical engineer. Useful soil-structure interaction analyses can then be performed of the pile-soil support system.

c. Load Conditions. Mechanisms of load transfer from the deep foundation to the soil are not well understood and complicate the analysis of deep foundations. Methods available and presented below for evaluating ultimate bearing capacity are approximate. Consequently, load tests are routinely performed for most projects, large or small, to determine actual bearing capacity and to evaluate performance. Load tests are not usually performed on drilled shafts carried to bedrock because of the large required loads and high cost.

(1) **Representation of Loads.** The applied loads may be separated into vertical and horizontal components that can be evaluated by soil-structure interaction analyses and computer-aided methods. Deep foundations must be designed and constructed to resist both applied vertical and lateral loads, Figure 5-1. The applied vertical load Q is supported by soil-shaft side friction Q_{su} and base resistance Q_{bu} . The applied lateral load T is carried by the adjacent lateral soil and structural resistance of the pile or drilled shaft in bending, Figure 5-2.

(a) Applied loads should be sufficiently less than the ultimate bearing capacity to avoid excessive vertical and lateral displacements of the pile or drilled shaft. Displacements should be limited to 1 inch or less.



Figure 5-1. Support of deep foundations

(b) Factors of safety applied to the ultimate bearing capacity to obtain allowable loads are often 2 to 4. FS applied to estimations of the ultimate bearing capacity from static load test results should be 2.0. Otherwise, FS should be at least 3.0 for deep foundations in both clay and sand. FS should be 4 for deep foundations in multi-layer clay soils and clay with undrained shear strength $C_u > 6$ ksf.

(2) **Side Friction.** Development of soil-shaft side friction resisting vertical loads leads to relative movements between the soil and shaft. The maximum side friction is often developed after relative small displacements less than 0.5 inch. Side friction is limited by the adhesion between the shaft and the soil or else the shear strength of the adjacent soil, whichever is smaller.

(a) Side friction often contributes the most bearing capacity in practical situations unless the base is bearing on stiff shale or rock that is much stiffer and stronger than the overlying soil.

(b) Side friction is hard to accurately estimate, especially for foundations constructed in augered or partially jetted holes or foundations in stiff, fissured clays.


Figure 5-2. Earth pressure distribution $T_{\mbox{\tiny us}}$ acting on a laterally loaded pile

(3) **Base Resistance.** Failure in end bearing normally consists of a punching shear at the tip. Applied vertical compressive loads may also lead to several inches of compression prior to a complete plunging failure. The full soil shear strength may not be mobilized beneath the pile tip and a well-defined failure load may not be observed when compression is significant.

Section I. Drilled Shafts

5-2. <u>Vertical Compressive Capacity of Single Shafts.</u> The approximate static load capacity of single drilled shafts from vertical applied compressive forces is

$$Q_{u} \approx Q_{bu} + Q_{su} - W_{p}$$

$$Q_{u} \approx Q_{bu}A_{b} + \sum_{i=1}^{n} Q_{sui} - W_{p}$$
(5-1a)
(5-1b)

where

Q_u = ultimate drilled shaft or pile resistance, kips Q_{bu} = ultimate end bearing resistance, kips Q_{su} = ultimate skin friction, kips q_{bu} = unit ultimate end bearing resistance, ksf A_b = area of tip or base, ft² n = number of increments the pile is divided for analysis (referred to as a pile element, Figure C-1) A pile may be visualized to consist of a number of elements as illustrated in Figure C-1, Appendix C, for the calculation of ultimate bearing capacity.

a. End Bearing Capacity. Ultimate end bearing resistance at the tip may be given as Equation 4-1 neglecting pile weight W_{p}

$$q_{\boldsymbol{b}\boldsymbol{u}} = C \cdot N_{\boldsymbol{c}\boldsymbol{p}} \cdot \zeta_{\boldsymbol{c}\boldsymbol{p}} + \boldsymbol{\sigma}_{\boldsymbol{L}} \cdot N_{\boldsymbol{q}\boldsymbol{p}} \zeta_{\boldsymbol{q}\boldsymbol{p}} + \frac{B_{\boldsymbol{b}}}{2} \cdot \boldsymbol{\gamma}_{\boldsymbol{b}} \cdot N_{\boldsymbol{\gamma}\boldsymbol{p}} \cdot \zeta_{\boldsymbol{\gamma}\boldsymbol{p}}$$
(5-2a)

where

$$M_{cp}, M_{qp}, M_{pp} = prie bearing capacity factors of coneston, surcharge, andwedge components$$

 $\zeta_{\rm cp}, \zeta_{\rm qp}, \zeta_{\rm qp} \text{ = pile soil and geometry correction factors of cohesion,} \\ \text{ surcharge, and wedge components}$

Methods for estimating end bearing capacity and correction factors of Equation 5-2a should consider that the bearing capacity reaches a limiting constant value after reaching a certain critical depth. Methods for estimating end bearing capacity from in situ tests are discussed in Section II on driven piles.

(1) **Critical Depth.** The effective vertical stress appears to become constant after some limiting or critical depth Lc, perhaps from arching of soil adjacent to the shaft length. The critical depth ratio Lc/B where B is the shaft diameter may be found from Figure 5-3. The critical depth applies to the Meyerhof and Nordlund methods for analysis of bearing capacity.

(2) Straight Shafts. Equation 5-2a may be simplified for deep foundations without enlarged tips by eliminating the $N_{\gamma p}$ term

$$q_{bu} = C \cdot N_{cp} \cdot \zeta_{cp} + \sigma_{L} \cdot (N_{qp} - 1) \cdot \zeta_{qp}$$

$$(5-2b)$$

or

$$q_{bu} = C \cdot N_{cp} \cdot \zeta_{cp} + \sigma'_{L} \cdot N_{qp} \cdot \zeta_{qp}$$
(5-2c)

Equations 5-2b and 5-2c also compensates for pile weight $W_{\rm p}$ assuming $\gamma_{\rm p}\approx\gamma'_{\rm L}.$ Equation 5-2c is usually used rather than Equation 5-2b because $N_{\rm qp}$ is usually large compared with "1" and $N_{\rm qp}-1\approx N_{\rm qp}$. $W_{\rm p}$ in Equation 5-1 may be ignored when calculating $Q_{\rm u}.$

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Figure 5-3. Critical depth ratio Lc/B (Data from Meyerhof 1976)

(3) **Cohesive Soil.** The undrained shear strength of saturated cohesive soil for deep foundations in saturated clay subjected to a rapidly applied load is $c = C_u$ and the friction angle $\phi = 0$. Equations 5-2 simplifies to (Reese and O'Neill 1988)

$$q_{bu} = F_r N_{cp} C_u, \ q_{bu} \le 80 \, ksf$$
 (5-3)

where the shape factor $\zeta_{\rm cp} = 1$ and $N_{\rm cp} = 6 \cdot [1 + 0.2 \cdot (L/B_{\rm b})] \leq 9$. The limiting $q_{\rm bu}$ of 80 ksf is the largest value that has so far been measured for clays. $C_{\rm u}$ may be reduced by about 1/3 in cases where the clay at the base has been softened and could cause local high strain bearing failure. $F_{\rm r}$ should be 1.0, except when $B_{\rm b}$ exceeds about 6 ft. For base diameter $B_{\rm b} > 6$ ft,

$$F_{r} = \frac{2.5}{aB_{b} + 2.5b}, \quad F_{r} \le 1.0$$
(5-4)

where

a =
$$0.0852 + 0.0252(L/B_b)$$
, a ≤ 0.18
b = $0.45C_u^{0.5}$, $0.5 \leq b \leq 1.5$

The undrained strength of soil beneath the base C_u is in units of ksf. Equation 5-3 limits q_{bu} to bearing pressures for a base settlement of 2.5 inches. The undrained shear strength C_u is estimated by methods in Chapter 3 and may be taken as the average shear strength within $2B_b$ beneath the tip of the shaft.

(4) **Cohesionless Soil.** Hanson, Vesic, Vesic Alternate, and general shear methods of estimating the bearing capacity and adjustment factors are recommended for solution of ultimate end bearing capacity using Equations 5-2. The Vesic method requires volumetric strain data ε_v of the foundation soil in addition to the

effective friction angle ϕ' . The Vesic Alternate method provides a lower bound estimate of bearing capacity. The Alternate method may be more appropriate for deep foundations constructed under difficult conditions, for drilled shafts placed in soil subject to disturbance and when a bentonite-water slurry is used to keep the hole open during drilled shaft construction. Several of these methods should be used for each design problem to provide a reasonable range of the probable bearing capacity if calculations indicate a significant difference between methods.

(a) Hanson Method. The bearing capacity factors $N_{\rm cp}$, $N_{\rm qp}$, and $N_{\gamma \rm p}$ and correction factors $\zeta_{\rm cp}$, $\zeta_{\rm qp}$, and $\zeta_{\gamma \rm p}$ for shape and depth from Table 4-5 may be used to evaluate end bearing capacity using Equations 5-2. Depth factors $\zeta_{\rm cd}$ and $\zeta_{\rm qd}$ contain a "k" term that prevents unlimited increase in bearing capacity with depth. k = tan^{-1}(L_{\rm b}/B) in radians where $L_{\rm b}$ is the embedment depth in bearing soil and B is the shaft diameter. $L_{\rm b}/B \leq L_{\rm c}/B$, Figure 5-3.

(b) Vesic Method. The bearing capacity factors of Equation 5-2b are estimated by (Vesic 1977)

$$N_{cp} = (N_{qp} - 1) \cot \mathbf{\phi}'$$
(5-5a)

$$N_{qp} = \frac{3}{3-\sin\phi} \cdot e^{\frac{(90-\phi')\pi}{180}\tan\phi'} \cdot \tan^2 \left[45 + \frac{\phi'}{2} \right] \cdot I_{rr}^{\frac{4\sin\phi'}{3}(1+\sin\phi')}$$
(5-5b)

$$I_{rr} = \frac{I_r}{1 + \epsilon_v \cdot I_r}$$
(5-5c)

$$I_r = \frac{G_s}{c + \sigma'_t \tan \phi'}$$
(5-5d)

$$\epsilon_{v} = \frac{1 - 2v_{s}}{2(1 - v_{s})} \cdot \frac{\sigma_{L}}{G_{s}}$$
(5-5e)

where

 I_{rr} = reduced rigidity index

 $I_r = rigidity index$

- ϵ_v = volumetric strain, fraction
- v_{s} = soil Poisson's ratio
- G_s = soil shear modulus, ksf
- c = undrained shear strength C_u , ksf
- ϕ' = effective friction angle, deg
- $\sigma'_{\scriptscriptstyle \rm L}$ = effective soil vertical overburden pressure at pile base, ksf

 $I_{\rm rr} \approx I_{\rm r} ~{\rm for~undrained~or~dense~soil~where~} \nu_{\rm s} \approx 0.5.~G_{\rm s} ~{\rm may~be~estimated~from}$ laboratory or field test data, Chapter 3, or by methods described in EM 1110-1-1904. The shape factor $\zeta_{\rm cp}$ = 1.00 and

$$\zeta_{qp} = \frac{1 + 2K_o}{3} \tag{5-6a}$$

$$K_o = (1 - \sin \mathbf{\phi}') \cdot OCR^{\sin \mathbf{\phi}'}$$

(5-6b)

where

 $\rm K_{\circ}~$ = coefficient of earth pressure at rest OCR = overconsolidation ratio

The OCR can be estimated by methods described in Chapter 3 or EM 1110-1-1904. If the OCR is not known, the Jaky equation can be used

$$K_o = 1 - \sin \phi' \tag{5-6c}$$

(c) Vesic Alternate Method. A conservative estimate of $N_{_{\rm T\!P}}$ can be readily made by knowing only the value of $\,\phi\,'$

$$N_{ap} = (1 + \tan \mathbf{\phi}') \cdot e^{\tan \mathbf{\phi}'} \cdot \tan^2 \left[45 + \frac{\mathbf{\phi}'}{2} \right]$$
(5-7)

The shape factor ζ_{qp} may be estimated by Equations 5-6. Equation 5-7 assumes a local shear failure and hence leads to a lower bound estimate of q_{bu} . A local shear failure can occur in poor soils such as loose silty sands or weak clays or else in soils subject to disturbance.

(d) General Shear Method. The bearing capacity factors of Equation5-2b may be estimated assuming general shear failure by (Bowles 1968)

$$N_{qp} = \frac{e^{\frac{270-\Phi'}{180}\cdot\pi\cdot\tan\Phi'}}{2\cdot\cos^2\left[45+\frac{\Phi'}{2}\right]}$$
(5-8)

The shape factor $\zeta_{\rm qp}$ = 1.00. $N_{\rm cp}$ = ($N_{\rm qp}$ -1)cot ϕ' .

b. Skin Friction Capacity. The maximum skin friction that may be mobilized along an element of shaft length ΔL may be estimated by

$$Q_{sui} = A_{si} f_{si}$$
(5-9)

where

Resistance t3o applied loads from skin friction along the shaft perimeter increases with increasing depth to a maximum, then decreases toward the tip. One possible distribution of skin friction is indicated in Figure 5-4. The estimates of skin friction f_{si} with depth is at best approximate. Several methods of estimating f_{si} , based on past experience and the results of load tests, are described below. The vertical load on the shaft may initially increase slightly with increasing depth near the ground surface because the pile adds weight which may not be supported by the small skin friction near the surface. Several of these methods should be used when possible to provide a range of probable skin friction values.



Figure 5-4. An example distribution of skin friction in a pile

(1) **Cohesive Soil.** Adhesion of cohesive soil to the shaft perimeter and the friction resisting applied loads are influenced by the soil shear strength, soil disturbance and changes in pore pressure, and lateral earth pressure existing after installation of the deep foundation. The average undrained shear strength determined from the methods described in Chapter 3 should be used to estimate skin friction. The friction angle ϕ is usually taken as zero.

(a) The soil-shaft skin friction $\,f_{\rm si}\,$ of a length of shaft element may be estimated by

$$f_{si} = \boldsymbol{\alpha}_{a} \cdot C_{u} \tag{5-10}$$

where

 $\alpha_{\rm a}$ = adhesion factor $C_{\rm u}$ = undrained shear strength, ksf

Local experience with existing soils and load test results should be used to estimate appropriate α_a . Estimates of α_a may be made from Table 5-1 in the absence of load test data and for preliminary design.

TABLE 5-1

Adhesion Factors for Drilled Shafts in a Cohesive Soil (Reese and O'Neill 1988)



(b) The adhesion factor may also be related to the plasticity index PI for drilled shafts constructed dry by (Data from Stewart and Kulhawy 1981)

Overconsolidated:	α _a = 0.7 - 0.01·PI	(5-11a)
Sl ig htly over- consolidated(OCR≤2):	α _a = 0.9 - 0.01· <i>PI</i>	(5-11b)
Normally consolidated:	$\alpha_a = 0.9 - 0.004 \cdot PI$	(5-11c)

where 15 < PI < 80. Drilled shafts constructed using the bentonite-water slurry should use α_a of about 1/2 to 2/3 of those given by Equations 5-11.

(2) **Cohesionless Soil.** The soil-shaft skin friction may be estimated using effective stresses with the beta method

$$f_{si} = \boldsymbol{\beta}_f \cdot \boldsymbol{\sigma}_i \tag{5-12a}$$

$$\boldsymbol{\beta}_f = K \tan \, \boldsymbol{\delta}_a \tag{5-12b}$$

where

 The cohesion c is taken as zero.

(a) Figure 5-5 indicates appropriate values of β_f as a function of the effective friction angle ϕ' of the soil prior to installation of the deep foundation.



Figure 5-5. Lateral earth pressure and friction angle factor β as a function of friction angle prior to installation (Data from Meyerhof 1976 and Poulos and Davis 1980)

(b) Refer to Figure 5-3 to determine the critical depth Lc below which $\sigma'_{\rm i}$ remains constant with increasing depth.

(3) **CPT Field Estimate.** The skin friction f_{si} may be estimated from the measured cone resistance q_c for the piles described in Table 5-2 using the curves given in Figure 5-6 for clays and silt, sands and gravels, and chalk (Bustamante and Gianeselli 1983).

c. **Example Application.** A 1.5-ft diameter straight concrete drilled shaft is to be constructed 30 ft deep through a 2-layer soil of a slightly overconsolidated clay with PI = 40 and fine uniform sand, Figure 5-7. Depth of embedment in the sand layer L_b = 15 ft. The water table is 15 ft below ground surface at the clay-sand interface. The concrete unit weight γ_{conc} = 150 lbs/ft³. Design load Q_d = 75 kips.

TABLE 5-2

Descriptions of Deep Foundations. Note that the curves matching the numbers are found in Figure 5-6. (Data from Bustamante and Gianeselli 1983)

Pile	Description	C Remarks	one Resistance q _c , ksf	Soil	Curve
Drilled shaft bored dry	Hole bored dry without slurry; applicable to cohesive soil above	Tool without teeth; oversize blades; remolded soil on sides	any	Clay-Silt	1
	water table	Tool with teeth; immediate	> 25	Clay-Silt	2
		concrete placement	> 94	Clay-Silt	3
			any	Chalk	1
		Immediate concrete placement	> 94	Chalk	3
		Immediate concrete placement with load test	>250	Chalk	4
Drilled shaft with slurry	Slurry supports sides; concrete placed through tremie from	Tool without teeth; oversize blades; remolded soil on sides	any	Clay-Silt	1
	bottom up displacing	Tool with teeth; immediate	> 25	Clay-Silt	2
		concrete placement	> 94	Clay-Silt	3
			any	Sand-Gravel	1
		Fine sands and length < 100 ft	>104	Sand-Gravel	2
		Coarse gravelly sand/gravel and length < 100 ft	>156	Sand-Gravel	3
		Gravel	> 83	Sand-Gravel	4
			any	Chalk	1
		Above water table; immediate concrete placement	> 94	Chalk	3
		Above water table; immediate concrete placement with load test	>250	Chalk	4
Drilled shaft	Bored within steel		any	Clay-Silt	1
with casing	casing; concrete	Dry holes	> 25	Clay-Silt	2
	placed as casing	1	any	Sand-Gravel	
	retrieved	Fine sands and length < 100 ft	> 104	Sand-Gravel	
		Coarse sand/gravel and length < 100 ft	>157	Sand-Gravel	
		Gravel	> 83	Sand-Gravel	4
			any	Chalk	1
		Above water table; immediate concrete placement	> 94	Chalk	3
		Above water table; immediate concrete placement	>250	Chalk	4
Drilled shaft	Hollow stem continuous		any	Clay-Silt	1
hollow auger	auger length > shaft		> 25	Clay-Silt	2
(auger cast	length; auger		any	Sand-Gravel	1
pile)	extracted without	Sand exhibiting some	>104	Sand-Gravel	2
	turning while concrete injected through auger stem	cohesion	any	Chalk	1
Pier	Hand excavated; sides		any	Clay-Silt	1
	supported with		> 25	Clay-Silt	2
	retaining elements or casing	Above water table; immediate concrete placement	> 94	Chalk	3
	2	Above water table; immediate concrete placement	>250	Chalk	4

a. Drilled Shafts

Pile	Description	Remarks	Cone Resistance q_c , ksf	Soil	Curve
Micropile	Drilled with casing;		any	Clay-Silt	1
I	diameter < 10 in.;		> 25	Clay-Silt	2
	casing recovered by	With load test	> 25	Clay-Silt	3
	applying pressure		any	Sand-Gravel	1
	inside top of plugged	Fine sands with load test	>104	Sand-Gravel	2
	casing	Coarse gravelly sand/gravel	>157	Sand-Gravel	3
			any	Chalk	1
			> 94	Chalk	3
Micropile	Drilled < 10 in.		any	Clay-Silt	1
II	diameter; reinforcing		> 42	Clay-Silt	4
	cage placed in hole	With load test	> 42	Clay-Silt	5
	and concrete placed		>104	Sand-Gravel	5
	from bottom-up		> 94	Chalk	4
High pressure	Diameter > 10 in. with		any	Clay-Silt	1
injected	injection system		> 42	Clay-Silt	5
	capable of high		>104	Sand-Gravel	5
	pressures	Coarse gravelly sand/gravel	>157	Sand-Gravel	3
			> 94	Chalk	4

TABLE 5-2 (Continued)

b. Driven Piles

Pile	Description	C Remarks	one Resistance q _c , ksf	Soil	Curve
Screwed-in	Screw type tool placed		any	Clay-Silt	1
	in front of corru-	$q_c < 53 \text{ ksf}$	> 25	Clay-Silt	2
	gated pipe that is	Slow penetration	> 94	Clay-Silt	3
	pushed or screwed	Slow penetration	any	Sand-Gravel	1
	in place; reverse	Fine sands with load test	> 73	Sand-Gravel	2
	rotation to pull	Coarse gravelly sand/gravel	>157	Sand-Gravel	3
	casing while placing	Coarse gravelly sand/gravel	any	Chalk	1
	concrete	q_c < 146 ksf without load test	> 63	Chalk	2
		q_c < 146 ksf with load test	> 63	Chalk	3
		Above water table; immediate concrete placement; slow penetration	> 94	Chalk	3
		Above water table with load test	>250	Chalk	4
Concrete	6 to 20 in. diameter		any	Clay-Silt	1
coated	pipe; H piles;		any	Sand-Gravel	1
	caissons of 2 to 4		>157	Sand-Gravel	4
	sheet pile sections;		any	Chalk	1
	pile driven with	With load test	> 63	Chalk	3
	oversize protecting		> 94	Chalk	3
	shoe; concrete in- jected through hose near oversize shoe producing coating around pile		>250	Chalk	4

TABLE	5-2	(Continued)
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Pile	Description	Remarks	cone	Resistance q _c , ksf	Soil	Curve
Prefabricated	Reinforced or			any	Clay-Silt	1
	prestressed concrete			any	Sand-Gravel	1
	installed by driving	Fine Sands		>157	Sand-Gravel	2
	or vibrodriving	Coarse gravelly sand/gravel		>157	Sand-Gravel	3
	5	With load test		>157	Sand-Gravel	4
				any	Chalk	1
		q_c < 147 ksf without load test	> 63	Chalk	2	-
		$q_c < 147$ ksf with load test	> 63	Chalk	3	
		With load test	2 05	>250	Chalk	4
Steel	H piles; pipe piles;			any	Clay-Silt	1
	any shape obtained by			any	Sand-Gravel	1
	welding sheet-pile	Fine sands with load test		> 73	Sand-Gravel	2
	sections	Coarse gravelly sand/gravel		>157	Sand-Gravel	3
				any	Chalk	1
		q _c < 147 ksf without load test	> 63	Chalk	2	
		q_c < 147 ksf with load test	> 63	Chalk	3	
Prestressed	Hollow cylinder element			any	Clay-Silt	1
tube	of lightly reinforced			any	Sand-Gravel	1
	concrete assembled by	With load test		> 73	Sand-Gravel	2
	prestressing before	Fine sands with load test		>157	Sand-Gravel	2
	driving; 4-9 ft long	Coarse gravelly sand/gravel		>157	Sand-Gravel	3
	elements; 2-3 ft	With load test		>157	Sand-GRavel	4
	diameter; 6 in.			< 63	Chalk	1
	thick; piles driven open ended	q_c < 146 ksf	> 63	Chalk	2	
		With load test		> 63	Chalk	3
		With load test		>250	Chalk	4
Concrete plug	Driving accomplished			any	Clay-Silt	1
bottom of	through bottom	q_c < 42 ksf	> 25	Clay-Si	.lt 3	
Pipe	concrete plug;			any	Sand-Gravel	1
	casing pulled	Fine sands with load test		> 73	Sand-Gravel	2
	while low slump			any	Chalk	1
	concrete compacted through casing			> 94	Chalk	4
Molded	Plugged tube driven to			any	Clay-Silt	1
	final position; tube	With load test		> 25	Clay-Silt	2
	filled to top with			any	Sand-Gravel	1
	medium slump concrete	Fine sand with load test		> 73	Sand-Gravel	2
	and tube extracted	Coarse gravelly sand/gravel		>157	Sand-Gravel	3
		course graveri, sana, graver		any	Chalk	1
		q_c < 157 ksf	> 63	Chalk	2	-
		With load test		> 63	Chalk	3
		With load test		>250	Chalk	4
Pushed-in	Cylindrical concrete			any	Clay-Silt	1
concrete	elements prefabricated			any	Sand-Gravel	1
	or cast-in-place	Fine sands		>157	Sand-Gravel	2
	1.5-8 ft long, 1-2 ft diameter; elements	Coarse gravelly sand/gravel Coarse gravelly sand/gravel wi	th	>157	Sand-Gravel	3
	pushed by hydraulic	load test		>157	Sand-Gravel	4
	jack			any	Chalk	1
		q_c < 157 ksf	> 63	Chalk	2	
		With load test		> 63	Chalk	3
						4
		With load test		>250	Chalk	4



TABLE 5-2 (Concluded)

c. CHALK

Figure 5-6. Skin friction and cone resistance relationships for deep foundations (Data from Bustamante and Gianeselli 1983). The appropriate curve to use is determined from Table 5-2



Figure 5-7. Drilled shaft 1.5-ft diameter at 30-ft depth

(1) Soil Parameters.

(a) The mean effective vertical stress in a soil layer $\sigma'_{\rm s}$ such as in a sand layer below a surface layer, Figure 5-7, may be estimated by

$$\boldsymbol{\sigma}_{s}^{\prime} = L_{clay} \boldsymbol{\gamma}_{c}^{\prime} + \frac{L_{sand}}{2} \boldsymbol{\gamma}_{s}^{\prime}$$
(5-13a)

where

The mean effective vertical stress in the sand layer adjacent to the embedded pile from Equation 5-13a is

The effective vertical soil stress at the pile tip is

$$\sigma'_{s} = L_{clay} \gamma'_{c} + \frac{L_{sand}}{2} \gamma'_{s} = 15 \cdot 0.12 + \frac{15}{2} \cdot 0.04 = 1.8 + 0.3$$

$$\sigma'_{s} = 2.1 \ ksf \qquad \sigma'_{L} = L_{clay} \gamma'_{c} + L_{sand} \gamma'_{s}$$

$$= 15 \cdot 0.12 + 15 \cdot 0.04$$

$$= 1.8 + 0.6 = 2.4 \ ksf$$
(5-13b)

(b) Laboratory strength tests indicate that the average undrained shear strength of the clay is $C_u = 2$ ksf. Cone penetration tests indicate an average cone tip resistance q_c in the clay is 40 ksf and in the sand 160 ksf.

(c) Relative density of the sand at the shaft tip is estimated from Equation 3-5

$$D_r = -74 + 66 \cdot \log_{10} \frac{q_c}{(\sigma'_{vo})^{0.5}} = -74 + 66 \cdot \log_{10} \frac{160}{(2.4)^{0.5}}$$
$$D_r = -74 + 133 = 59 \text{ percent}$$

The effective friction angle estimated from Table 3-1a is $\phi' = 38 \text{ deg}$, while Table 3-1b indicates $\phi' = 36$ to 38 deg. Figure 3-1 indicates $\phi' = 38$ deg. The sand appears to be of medium to dense density. Select a conservative $\phi = 36$ deg. Coefficient of earth pressure at rest from the Jaky Equation 5-6c is $K_o = 1 - \sin \phi$ = 1 - sin 36 deg = 0.42.

(d) The sand elastic modulus $E_{\rm s}$ is at least 250 ksf from Table D-3 in EM 1110-1-1904 using guidelines for a medium to dense sand. The shear modulus $G_{\rm s}$ is estimated using $G_{\rm s} = E_{\rm s}/[2(1 + \upsilon_{\rm s})] = 250/[2(1 + 0.3)] = 96$ or approximately 100 ksf. Poisson's ratio of the sand $\nu_{\rm s} = 0.3$.

(2) End Bearing Capacity. A suitable estimate of end bearing capacity q_{bu} for the pile tip in the sand may be evaluated from the various methods in 5-2a for cohesionless soil as described below. Hanson and Vesic methods account for a limiting effective stress, while the general shear method and Vesic alternate method ignore this stress. The Vesic Alternate method is not used because the sand appears to be of medium density and not loose. Local shear failure is not likely.

(a) Hansen Method. From Table 4-4 (or calculated from Table 4-5), $N_{_{\rm TP}}$ = 37.75 and $N_{_{\rm YP}}$ = 40.05 for ϕ' = 36 deg. From Table 4-5,

From Equation 5-2a

$$q_{bu} = \sigma_{L} N_{qp} \zeta_{qp} + \frac{B_{b}}{2} \cdot \gamma_{b} N_{\gamma p} \zeta_{\gamma p}$$

= 2.4.37.75.2.354 + $\frac{1.5}{2} \cdot 0.04.40.05.0.6$
= 213.3 + 0.7 = 214 ksf

(b) Vesic Method. The reduced rigidity index from Equation 5-5c is

$$I_{rr} = \frac{I_r}{1 + \epsilon_v \cdot I_r} = \frac{57.3}{1 + 0.006 \cdot 57.3} = 42.6$$

where

$$\epsilon_{v} = \frac{1 - 2v_{s}}{2(1 - v_{s})} \cdot \frac{\sigma_{L}}{G_{s}} = \frac{1 - 2 \cdot 0.3}{2(1 - 0.3)} \cdot \frac{2.4}{100} = 0.006$$
(5-5e)

$$I_{r} = \frac{G_{s}}{c + \sigma_{L}^{\prime} \tan \dot{\Phi}^{\prime}} = \frac{100}{2.4 \cdot tan 36} = 57.3$$
(5-5d)

From Equation 5-5b

$$N_{qp} = \frac{3}{3-\sin\phi} \cdot e^{\frac{(90-\phi')\pi}{180}\tan\phi'} \cdot \tan^{2}\left[45 + \frac{\phi'}{2}\right] \cdot \mathcal{I}_{rr}^{\frac{4\sin\phi'}{3(1+\sin\phi')}} \\ = \frac{3}{3-\sin36} \cdot e^{\frac{(90-36)\pi}{180}\tan^{2}6} \cdot \tan^{2}\left[45 + \frac{36}{2}\right] \cdot \mathcal{I}_{rr}^{\frac{4\sin36}{3(1+\sin^{3}6)}} \\ N_{qp} = \frac{3}{3-0.588} \cdot e^{0.685 \cdot 3} \cdot 852 \cdot 42 \cdot 6^{0.494} \\ = 1.244 \cdot 1.984 \cdot 3 \cdot 852 \cdot 6 \cdot 382 = 60.7$$

The shape factor from Equation 5-6a is

$$\zeta_{qp} = \frac{1 + 2K_o}{3} = \frac{1 + 2 \cdot 0.42}{3} = 0.61$$

From Equation 5-2c,

$$q_{bu} = \sigma'_{L} N_{qp} \zeta_{qp} = 2.4 \cdot 60.7 \cdot 0.61 = 88.9 \text{ ksf}$$

(c) General Shear Method. From Equation 5-8

$$N_{qp} = \frac{e^{\frac{270-\Phi'}{180} \cdot \pi \cdot \tan \Phi'}}{2 \cdot \cos^2 \left[45 + \frac{\Phi'}{2} \right]} = \frac{e^{\frac{270-36}{180} \cdot \pi \cdot \tan 36}}{2 \cdot \cos^2 \left[45 + \frac{36}{2} \right]}$$
$$= \frac{e^{1.3\pi \cdot 0.727}}{2 \cdot 0.206} = 47.24$$

The shape factor $~\zeta_{\rm qp}$ = 1.00 when using Equation 5-8. From Equation 5-2c,

$$q_{bu} = \sigma'_{L} N_{qp} \zeta_{qp} = 2.4 \cdot 47.24 \cdot 1.00 = 113.4 \text{ ksf}$$

(d) Comparison of Methods. A comparison of methods is shown as follows:

Method	q _{bu} , ksf
Hansen	214
Vesic	89
General Shear	113

The Hansen result of 214 ksf is much higher than the other methods and should be discarded without proof from a load test. The Vesic and General Shear methods give an average value $q_{bu} = 102$ ksf.

(2) Skin Friction Capacity. A suitable estimate of skin friction f_s from the soil-shaft interface may be evaluated by methods in Section 5-2b for embedment of the shaft in both clay and sand as illustrated below.

(a) Cohesive Soil. The average skin friction from Equation 5-10 is

 $f_s = \alpha_a \cdot C_u = 0.5 \cdot 2 = 1.0 \text{ ksf}$

where α_a was estimated from Equation 5-11b, $\alpha_a = 0.9 - 0.01 \cdot 40 = 0.5$ or 0.55 from Table 5-1. Skin friction from the top 5 ft should be neglected.

(b) Cohesionless Soil. Effective stresses are limited by Lc/B = 10 or to depth Lc = 15 ft. Therefore, $\sigma_{\rm s}'$ = 1.8 ksf, the effective stress at 15 ft. The average skin friction from Equation 5-12a is

$$f_s = \beta_f \sigma'_s = 0.26 \cdot 1.8 = 0.5 \text{ ksf}$$

where $\beta_{\rm f}$ = 0.26 from Figure 5-5 using $\phi^{\,\prime}$ = 36 deg.

(c) CPT Field Estimate. The shaft was bored using bentonite-water slurry. Use curve 2 of clay and silt, Figure 5-6a, and curve 3 of sand and gravel, Figure 5-6b. From these figures, f_s of the clay is 1.5 ksf and f_s of the sand is 2.0 ksf.

(d) Comparison of Methods. Skin friction varies from 1.0 to 1.5 ksf for the clay and 0.5 to 2 ksf for the sand. Skin friction is taken as 1 ksf in the clay and 1 ksf in the sand, which is considered conservative.

(3) Total Capacity. The total bearing capacity from Equation 5-1a is

$$Q_u = Q_{bu} + Q_{su} - W_p$$

where

$$W_{p} = \frac{\pi B^{2}}{4} \cdot L_{clay} \cdot \gamma_{conc} + \frac{\pi B^{2}}{4} \cdot L_{sand} \cdot \gamma'_{conc}$$

= $\frac{\pi 1.5^{2}}{4} \cdot [15 \cdot \frac{150}{1000} + 15 \cdot \frac{86}{1000}]$
= 4.0 + 2.3 = 6.3 kips

 $\gamma_{\rm conc}$ is the unit weight of concrete, 150 lbs/ft³.

(a) Q_{bu} from Equation 5-1b is

$$Q_{bu}$$
 = $q_{bu} \cdot A_{b}$ = 102 \cdot 1.77 = 180 kips

where A_{b} = area of the base, $\pi B^{2}/4 = \pi \cdot 1.5^{2}/4 = 1.77$ ft².

(b) Q_{su} from Equation 5-1b and 5-9

 $Q_{su} = \sum_{i=1}^{n} Q_{sui} = C_s \cdot \Delta L \sum_{i=1}^{2} f_{si}$

where $C_s = \pi B$ and $\Delta L = 15$ ft for clay and 15 ft for sand. Therefore,

sand clay $Q_{su} = \pi \cdot B \cdot [\Delta L \cdot f_s + \Delta L \cdot f_s)$ $= \pi \cdot 1.5 \cdot [15 \cdot 1 + 10 \cdot 1)] = 118 \text{ kips}$

where skin friction is ignored in the top 5 ft of clay.

(c) Total Capacity. Inserting the end bearing and skin resistance bearing capacity values into Equation 5-1a is

 $Q_{ij} = 180 + 118 - 6 = 292$ kips

(4) Allowable Bearing Capacity. The allowable bearing capacity from Equation 1-2b is

$$Q_a = \frac{Q_u}{FS} = \frac{292}{3} = 97$$
 kips

using FS = 3 from Table 1-2. $Q_d = 75 < Q_a = 97$ kips. A settlement analysis should also be performed to check that settlement is tolerable. A load test is recommended to confirm or correct the ultimate bearing capacity. Load tests can increase Q_a because FS = 2 and permit larger Q_d depending on results of settlement analysis.

d. Load Tests for Vertical Capacity. ASTM D 1143 testing procedures for piles under static compression loads are recommended and should be performed for individual or groups of vertical and batter shafts (or piles) to determine their response to axially applied compression loads. Load tests lead to the most efficient use of shafts or piles. The purpose of testing is to verify that the actual pile response to compression loads corresponds to that used for design and that the calculated ultimate load is less than the actual ultimate load. A load cell placed at the bottom of the shaft can be used to determine the end bearing resistance and to calculate skin friction as the difference between the total capacity and end bearing resistance.

(1) **Quick Load Test.** The "Quick" load test option is normally satisfactory, except that this test should be taken to plunging failure or three times the design load or 1000 tons, whichever comes first.

(2) **Cost Savings.** Load tests can potentially lead to significant savings in foundation costs, particularly on large construction projects when a substantial part of the bearing capacity is contributed by skin friction. Load tests also assist the selection of the best type of shaft or pile and installation depth.

(3) Lower Factor of Safety. Load tests allow use of a lower safety factor of 2 and can offer a higher allowable capacity.

(4) **Scheduling of Load Tests.** Load tests are recommended during the design phase, when economically feasible, to assist in selection of optimum equipment for construction and driving the piles in addition to verifying the bearing capacity. This information can reduce contingency costs in bids and reduce the potential for later claims.

(a) Load tests are recommended for most projects during early construction to verify that the allowable loads used for design are appropriate and that installation procedures are satisfactory.

(b) Load tests during the design phase are economically feasible for large projects such as for multistory structures, power plants, locks and dams.

(c) When load tests are performed during the design phase, care must be taken to ensure that the same procedures and equipment (or driving equipment including hammer, helmet, cushion, etc. in the case of driven piles) are used in actual construction.

(5) Alternative Testing Device. A load testing device referred to as the Osterberg method (Osterberg 1984) can be used to test both driven piles and drilled shafts. A piston is placed at the bottom of the bored shaft before the concrete is placed or the piston can be mounted at the bottom of a pile, Figure 5-8a. Pressure is applied to hydraulic fluid which fills a pipe leading to the piston. Fluid passes through the annular space between the rod and pressure pipe into the pressure chamber. Hydraulic pressure expands the pressure chamber forcing the piston down. This pressure is measured by the oil (fluid) pressure gage, which can be calibrated to determine the force applied to the bottom of the pile and top of the piston. End bearing capacity can be determined if the skin friction capacity exceeds the end bearing capacity; this condition is frequently not satisfied.

(a) A dial attached to the rod with the stem on the reference beam, Figure 5-8b, measures the downward movement of the piston. A dial attached to the pressure pipe measures the upward movement of the pile base. A third dial attached to the reference beam with stem on the pile top measures the movement of the pile top. The difference in readings between the top and bottom of the pile is the elastic compression due to side friction. The total side friction force can be estimated using Young's modulus of the pile.

(b) If the pile is tested to failure, the measured force at failure (piston downward movement is continuous with time or excessive according to guidance in Table 5-3) is the ultimate end bearing capacity. The measured failure force in the downward plunging piston therefore provides a FS > 2 against failure considering that the skin friction capacity is equal to or greater than the end bearing capacity.

(c) This test can be more economical and completed more quickly than a conventional load test; friction and end bearing resistance can be determined separately; optimum length of driven piles can be determined by testing the same pile at successfully deeper depths. Other advantages include ability to work over water, to work in crowded and inaccessible locations, to test battered piles, and to check pullout capacity as well as downward load capacity.



a. LOAD CELL ARRANGEMENT





Figure 5-8. Example load test arrangement for Osterberg method

(6) Analysis of Load Tests. Table 5-3 illustrates four methods of estimating ultimate bearing capacity of a pile from data that may be obtained from a loaddisplacement test such as described in ASTM D 1143. At least three of these methods, depending on local experience or preference, should be used to determine a suitable range of probable bearing capacity. The methods given in Table 5-3 give a range of ultimate pile capacities varying from 320 to 467 kips for the same pile load test data.

5-3. <u>Capacity to Resist Uplift and Downdrag</u>. Deep foundations may be subject to other vertical loads such as uplift and downdrag forces. Uplift forces are caused by pullout loads from structures or heave of expansive soils surrounding the shaft tending to drag the shaft up. Downdrag forces are caused by settlement of soil surrounding the shaft that exceeds the downward displacement of the shaft and increases the downward load on the shaft. These forces influence the skin friction that is developed between the soil and the shaft perimeter and influences bearing capacity.

TABLE 5-3

	Procedure	Diagram		
Tangent Butler and Hoy 1977)	 Draw a tangent line to the curve at the graph's origin 			
10, 1977,	 Draw another tangent line to the curve with slope equivalent to slope of 1 inch for 40 kips of load 	600 С 500 С 500 С 2 2 = 390 кips		
	 Ultimate bearing capacity is the load at the intersection of the tangent lines 	G 400 1 INCH 40 KIPS		
		APPLED LOAD		
		APPLI 001		
	-72	DISPLACEMENT p, INCHES		
lmit Value Davisson 1972)	1. Draw a line with slope $\frac{\pi B^2}{4L} \cdot E_p$ where B = diameter 4L of pile, inches; E_p = Young's pile modulus, kips/inch ² ; L = pile length, inches			
	 Draw a line parallel with the first line starting at a displacement of 0.15 + 	0, = 320 KIPS		
120		□ 0.47 IN.		
.20	inch at zero load			
20	inch at zero load 3. Ultimate bearing capacity is the load at the intersection	월 200 ₩		

Methods of Estimating Ultimate Bearing Capacity From Load Tests

Method	Procedure	Diagram
80 Percent (Hansen 1963)	1. Plot load test results as $\frac{\sqrt{\rho}}{Q}$ vs. ρ 2. Draw straight line through	$0.008 = 1/2 k_{0b} = 467 \text{ KiPS}$ $0.005 = \rho_{11} = b/a = 2.8 \text{ INCHES}$
	data points 3. Determine the slope a and intercept b of this line	
	4. Ultimate bearing capacity is $Q_u = \frac{1}{2 \sqrt{ab}}$	C = 0.00064
	$2 \ \sqrt[]{ab}$ 5. Ultimate deflection is $\rho_{u} \ = \ b/a$	$\begin{array}{c} 0.002 \\ 0.001 \\ 0.001 \end{array}$
		$a.000 \qquad \qquad$
00 Percent Hansen 1963)	 Calculate 0.9Q for each load Q Find ρ_{0.9Q}, displacement for load of 0.9Q, for each Q from Q vs. ρ plot 	0 400
	3. Determine $2\rho_{0.9Q}$ for each Q and plot vs. Q on chart with the load test data of Q vs. ρ	$\begin{array}{c} \begin{array}{c} \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} \\ \begin{array}{c} \\ \\ \end{array} $
	 Ultimate bearing capacity is the load at the intersection of the two plots of data 	
		$ \begin{array}{c} $

TABLE 5-3 (Concluded)

a. **Method of Analysis.** Analysis of bearing capacity with respect to these vertical forces requires an estimate of the relative movement between the soil and the shaft perimeter and the location of neutral point n, the position along the shaft length where there is no relative movement between the soil and the shaft. In addition, tension or compression stresses in the shaft or pile caused by uplift or downdrag must be calculated to properly design the shaft. These calculations are time-dependent and complicated by soil movement. Background theory for analysis of pullout, uplift and downdrag forces of single circular drilled shafts, and a method for computer analysis of these forces is provided below. Other methods of

evaluating vertical capacity for uplift and downdrag loads are given in Reese and O'Neill (1988).

b. **Pullout.** Deep foundations are frequently used as anchors to resist pullout forces. Pullout forces are caused by overturning moments such as from wind loads on tall structures, utility poles, or communication towers.

(1) Force Distribution. Deep foundations may resist pullout forces by shaft skin resistance and resistance mobilized at the tip contributed by enlarged bases illustrated in Figure 5-9. The shaft resistance is defined in terms of negative skin friction f_n to indicate that the shaft is moving up relative to the soil. This is in contrast to compressive loads that are resisted by positive skin friction where the shaft moves down relative to the soil, Figure 5-4. The shaft develops a tensile stress from pullout forces. Bearing capacity resisting pullout may be estimated by

$$P_{u} = Q_{bu} + P_{nu} + W_{p}$$
 (5-14a)

$$P_{u} = q_{bu} A_{bp} + \sum_{j=1}^{n} P_{nuj} + W_{p}$$
 (5-14b)

where

(2) **End Bearing Resistance.** Enlarged bases of drilled shafts resist pullout and uplift forces. q_{bu} may be estimated using Equation 5-2c. Base area A_b resisting pullout to be used in Equation 5-1b for underreamed drilled shafts is

$$A_{bp} = \frac{\pi}{4} \cdot (B_b^2 - B_s^2)$$
 (5-15)

where

 B_b = diameter of base, ft B_s = diameter of shaft, ft

(a) Cohesive Soil. The undrained shear strength $C_{\rm u}$ to be used in Equation 5-3 is the average strength above the base to a distance of $2B_{\rm b}$. $N_{\rm cp}$ varies from 0 at the ground surface to a maximum of 9 at a depth of $2.5B_{\rm b}$ below the ground (Vesic 1971).

(b) Cohesionless Soil. $N_{\rm qp}$ of Equation 5-2 can be obtained from Equation 5-7 of the Vesic alternate method where $\zeta_{\rm qp}$ is given by Equations 5-6.



Figure 5-9. Underreamed drilled shaft resisting pullout

(3) **Skin Resistance.** The diameter of the shaft may be slightly reduced from pullout forces by a Poisson effect that reduces lateral earth pressure on the shaft perimeter. Skin resistance will therefore be less than that developed for shafts subject to compression loads because horizontal stress is slightly reduced. The mobilized negative skin friction f_{ni} may be estimated as 2/3 of that evaluated for compression loads f_{si}

$$\sum_{i=1}^{n} P_{nui} = C_s \cdot \Delta L \sum_{i=1}^{n} f_{ni}$$

$$f_{ni} = \frac{2}{3} \cdot f_{si}$$
(5-16a)
(5-16b)

where

 C_s = shaft circumference, ft

- ΔL = length of pile element i, ft
- $\rm f_{si}$ = positive skin friction of element ~i~ from compressive loading using Equations 5-10 to 5-12

The sum of the elements equals the shaft length.

c. **Uplift.** Deep foundations constructed in expansive soil are subject to uplift forces caused by swelling of expansive soil adjacent to the shaft. These uplift forces cause a friction on the upper length of the shaft perimeter tending to move the shaft up. The shaft perimeter subject to uplift thrust is in the soil subject to heave. This soil is often within the top 7 to 20 ft of the soil profile referred to as the depth of the active zone for heave Z_a . The shaft located within Z_a is sometimes constructed to isolate the shaft perimeter from the expansive soil to reduce this uplift thrust. The shaft base and underream resisting uplift should be located below the depth of heaving soil.

(1) Force Distribution. The shaft moves down relative to the soil above neutral point n, Figure 5-10, and moves up relative to the soil below point n. The negative skin friction f_n below point n and enlarged bases of drilled shafts resist the uplift thrust of expansive soil. The positive skin friction f_s above point n contributes to uplift thrust from heaving soil and puts the shaft in tension. End bearing and skin friction capacity resisting uplift thrust may be estimated by Equations 5-14.



Figure 5-10. Deep foundation resisting uplift thrust

(2) **End Bearing.** End bearing resistance may be estimated similar to that for pullout forces. N_{cp} should be assumed to vary from 0 at the depth of the active zone of heaving soil to 9 at a depth 2.5B_b below the depth of the active zone of heave. The depth of heaving soil may be at the bottom of the expansive soil layer or it may be estimated by guidelines provided in TM 5-818-7, EM 1110-1-1904, or McKeen and Johnson (1990).

(3) **Skin Friction.** Skin friction from the top of the shaft to the neutral point n contributes to uplift thrust, while skin friction from point n to the base contributes to skin friction that resists the uplift thrust.

(a) The magnitude of skin friction $f_{\rm s}$ above point n that contributes to uplift thrust will be as much or greater than that estimated for compression loads. The adhesion factor $\alpha_{\rm a}$ of Equation 5-10 can vary from 0.6 to 1.0 and can contribute to shaft heave when expansive soil is at or near the ground surface. $\alpha_{\rm a}$ should not be underestimated when calculating the potential for uplift thrust; otherwise, tension, steel reinforcement, and shaft heave can be underestimated.

(b) Skin friction resistance f_n that resists uplift thrust should be estimated similar to that for pullout loads because uplift thrust places the shaft in tension tending to pull the shaft out of the ground and may slightly reduce lateral pressure below neutral point n.

d. **Downdrag.** Deep foundations constructed through compressible soils and fills can be subject to an additional downdrag force. This downdrag force is caused by the soil surrounding the drilled shaft or pile settling downward more than the deep foundation. The deep foundation is dragged downward as the soil moves down. The downward load applied to the shaft is significantly increased and can even cause a structural failure of the shaft as well as excessive settlement of the foundation. Settlement of the soil after installation of the deep foundation can be caused by the weight of overlying fill, settlement of poorly compacted fill and lowering of the groundwater level. The effects of downdrag can be reduced by isolating the shaft from the soil, use of a bituminous coating or allowing the consolidating soil to settle before construction. Downdrag loads can be considered by adding these to column loads.

(1) Force Distribution. The shaft moves up relative to the soil above point n, Figure 5-11, and moves down relative to the soil below point n. The positive skin friction f_s below point n and end bearing capacity resists the downward loads applied to the shaft by the settling soil and the structural loads. Negative skin friction f_n above the neutral point contributes to the downdrag load and increases the compressive stress in the shaft.

(2) **End Bearing.** End bearing capacity may be estimated similar to methods for compressive loads given by Equations 5-2.

(3) **Skin Friction.** Skin friction may be estimated by Equation 5-9 where the positive skin friction is given by Equations 5-10 to 5-12.

e. **Computer Analysis.** Program AXILTR (AXIal Load-TRansfeR), Appendix C, is a computer program that computes the vertical shaft and soil displacements for axial down-directed structural, axial pullout, uplift, and down-drag forces using equations in Table 5-4. Load-transfer functions are used to relate base pressures and skin friction with displacements. Refer to Appendix C for example applications using AXILTR for pullout, uplift and downdrag loads.

(1) **Load-Transfer Principle.** Vertical loads are transferred from the top of the shaft to the supporting soil adjacent to the shaft using skin friction-load transfer functions and to soil beneath the base using consolidation theory or base load-transfer functions. The total bearing capacity of the shaft Q_u is the sum of the total skin Q_{su} and base Q_{bu} resistances given by Equations 5-1.



Figure 5-11. Deep foundation resisting downdrag. $\rm q_{\rm load}$ is an area pressure from loads such as adjacent structures

(a) The load-displacement calculations for rapidly applied downward vertical loads have been validated by comparison with field test results (Gurtowski and Wu 1984). The strain distribution from uplift forces for drilled shafts in shrink/swell soil have been validated from results of load tests (Johnson 1984).

(b) The program should be used to provide a minimum and maximum range for the load-displacement behavior of the shaft for given soil conditions. A listing of AXILTR is provided to allow users to update and calibrate this program from results of field experience.

(2) Base Resistance Load Transfer. The maximum base resistance $\,q_{bu}\,$ in Equation 5-1b is computed by AXILTR from Equation 5-2a

$$q_{bu} = CN_{cp} + \sigma_L N_{qp} \qquad (5-17)$$

where

TABLE 5-4

Program AXILTR Shaft Resistance To Pullout, Uplift and Downdrag Loads

Soil Volume Change	Type of Applied Load	Applied Load, Pounds		ance to Applied oad, Pounds	Equations
None	Pullout	$Q_{\rm DL}$ – P	Straight:	Q _{aur} + W _p Q _{aur} :	L = πB _a ∫f _a dL 0
			Underream	: Smaller of	
				Q_{sub} + W_{p}	$Q_{sub} = \pi B_b \int \tau_s dL$
				Q_{sur} + Q_{bur} + W_{p}	$egin{array}{ccc} \eta_{\mathrm{pur}} &=_{\mathrm{b}} q_{\mathrm{bu}} \mathbf{B}_{\mathrm{s}}^2 \end{pmatrix}$ (\mathbf{B}^2
					$W_{\underline{A}}^{\pi}$ s=L γ_{p} ·····B ²
Swelling soil	Uplift thrust	Q _{us}	Straight:	Q_{sur} + W_p Q_{us}	$= \pi B_{s} \int f_{s} dL $
			Underream	1:	L
				Q_{sur} + Q_{bur} + W_{p}	Q _{sur} =d h B _s ∫ f- L _n
					$\begin{array}{c} \eta & \ Q_{\mathrm{pur}} & =_{\mathrm{b}} q_{\mathrm{bu}} \mathrm{B}_{\mathrm{s}}^{2} \end{array}$ (B^{2}
Settling soil	Downdrag	Q_d + Q_{sud}	Q_{sur} + Q_{bu}		$Q_{sud} = \pi B_s \int_{0}^{L_n} f_n dL$
					$\mathbf{q}_{sur} = \mathbf{d}\mathbf{n} \mathbf{B}_s \int \mathbf{f} - \mathbf{L}_n$
Nomencla					
B _b B _s	Base diameter Shaft diamete			Q _{DL} Dead load of P Pullout load	structure, pounds
B₅ f−₅		r, it ized shear streng	gth, psf		d, pounds l shear resistance of
fn		friction, psf			ameter $B_{\scriptscriptstyle \rm b}$ and length equal
L	Shaft length,				underream, pounds
L _n		tral point n, ft resistance, psf	2	Q _{sud} Downdrag, pou	unds 1 resistance, pounds
		capacity, pound		Q _{sur} Ultimate skin Q _{us} Uplift thrust	
	Ultimate base	resistance of up derream, pounds	per		Dead + Live loads, pounds
τ_{s}	Soil shear st	rength, psf		$\gamma_{\rm p}$ Unit shaft w	weight, pounds/ft3

Correction factors $\,\zeta\,$ are assumed unity and the $\,N_{\gamma_P}\,$ term is assumed negligible. Program AXILTR does not limit $\,\sigma_{\rm L}'.\,$

(a) $N_{\rm qp}$ for effective stress analysis is given by Equation 5-7 for local shear (Vesic Alternate method) or Equation 5-8 for general shear.

(b) N_{cp} for effective stress analysis is given by

$$N_{cp} = (N_{qp} - 1) \cot \mathbf{\phi}' \tag{5-5a}$$

 N_{cp} for total stress analysis is assumed 9 for general shear and 7 for local shear; N_{cp} and total stress friction angle ϕ are zero for total stress analysis.

(c) End bearing resistance may be mobilized and base displacements computed using the Reese and Wright (1977) or Vijayvergiya (1977) base load-transfer functions, Figure 5-12a, or consolidation theory. Ultimate base displacement for the Reese and Wright model is computed by

$$\mathbf{\rho}_{bu} = 2B_b \cdot \epsilon_{50} \cdot 12 \tag{5-18}$$

where

 $\rho_{\mbox{\tiny bu}}$ = ultimate base displacement, in.

 B_{b} = diameter of base, ft

 $\epsilon_{\rm 50}$ = strain at 1/2 of maximum deviator stress of clay from undrained triaxial test, fraction

The ultimate base displacement for the Vijayvergiya model is taken as 4 percent of the base diameter.

(d) Base displacement may be calculated from consolidation theory for overconsolidated soils as described in Chapter 3, Section III of EM 1110-1-1904. This calculation assumes no wetting beneath the base of the shaft from exterior water sources, except for the effect of changes in water level elevations. The calculated settlement is based on effective stresses relative to the initial effective pressure on the soil beneath the base of the shaft prior to placement of any structural loads. The effective stresses include any pressure applied to the surface of the soil adjacent to the shaft. AXILTR may calculate large settlements for small applied loads on the shaft if the maximum past pressure is less than the initial effective pressure simulating an underconsolidated soil. Effective stresses in the soil below the shaft base caused by loads in the shaft are attenuated using Boussinesg stress distribution theory (Boussinesg 1885).

(3) **Underream Resistance.** The additional resistance provided by a bell or underream for pullout or uplift forces is 7/9 of the end bearing resistance. If applied downward loads at the base of the shaft exceed the calculated end bearing capacity, AXILTR prints "THE BEARING CAPACITY IS EXCEEDED". If pullout loads exceed the pullout resistance, the program prints "SHAFT PULLS OUT". If the shaft heave exceeds the soil heave, the program prints "SHAFT UNSTABLE".

(4) **Skin Resistance Load Transfer.** The shaft skin friction load-transfer functions applied by program AXILTR are the Seed and Reese (1957) and Kraft, Ray, and Kagawa (1981) models illustrated in Figure 5-12b. The Kraft, Ray, and Kagawa model requires an estimate of a curve fitting constant R from

$$G_{s} = G_{i} \left[1 - \frac{\tau R}{\tau_{\max}} \right]$$
 (5-19a)



b. SHAFT TRANSFER (NORMALIZED T-Z) FUNCTIONS
 Figure 5-12. Load-transfer curves applied in AXILTR

where

G_s = soil shear modulus at an applied shear stress τ, pounds/square foot (psf) G_i = initial shear modulus, psf τ = shear stress, psf τ_{max} = shear stress at failure, psf R = curve fitting constant, usually near 1.0

The curve fitting constant R is the slope of the relationship of 1 - $G_{_{\rm S}}/G_{_{\rm i}}$ versus $\tau/\tau_{_{max}}$ and may be nearly 1.0. The soil shear modulus $G_{_{\rm S}}$ is found from the elastic soil modulus $E_{_{\rm S}}$ by

$$G_s = \frac{E_s}{2\left(1 + v_s\right)} \tag{5-19b}$$

where $v_{\rm s}$ is the soil Poisson's ratio. A good value for $v_{\rm s}$ is 0.3 to 0.4.

(a) Load-transfer functions may also be input into AXILTR for each soil layer up to a maximum of 11 different functions. Each load-transfer function consists of 11 data values consisting of the ratio of the mobilized skin friction/maximum mobilized skin friction $f_s/f_{\overline{s}}$ correlated with displacement as illustrated in Figure 5-12b. The maximum mobilized skin friction $f_{\overline{s}}$ is assumed the same as the maximum soil shear strength. The corresponding 11 values of the shaft displacement (or shaft movement) in inches are input only once and applicable to all of the load-transfer functions. Therefore, the values of $f_s/f_{\overline{s}}$ of each load transfer function must be correlated with the given shaft displacement data values.

(b) The full mobilized skin friction $\, f_{\overline{s}} \,$ is computed for effective stresses from

$$f_{\overline{s}} = c' + \beta_f \sigma'_v \tag{5-20}$$

where

c' = effective cohesion, psf $\beta_{\rm f}$ = lateral earth pressure and friction angle factor $\sigma'_{\rm v}$ = effective vertical stress, psf

The factor $\,\beta_{\rm f}\,$ is calculated in AXILTR by

$$\boldsymbol{\beta}_f = K_o \tan \boldsymbol{\phi}' \tag{5-21}$$

where

 $K_{_{\rm O}}$ = lateral coefficient of earth pressure at rest $\phi^{\,\prime}$ = effective peak friction angle from triaxial tests, deg

The effective cohesion is usually ignored.

(c) The maximum mobilized skin friction $f_{\overline{s}}$ for each element is computed for total stresses from Equation 5-10 using α_a from Table 5-1 or Equations 5-11.

(5) Influence of Soil Movement. Soil movement, heave or settlement, alters the performance of the shaft. The magnitude of the soil heave or settlement is controlled by the swell or recompression indices, compression indices, maximum past pressure and swell pressure of each soil layer, depth to the water table, and depth of the soil considered active for swell or settlement. The swell index is the slope of the rebound pressure - void ratio curve on a semi-log plot of consolidation test results as described in ASTM D 4546. The recompression index is the slope of the pressure-void ratio curve on a semi-log plot for pressures less than the maximum past pressure. The swell index is assumed identical with the recompression index. The compression index is the slope of the linear portion of the pressure-void ratio curve on a semi-log plot for pressures exceeding the maximum past pressure. The maximum past pressure (preconsolidation stress) is the greatest effective pressure to which a soil has been subjected. Swell pressure is defined as a pressure which prevents a soil from swelling at a given initial void ratio as described by method C in ASTM D 4546.

(a) The magnitude of soil movement is determined by the difference between the initial and final effective stresses in the soil layers and the soil parameters. The final effective stress in the soil is assumed equivalent with the magnitude of the total vertical overburden pressure, an assumption consistent with zero final pore water pressure. Program AXILTR does not calculate soil displacements for shaft load transferred to the soil.

(b) Swell or settlement occurs depending on the difference between the input initial void ratio and the final void ratio determined from the swell and compression indices, the swell pressure, and the final effective stress for each soil element. The method used to calculate soil swell or settlement of soil adjacent to the shaft is described as Method C of ASTM D 4546.

(c) The depth of the active zone Z_a is required and it is defined as the soil depth above which significant changes in water content and soil movement can occur because of climate and environmental changes after construction of the foundation. Refer to EM 1110-1-1904 for further information.

5-4. Lateral Load Capacity of Single Shafts. Deep foundations may be subject to lateral loads as well as axial loads. Lateral loads often come from wind forces on the structure or inertia forces from traffic. Lateral load resistance of deep foundations is determined by the lateral resistance of adjacent soil and bending moment resistance of the foundation shaft. The ultimate lateral resistance T_u often develops at lateral displacements much greater than can be allowed by the structure. An allowable lateral load T_a should be determined to be sure that the foundation will be safe with respect to failure.

a. Ultimate Lateral Load. Brom's equations given in Table 5-5 can give good results for many situations and these are recommended for an initial estimate of ultimate lateral load T_u . Ultimate lateral loads can be readily determined for complicated soil conditions using a computer program such as COM624G based on beam-column theory and given p-y curves (Reese, Cooley, and Radhakkrishnan 1984). A p-y curve is the relationship between the soil resistance per shaft length (kips/inch) and the deflection (inches) for a given lateral load T.

TABLE 5-5

Brom's Equations for Ultimate Lateral Load (Broms 1964a, Broms 1964b, Broms 1965)



a. Free Head Pile in Cohesive Soil

b. Free Head Pile in Cohesionless Soil



TABLE 5-5 (Continued)

c. Fixed Head Pile in Cohesive Soil



d. Fixed Head Pile in Cohesionless Soil

Equations		Diagram
$T_s = 1.5\gamma B_s K_p L^2$	(5-25a)	
$L_{cs} = \left[\frac{M_{y}}{\gamma B_{s} K_{p}}\right]^{1/3}$	(5-25b)	
	$T_{s} = 1.5\gamma B_{s}K_{p}L^{2}$ $T_{s} = \left[\frac{M_{y}}{M_{y}} \right]^{1/3}$	$T_{s} = 1.5\gamma B_{s} K_{p} L^{2} $ (5-25a) $T_{s} = \left[\frac{M_{y}}{M_{y}} \right]^{1/3} $ (5-25b)



(1) **Considerations.**

(a) Lateral load failure may occur in short drilled shafts and piles, which behave as rigid members, by soil failure and excessive pile deflection and in long piles by excessive bending moment.

(b) Computation of lateral deflection for different shaft penetrations may be made to determine the depth of penetration at which additional penetration will not significantly decrease the groundline deflection. This depth will be approximately $4\beta_{\ell}$ for a soil in which the soil stiffness increases linearly with depth

$$\beta_{\ell} = \left[\frac{E_p I_p}{k}\right]^{1/5} \tag{5-26}$$

where

 ${\rm E}_{\rm p}$ = elastic modulus of shaft or pile, ksf

 ${\rm I}_{_{\rm p}}$ = moment of inertia of shaft, ${\rm ft}^4$

k = constant relating elastic soil modulus with depth, $\rm E_{s}$ = kz $\rm kips/ft^{3}$

Shafts which carry insignificant axial loads such as those supporting overhead signs can be placed at this minimum depth if their lateral load capacity is acceptable.

(c) Cyclic loads reduce the support provided by the soil, cause gaps to appear near the ground surface adjacent to the shaft, increase the lateral deflection for a given applied lateral load and can reduce the ultimate lateral load capacity because of the loss of soil support.

(d) Refer to ASTM D 3966 for details on conducting lateral load tests.

(2) **Broms' Closed Form Solution.** Broms' method uses the concept of a horizontal coefficient of subgrade reaction and considers short pile failure by flow of soil around the pile and failure of long piles by forming a plastic hinge in the pile. Refer to Broms (1964a), Broms (1964b), Broms (1965), and Reese (1986) for estimating T_u from charts.

(a) Cohesive soil to depth $1.5B_{\rm s}$ is considered to have negligible resistance because a wedge of soil to depth $1.5B_{\rm s}$ is assumed to move up and when the pile is deflected.

(b) Iteration is required to determine the ultimate lateral capacity of long piles T_{ul} in cohesionless soil, Table 5-5. Distance f, Table 5-5b and 5-5d, may first be estimated and T_{ul} calculated; then, f is calculated and T_{ul} recalculated as necessary. T_{ul} is independent of length L in long piles.

(3) **Load Transfer Analysis.** The method of solution using load transfer p-y curves is also based on the concept of a coefficient of horizontal subgrade reaction. A fourth-order differential equation is solved using finite differences and load transfer p-y curves.

(a) Numerous p-y relationships are available to estimate appropriate values of soil stiffness for particular soil conditions (Reese 1986). p-y curves developed from local experience and back-calculated from lateral load tests may also be used in program COM624G.

(b) Program COM624G has provided excellent agreement with experimental data for many load test results.

b. Allowable Lateral Loads. Estimates of allowable lateral load T_a is best accomplished from results of lateral load-deflection (p-y) analysis using given p-y cuves and a computer program such as COM624G. The specified maximum allowable lateral deflection should be used to estimate T_a .

(1) Minimum and maximum values of the expected soil modulus of subgrade reaction should be used to determine a probable range of lateral load capacity. This modulus may be estimated from results of pressuremeter tests using the Menard deformation modulus (Reese 1986), estimates of the elastic soil modulus with depth, or values given in Table 5-6b.

(2) A rough estimate of allowable lateral load T_a may be made by calculating lateral groundline deflection y_o using Equations in Table 5-6,

$$T_a = \frac{Y_a}{Y_o} \cdot T_u \tag{5-27}$$

where $\,y_a\,$ is a specified allowable lateral deflection and $\,T_u\,$ is estimated from equations in Table 5-5.

c. **Example Application.** A concrete drilled shaft is to be constructed to support a design lateral load $T_d = 10$ kips. This load will be applied at the ground surface, therefore length above the ground surface e = 0. Lateral deflection should be no greater than $y_a = 0.25$ inch. An estimate is required to determine a suitable depth of penetration and diameter to support this lateral load in a clay with cohesion $C_u = 1$ ksf for a soil in which the elastic modulus is assumed to increase linearly with depth. A trial diameter $B_s = 2.5$ ft (30 inches) is selected with 1 percent steel. Yield strength of the steel $f'_{ys} = 60$ ksi and concrete strength $f'_c = 3$ ksi.

(1) Minimum Penetration Depth. The minimum penetration depth may be estimated from Equation 5-26 using E_pI_p and k. Table 5-7 illustrates calculation of E_pI_p for a reinforced concrete shaft which is $2.7 \cdot 10^5$ kips-ft². k = 170 kips/ft³ from Table 5-6b when the elastic modulus increases linearly with depth. Therefore,

$$\beta_{\ell} = \left[\frac{E_{p}I_{p}}{k}\right]^{1/5} = \left[\frac{2.7 \cdot 10^{5}}{170}\right]^{1/5} = 4.37 \ ft$$

The minimum depth of penetration $L = 4\beta_{\ell} = 4 \cdot 4.37 = 17.5$ ft. Select L = 20 ft.
TABLE 5-6

$\frac{\text{Estimation of Ultimate Lateral Deflection } y_{\circ} \text{ at the Groundline}}{(\text{Broms 1964a, Reese 1986})}$

a. Soil With Modulus of Subgrade Reaction Constant With Depth

Pile	Equation	Remarks
Short Free Head β_{c} L < 1.5	$y_{o} = \frac{4T_{u} (1 + 1.5 \frac{e}{L})}{\frac{E_{sl}L}{}}$	$\beta_{c} = \left[\frac{E_{s1}}{\frac{4E_{p}}{p}}\right]^{1/4}$
Short Fixed β_{c} L < 0.5	$y_{o} = \frac{T_{u}}{E_{sl}L}$	E = pile lateral elastic modulus, ksf I = pile moment of inertia, ft ⁴ E = modulus of subgrade reaction, ksf
Long Free Head β_{c} L > 1.5	$y_{o} = \frac{2T_{u}\beta_{c}}{E_{sl}}$	Terzaghi Recommendations for E _{sl} Clay C _u , ksf E _{sl} , ksf
Long Fixed Head $\beta_{\rm C}$ L > 1.5	$y_{o} = \frac{T_{u}\beta_{c}}{E_{sl}}$	Stiff 1 - 2 3 - 6 Very Stiff 2 - 4 6 - 13 Hard > 4 > 13

b. Soil With Modulus of Subgrade Reaction Increasing Linearly With Depth

Equation	Definitions		
$Y_{o} = F_{y} \frac{T_{u} \beta_{l}^{3}}{F_{p} T_{p}}$	$\beta_{\ell} = \left[\frac{\mathbf{E} \mathbf{I}}{\frac{\mathbf{p} \cdot \mathbf{p}}{\mathbf{k}}}\right]^{1/5}$		
	k = constant rela E = kz, kipa s	ating elastic soi s/ft ³	l modulus with dep
	Representat	ive Values for	k
	C _u , kips/ft ²	k, Statio	kips/ft ³ c Cyclic
	0.25 - 0.5	50	20
	0.50 - 1.0	170	70
	1.0 - 2.0	500	200
	2.0 - 4.0	1700	700
	4.0 - 8.0	5000	2000
	Values	s for F Y	
	$\frac{L}{\beta_{\varrho}}$	F Y	
	2	1.13	
	3	1.03	
	4	0.96	
	5	0.93	

TABLE 5-7

<u>Example E_pI_p Computation of Drilled Shafts</u> (After American Concrete Institute Committee 318, 1980)



(2) Ultimate Lateral Load. Broms equations in Table 5-5a for a free head pile in cohesive soil may be used to roughly estimate T_u . The ultimate bending moment resistance M_v using data in Table 5-7 is

$$\begin{split} M_{y} &= 1.3f_{y}Z = 1.3\left[f_{ys}^{'}Z_{st} + 0.03f_{c}^{'}Z_{c}\right] \\ &= 1.3\left[f_{ys}^{'}\sum\frac{I_{st}}{c_{st}} + 0.03f_{c}^{'}\frac{2I_{g}}{B_{s}}\right] \\ &= 1.3\left[60\cdot2\cdot0.79\left(11.33 + 9.96 + 7.39 + 3.93\right) + 0.03\cdot3\frac{2\cdot39760}{30}\right] \\ &= 1.3\left[94.8\cdot32.61 + 238.56\right] = 4329 \ kip-in \end{split}$$

or 360.7 kip-ft. From Table 5-6a

$$L_{c} = 1.5B_{s} + \frac{9}{C_{u}B_{s}} + \left[\frac{M_{y}}{2.25C_{u}B_{s}}\right]^{1/2}$$

= 1.5.2.5 + $\frac{9}{1.2.5} + \left[\frac{360.7}{2.25\cdot1.2.5}\right]^{1/2}$
= 3.75 + 3.6 + 8.0 = 15.4 ft

This shaft with L = 20 ft is considered long. From Equation 5-27c, the ultimate lateral load $\rm T_u$ is

$$\begin{split} T_u &= 9 C_{uB_s} \! \left[\left(1.5B_s \right)^2 + \frac{2M_y}{9C_uB_s} \right]^{1/2} - 1.5B_s \right) \\ &= 9 \cdot 1 \cdot 2.5 \! \left[\left(1.5 \cdot 2.5 \right)^{1/2} + \frac{2 \cdot 360 \cdot 7}{9 \cdot 1 \cdot 2.5} \right]^{1/2} - 1.5 \cdot 2.5 \right) \\ &= 22.5 (\left[14.06 + 32.06 \right]^{1/2} - 3.75 \right) = 68.4 \ kips \end{split}$$

(3) Allowable Lateral Load. From Table 5-6b, the ultimate lateral deflection y_{\circ} is

$$y_o = F_y \frac{T_u B_\ell^3}{E_p I_p} \\ = 0.95 \frac{68.4 \cdot 4.4^3}{2.7 \cdot 10^5} \\ = 0.022 \ ft$$

or 0.26 inch. On the basis of Equation 5-27 the design displacement will be $(10/68.4) \cdot 0.26$ or 0.04 inch, which is less than the specified allowable deflection $y_a = 0.25$ inch. The trial dimensions are expected to be fully adequate to support the design lateral load of 10 kips. Additional analysis using COM624G should be performed to complete a more economical and reliable design.

5-5. <u>Capacity of Shaft Groups.</u> Drilled shafts are often not placed in closely spaced groups because these foundations can be constructed with large diameters and can extend to deep depths. The vertical and lateral load capacities of shaft foundations are often the sum of the individual drilled shafts. The FS for groups should be 3.

a. Axial Capacity. The axial capacity of drilled shafts spaced $\geq 8B_s$ will be the sum of the capacities of individual shafts. If drilled shafts are constructed in closely spaced groups where spacing between shafts is $< 8B_s$, then the capacity of the group may be less than the sum of the capacities of the individual shafts. This is because excavation of a hole for a shaft reduces effective stresses against both the sides and bases of shafts already in place. Deep foundations where spacings between individual piles are less than 8 times the shaft width B also cause interaction effects between adjacent shafts from overlapping of stress zones in the soil, Figure 5-13. In situ soil stresses from shaft loads are applied over a much larger area leading to greater settlement and bearing failure at lower total loads.



Figure 5-13. Stress zones in soil supporting group

(1) **Cohesive Soil.** Group capacity may be estimated by efficiency and equivalent methods. The efficiency method is recommended when the group cap is isolated from the soil surface, while the equivalent method is recommended when the cap is resting on the soil surface. The equivalent method is useful for spacings \leq 3B_s where B_s is the shaft or pile diameter, Figure 5-14.

(a) Group ultimate capacity by the efficiency method is

$$Q_{ug} = n \cdot E_g \cdot Q_u$$

(5-28a)

where

 Q_{ug} = group capacity, kips n = number of shafts in the group E_g = efficiency Q_u = ultimate capacity of the single shaft, kips



Figure 5-14. Schematic of group

 E_g should be > 0.7 for spacings > $3B_s$ and 1.0 for spacings > $8B_s$. E_g should vary linearly for spacings between $3B_s$ and $8B_s$. E_g = 0.7 for spacings $\leq 2.5B_s$.

(b) Group capacity by the equivalent method is

$$Q_{ug} = 2L(B + W)C_{ua} + 9 \cdot C_{ub} \cdot B \cdot W$$
(5-28b)

where

- L = depth of penetration, ft
- W = horizontal length of group, ft
- B = horizontal width of group, ft
- $\ensuremath{C_{ua}}$ = average undrained shear strength of the cohesive soil in which the group is placed, ksf
- C_{ub} = average undrained shear strength of the cohesive soil below the tip to a depth of 2B below the tip, ksf

The presence of locally soft soil should be checked because this soil may cause some shafts to fail.

(c) The ultimate bearing capacity of a group in a strong clay soil overlying weak clay may be estimated by assuming block punching through the weak underlying soil layer. Group capacity may be calculated by Equation 5-28b using the undrained strength C_{ub} of the underlying weak clay. A less conservative solution is provided by (Reese and O'Neill 1988)

$$Q_{ug} = Q_{ug,lower} + \frac{H_b}{10B} \left[Q_{ug,upper} - Q_{ug,lower} \right] \le Q_{ug,upper}$$
(5-29)

where

(2) **Cohesionless Soil.** During construction of drilled shafts in cohesionless soil, stress relief may be more severe than in cohesive soils because cohesionless soils do not support negative pore pressures as well as cohesive soils. Negative pore pressures generated during excavation in cohesive soils tend to keep effective stresses higher than in cohesionless soil.

(a) The efficiency Equation 5-28a is usually recommended.

(b) Equation 5-29 can be used to estimate ultimate bearing capacity of a group in a strong cohesionless soil overlying a weak cohesive layer.

b. Lateral Load Capacity. Response of groups to lateral load requires lateral and axial load soil-structure interaction analysis with assistance of a finite element computer program.

(1) Widely Spaced Drilled Shafts. Shafts spaced > $7B_s$ or far enough apart that stress transfer is minimal and loading is by shear, the ultimate lateral load of the group T_{ug} is the sum of individual shafts. The capacity of each shaft may be estimated by methodology in 5-4.

(2) **Closely Spaced Drilled Shafts.** The solution of ultimate lateral load capacity of closely spaced shafts in a group requires analysis of a nonlinear soil-shaft system

$$T_{ug} = \sum_{j=1}^{n} T_{uj}$$
 (5-30)

where

 T_{uj} = ultimate lateral load capacity of shaft j, kips n = number of shafts in the group

Refer to Poulos (1971a, Poulos (1971b), and Reese (1986) for detailed solution of the lateral load capacity of each shaft by the Poulos-Focht-Koch method.

(3) **Group Behavior as a Single Drilled Shaft.** A pile group may be simulated as a single shaft with diameter C_g/π where C_g is the circumference given as the minimum length of a line that can enclose the group. The moment of inertia of the group is $n \cdot I_p$ where I_p is the moment of inertia of a single shaft. Program COM624G may be used to evaluate lateral load-deflection behavior of the simulated single shaft for given soil conditions. Comparison of results between the Poulos-Focht-Koch and simulated single pile methods was found to be good (Reese 1986).

Section II. Driven Piles

5-6. <u>Effects of Pile Driving.</u> Driving piles disturbs and substantially remolds soil. Driving radially compresses cohesive soils and increases the relative density of cohesionless soils near the pile.

a. **Cohesive Soil.** Soil disturbance around piles driven into soft or normally consolidated clays is within one pile diameter. Driving into saturated stiff clays closes fissures and causes complete loss of stress history near the pile (Vesic 1969).

(1) **Driving in Saturated Clay.** Soil disturbance and radial compression increase pore water pressures that temporarily reduce the soil shear strength and pile load capacity. Pore pressures decrease with time after driving and lead to an increase in shear strength and pile load capacity. This effect is soil freeze.

(2) **Driving in Unsaturated Clay.** Driving in unsaturated clay does not generate high pore pressures and probably will not lead to soil freeze.

b. **Cohesionless Soil.** The load capacity of cohesionless soil depends strongly on relative density. Driving increases relative density and lateral displacement within a zone around the pile of one to two pile diameters. Large displacement piles such as closed end pipe piles cause larger increases in relative density than small displacement piles such as H-piles. The increase in bearing capacity can therefore be greater with large displacement piles.

(1) **Driving in Dense Sand and Gravel.** Driving in dense sand and gravel can decrease pore pressures from soil dilation and temporarily increase soil shear strength and pile load capacity. Shear strength can increase substantially and may exceed the capacity of pile driving equipment to further drive the piles into the soil. Pore pressures increase after driving and cause the shear strength to decrease and reduce the pile load capacity. This effect is soil relaxation.

(2) Driving in Saturated Cohesionless Silts. Driving in saturated cohesionless silts increases pore pressures and can temporarily reduce the soil shear strength and pile load capacity. Pore pressures dissipate after driving and lead to an increase in shear strength and pile load capacity. This effect is soil freeze as described in cohesive soil, but can occur more quickly than in cohesive soil because permeability is greater in silts.

5-7. <u>Vertical Capacity of Single Driven Piles.</u> The vertical capacity of driven piles may be estimated using Equations 5-1 similar to drilled shafts

$$Q_u \approx Q_{bu} + Q_{su} - W_p \tag{5-1a}$$

$$Q_u \approx q_{bu} A_b + \sum_{i=1}^n Q_{sui} - W_p$$
 (5-1b)

where

In addition, a wave equation analysis should be performed to estimate the driving forces to prevent pile damage during driving, to estimate the total driving resistance that will be encountered by the pile to assist in determining the

required capability of the driving equipment and to establish pile driving criteria. Refer to program GRLWEAP (Goble Rausche Likins and Associates, Inc. 1988) for details of wave equation analysis. Pile driving formulas are also recommended to quickly estimate the ultimate bearing capacity.

a. End Bearing Capacity. End bearing capacity may be estimated by

$$q_{bu} = c \cdot N_{cp} \cdot \zeta_{cp} + \sigma'_L \cdot N_{qp} \zeta_{qp} + \frac{B_b}{2} \cdot \gamma'_b \cdot N_{qp} \cdot \zeta_{qp}$$
(5-2a)

where

Equation 5-2a may be simplified for driven piles by eliminating the $N_{\nu_{D}}$ term

$$q_{bu} = C \cdot N_{cp} \cdot \zeta_{cp} + \sigma_L' \cdot (N_{qp} - 1) \cdot \zeta_{qp}$$

$$(5-2b)$$

or

$$q_{bu} = c N_{cp} \zeta_{cp} + \sigma_L N_{qp} \zeta_{qp}$$
(5-2c)

Equations 5-2b and 5-2c also adjust for pile weight W_p assuming $\gamma_p \approx \gamma'_L$. Equation 5-2c is usually used because omitting the "1" is usually negligible. Bearing capacity does not increase without limit with increasing depth. Refer to Figure 5-3 to determine the critical depth Lc below which effective stress remains constant using the Meyerhof and Nordlund methods.

(1) Cohesive Soil. The shear strength of cohesive soil is c = $C_u,$ the undrained strength, and the effective friction angle $\phi\prime$ = 0. Equation 5-2a leads to

$$q_{bu} = N_{cp} \cdot C_u = 9 \cdot C_u \tag{5-2d}$$

where shape factor $\zeta_{cp} = 1$ and $N_{cp} = 9$. Undrained shear strength C_u is estimated by methods in Chapter 3 and may be taken as the average shear strength within $2B_b$ beneath the tip of the pile.

(2) **Cohesionless Soil.** Meyerhof, Nordlund, and in situ methods described below and Hanson, Vesic, and general shear methods described in Section I are recommended for solution of ultimate end bearing capacity using Equations 5-2. Several of these methods should be used for each design problem to provide a reasonable range of probable bearing capacity if calculations indicate a significant difference between methods.

(a) Meyerhof Method. Figure 5-15 illustrates the bearing capacity factors to be used with Equation 5-2b (Meyerhof 1976). The range between "low" and "high" factors in Figure 5-15 should account for soil conditions such as loose or dense sands, overconsolidation ratio of clays, and soils with different degrees of compressibility. The correction factors $\zeta_{\rm cp}$ and $\zeta_{\rm qp}$ in Equation 5-2b are unity. $N_{\rm cp}$ and $N_{\rm qp}$ are estimated as follows:

Evaluate the critical depth ratio Rc = Lc/B from the given friction angle ϕ' using Figure 5-3. Then calculate the critical depth $Lc = Rc \cdot B$ where B = pile diameter or width.

- 1. If $\phi^{\,\prime}$ < 30° and L > Lc/2, then use $N_{_{\rm cp,high}}$ and $N_{_{\rm gp,high}}$ directly from curves of Figure 5-15
- 2. If $\phi' < 30^{\circ}$ and L < Lc/2, then from Figure 5-15

$$N_{cp} = N_{cp,low} + (N_{cp,high} - N_{cp,low}) \frac{2L}{LC}$$
(5-31a)

$$N_{qp} = N_{qp,low} + (N_{qp,high} - N_{qp,low}) \frac{2L}{LC}$$
(5-31b)

If $\phi' \ge 30^{\circ}$, evaluate the bearing depth ratio Rb = L/B, locate the intersection of Rb and ϕ' in Figure 5-15, then estimate by interpolation N_{cb} and N_{mp} , respectively.

3. If Rb > Rc, check to be sure that $q_{bu} \leq q_{\ell}$ = the limiting stress. The limiting stress is given by

$$q_{l} = N_{op}$$
 tan ϕ'

where q_{ℓ} is in units of ksf.

Refer to Vanikar (1986) for further applications using the Meyerhof method.

(b) Nordlund Method. This semi-empirical method considers the shape of the pile taper and the influence of soil displacement on skin friction. Equations for calculating ultimate capacity are based on load test results that include timber, steel H, pipe, monotube, and Raymond steptaper piles. Ultimate capacity is determined by, Figure 5-16



Figure 5-15. Bearing capacity factors for Meyerhof method (Data from Meyerhof 1976)



Figure 5-16. Illustration of input parameters for Nordlund's equation.

$$Q_u = \alpha_f N_{qp} A_b \sigma_L^* + \sum_{z=0}^{Z=L} K C_f \sigma_z^* \frac{\sin(\delta + \omega)}{\cos \omega} C_z \Delta L$$
(5-32a)

where

 $\alpha_{\rm f}$ = dimensionless pile depth-width relationship factor A_{b} = pile point area, ft² $\sigma_{\!\scriptscriptstyle \mathrm{L}}$ = effective overburden pressure at pile point, ksf K = coefficient of lateral earth pressure at depth z $C_{\rm f}$ = correction factor for K when $\delta \neq \phi'$ ϕ' = effective soil friction angle, degrees δ = friction angle between pile and soil = angle of pile taper from vertical ω σ'_{i} = effective overburden pressure at the center of depth increment ΔL , 0 < z \leq L, ksf C_z = pile perimeter at depth z, ft ΔL = pile increment, ft = length of pile, ft L

 ϕ' may be estimated from Table 3-1. Point resistance $q_{bu} = \alpha_f N_{qp} \sigma'_L A_p$ should not exceed $q_\ell A_p$ where q_ℓ is given by Equation 5-31c. α_f and N_{qp} may be found from Figure 5-17, K from Figure 5-18, δ from Figure 5-19 for a given ϕ' and C_f may be found from Figure 5-20. Equation 5-32a for a pile of uniform cross-section (ω = 0) and length L driven in a homogeneous soil with a single friction angle ϕ and single effective unit weight is

$$Q_u = \alpha_f N_{qp} A \sigma'_L + K C_f \sigma'_m \sin \delta C_s L$$
(5-32b)

where A is the pile cross-section area, C_s is the pile perimeter and σ'_m is the mean effective vertical stress between the ground surface and pile tip, ksf. Table 5-8 provides a procedure for using the Nordlund method (Data from Vanikar 1986).







b. N_{qp}

Figure 5-17. Coefficient $\alpha_{\rm f}$ and bearing capacity factor $\rm N_{qp}$ for the Nordlund method (Data from Vanikar 1986)



 $c, \phi' = 35^{\circ}$

d. $\phi' = 40^{\circ}$

Figure 5-18. Coefficient K for various friction angles $\phi^{\,\prime}$ and pile taper $\,\omega\,$ for Nordlund method (Data from Vanikar 1986)



- 1. Pipe and nontapered portions portions of monotube piles
- 2. Timber piles
- 3. Precast concrete piles
- 4. Raymond step-taper piles
- 5. Tapered portion of monotube piles
- 6. Raymond uniform taper piles
- 7. H and augercast piles

Figure 5-19. Ratio $\,\delta/\varphi\,$ for given displacement volume V (Data from Vanikar 1986)



Figure 5-20. Correction factor C_{f} when $\delta \neq \phi$ (Data from Vanikar 1986)

TABLE 5-8

Procedure for the Nordlund Method

	Flocedule for the Nordfund Method
Step	Procedure
	a. End Bearing Capacity
1	Determine friction angle ϕ' from in situ test results using Tables 3-1 and 3-2 for each soil layer. $\phi = \phi'$
2	Determine $lpha_{ m f}$ using ϕ for the soil layer in which the tip is embedded and the pile L/B ratio from Figure 5-17a
3	Determine $N_{_{\rm T\!P}}$ using φ for the soil layer in which the tip is embedded from Figure 5-17b
4	Determine effective overburden pressure at the pile tip, $\sigma_{\scriptscriptstyle\! L}$
5	Determine the pile point area, A_{b}
6	Determine end bearing resistance pressure $q_{bu} = \alpha_f N_{qp} \sigma'_L$. Check $q_{bu} \leq q_{\ell} = N_{qp} tan \phi$ of Equation 5-31c. Calculate end bearing capacity $Q_{bu} = q_{bu} A_b \leq q_{\ell} A_b$. N_{qp} used in Equation 5-31c should be determined by Meyerhof's method using Figure 5-15
	b. Skin Friction Capacity
7	Compute volume of soil displaced per unit length of pile
8	Compute coefficient of lateral earth pressure K for ϕ' and ω using Figure 5–18. Use linear interpolation
9	Determine δ/ϕ for the given pile and volume of displaced soil V from Figure 5–19. Calculate δ for friction angle ϕ
10	Determine correction factor ${\sf C}_{\rm f}$ from Figure 5-20 for ϕ and the δ/ϕ ratio
11	Calculate the average effective overburden pressure σ_{z}^{\prime} of each soil layer
12	Calculate pile perimeter at center of each soil layer $C_{ m z}$
13	Calculate the skin friction capacity of the pile in each soil layer i from
	$Q_{sui} = KC_f \sigma_z' \frac{\sin(\delta + \omega)}{\cos \omega} C_z \Delta L$
	Add ${\tt Q}_{\rm sui}$ of each soil layer to obtain ${\tt Q}_{\rm su},{\tt Q}_{\rm su}$ = \sum ${\tt Q}_{\rm sui}$ of each layer

14 Compute ultimate total capacity, $Q_u = Q_{bu} + Q_{su}$

(3) Field Estimates From In Situ Soil Tests. The ultimate end bearing capacity of soils may be estimated from field tests if laboratory soil or other data are not available.

(a) SPT Meyerhof Method. End bearing capacity may be estimated from penetration resistance data of the SPT by (Meyerhof 1976)

$$q_{bu} = 0.8 N_{SPT} \frac{L_b}{B} < 8 N_{SPT}, \quad \frac{L}{B} \ge 10$$
 (5-33)

where N_{SPT} is the average uncorrected blow count within $8B_b$ above and $3B_b$ below the pile tip. L_b is the depth of penetration of the pile tip into the bearing stratum. q_{bu} is in units of ksf.

(b) CPT Meyerhof method. End bearing capacity may be estimated from cone penetration resistance data by (Meyerhof 1976)

$$q_{bu} = \frac{q_c}{10} \cdot \frac{L_b}{B} < q_\ell \tag{5-34}$$

based on numerous load tests of piles driven to a firm cohesionless stratum not underlain by a weak deposit. q_{ℓ} is the limiting static point resistance given approximately by Equation 5-31c. N_{qp} should be estimated by the Meyerhof method, Table 4-3. q_{bu} and q_{ℓ} are in units of ksf.

(c) CPT B & G method. End bearing capacity may also be estimated from cone penetration resistance data by (Bustamante and Gianeselli 1983)

$$\boldsymbol{q}_{\boldsymbol{b}\boldsymbol{u}} = \boldsymbol{k}_{\boldsymbol{c}} \cdot \boldsymbol{q}_{\boldsymbol{c}} \tag{5-35}$$

where

 k_c = point correlation factor, Table 5-9

 $\mathbf{q}_{\rm c}$ = average cone point resistance within 1.5B $% \mathbf{r}_{\rm c}$ below the pile point, ksf

 B_{b} = base diameter, ft

TABLE 5-9

```
Point Correlation Factor k_{c} (Bustamante and Gianeselli 1983)
```

	k c		
Soil	Driven Pile	Drilled Shaft	
Clay - Silt	0.600	0.375	
Sand - Gravel	0.375	0.150	
Chalk	0.400	0.200	

(d) CPT 1978 FHWA-Schmertmann method (modified). End bearing capacity may be estimated by (Schmertmann 1978)

$$q_{bu} = \frac{q_{c1} + q_{c2}}{2} \tag{5-36}$$

where q_{c1} and q_{c2} are unit cone resistances determined by the procedure described in Figure 5-21. For example, q_{c1} calculated over the minimum path is as follows:

$$q_{c1} = \frac{180+170+170+170+170}{5} = 172 \ ksf$$

 q_{c2} over the minimum path is as follows:

$$q_{c2} = \frac{120+150+160+160+160+160+160+160}{8} = 153.75 \ ksf$$

From Equation 5-36, $q_{bu} = (172 + 153.75)/2 = 162.9 \text{ ksf.}$



$$d_{\rm bu} = \frac{q_{c1} + q_{c2}}{2}$$

- q_{c1} Average q_o over a distance \sim L+0.7B to L+4B below the pi tip. Use the minimum path. minimum path is a vertical lin that spans the minimum measure q_c between L+0.7B and L+4B.
- q_{c2} Average q_c over a distance of L to L-8B above the pile tip. Use the minimum path as above.

Figure 5-21. Estimating pile tip capacity from CPT data (Data from Schmertmann 1978)

(4) **Scale Effects.** Ultimate end bearing capacity q_{bu} tends to be less for larger diameter driven piles and drilled shafts than that indicated by Equations 5-33 or 5-34 or Equation 5-2b using Equations 5-31 to estimate N_{cp} or N_{qp} (Meyerhof 1983). Skin friction is independent of scale effects.

(a) Sands. The reduction in end bearing capacity has been related with a reduction of the effective angle of internal friction ϕ' with larger diameter deep foundations. End bearing capacity q_{bu} from Equation 5-2 should be multiplied by a reduction factor $R_{\rm bs}$ (Meyerhof 1983)

$$R_{bs} = \left[\frac{B+1.64}{2B}\right]^m \le 1 \tag{5-37a}$$

for B > 1.64 ft. The exponent m = 1 for loose sand, 2 for medium dense sand, and 3 for dense sand.

(b) Clays. The reduction factor R_{bc} appears related to soil structure and fissures. For driven piles in stiff fissured clay, R_{bc} is given by Equation 5-37a where m = 1. For bored piles

$$R_{bc} = \left[\frac{B+3.3}{2B+3.3}\right] \le 1$$
 (5-37b)

for B from 0 to 5.75 ft.

b. Skin Resistance Capacity. The maximum skin resistance that may be mobilized along an element of pile length ΔL may be estimated by

$$Q_{sui} = A_{si} f_{si} \tag{5-9}$$

where

(1) Cohesive Soil.

(a) Alpha method. The skin friction of a length of pile element may be estimated by

$$f_{si} = \alpha_a C_u \tag{5-10}$$

where

 $\alpha_{\rm a}$ = adhesion factor $C_{\rm u}$ = undrained shear strength, ksf

Local experience with existing soils and load test results should be used to estimate appropriate α_a . Estimates of α_a may be made from Table 5-10 in the absence of load test data and for preliminary design.

(b) Lambda Method. This semi-empirical method is based on numerous load test data of driven pipe piles embedded in clay assuming that end bearing capacity was evaluated from Equation 5-2a using $N_{cp} = 9$ and $\zeta_{cp} = 1$ (Vijayvergiya and Focht 1972). The N_{qp} and $N_{\gamma p}$ terms are not used. Skin friction is

$$f_{si} = \lambda \cdot (\sigma_m^* + 2C_{um}) \tag{5-38a}$$

where

- λ = correlation factor, Figure 5-22 $\sigma'_{\rm m}$ = mean effective vertical stress between the ground surface and pile tip, ksf
- C_{um} = mean undrained shear strength along the pile length, ksf

TABLE 5-10

Adhesion	Factors	for	Driven	Piles	in	Cohesive	Soil
(Data from Tomlinson 1980)							

Length/Width Ratio L B	Undrained Shear Strength C _u , ksf	Adhesion Factor $lpha_{a}$
< 20	< 3 > 3	1.2 - 0.3C _u 0.25
> 20	0.0 - 1.5 1.5 - 4.0 > 4	1.0 1.5 - 0.4C _u 0.3



Figure 5-22. Lambda correlation factor (Data from Vijayvergiya and Focht 1972)

 λ may also be given approximately by

$$\lambda = L^{-0.42} \quad L \ge 10FT$$
 (5-38b)

where L is the pile length, ft.

(2) **Cohesionless Soil.** The soil-shaft skin friction may be estimated using effective stresses

$$f_{si} = \beta_f \sigma'_i \tag{5-12a}$$

$$\beta_f = K \tan \delta_a \tag{5-12b}$$

where

Cohesion c is taken as zero.

(a) Figure 5-5 indicates appropriate values of $\beta_{\rm f}$ as a function of the effective friction angle $\,\phi'\,$ of the soil prior to installation of the deep foundation.

(b) The effective vertical stress σ_i' approaches a limiting stress at the critical depth Lc, then remains constant below Lc. Lc may be estimated from Figure 5-3.

(c) The Nordlund method in Table 5-8b provides an alternative method of estimating skin resistance.

(3) **CPT Field Estimate.** The skin friction f_{si} may be estimated from the measured cone resistance q_c for the piles described in Table 5-2b using the curves given in Figure 5-6 for clay and silt, sand and gravel, and chalk (Bustamante and Gianeselli 1983).

c. Ultimate Capacity From Wave Equation Analysis. Estimates of total bearing capacity may be performed using computer program GRLWEAP (Goble Rausche Likins and Associates, Inc. 1988). The analysis uses wave propagation theory to calculate the force pulse transmitted along the longitudinal pile axis caused by impact of the ram, Figure 5-23. The force pulse travels at a constant velocity depending on the pile material and this pulse is attenuated by the soil frictional resistance along the embedded length of the pile. The pile penetrates into the soil when the force pulse reaching the pile tip exceeds the ultimate soil resistance at the pile tip Q_{ub} . Program GRLWEAP and user's manual are licensed to the Waterways Experiment Station and it is available to the US Army Corps of Engineers.



Figure 5-23. Schematic of wave equation model

(1) **Description.** The pile driving and soil system consists of a series of elements supported by linear elastic springs and dashpots which have assumed parameters, Figure 5-23. Characteristics of commonly used pile hammers and piles are available in the program data files driving systems. Input parameters include the dynamic damping constants for each dashpot, usually in units of seconds/inch, ultimate soil resistance Q_u in kips and quake in fractions of an inch for each spring. Each dashpot and spring represent a soil element. The quake of the pile is its displacement at Q_{ub} . Input data for Q_{ub} , quake, and ultimate skin resistance of each element Q_{sui} are usually assumed. Actual load distribution data are

normally not available and require results of instrumented load tests. Standard values are available in the user's manual for soil input parameters.

(2) **Analysis.** The wave equation analysis provides a relationship between the pile capacity and the driving resistance in blows per inch (or blows per foot if needed). This relationship can be developed for different pile lengths and then used in the field when the pile has been driven sufficiently to develop the required capacity. The wave equation can also be used to develop relationships between driving stresses in the pile and penetration resistance for different combinations of piles and pile driving equipment.

(3) **Application.** The wave equation analysis is used to select the most suitable driving equipment to ensure that the piles can develop the required capacity and select the minimum pile section required to prevent overstressing the pile during driving.

(4) **Calibration.** Calculations from program GRLWEAP may be calibrated with results of dynamic load tests using pile driving analyzer (PDA) equipment. The force and velocity versus time curves calculated from GRLWEAP are adjusted to agree with the force and velocity versus time curves measured by the PDA during pile driving or during a high strain test. A high strain causes a force at the pile tip sufficient to exceed the ultimate soil resistance Q_{ub} . Drilled shafts may be analyzed with the PDA during a high strain test where heavy loads are dropped by a crane on the head of the shaft.

(5) Factors of Safety. In general, pile capacity calculated by GRLWEAP should be divided by a factor of safety FS = 3 to estimate allowable capacity or FS = 2.5 if calibrated with results of dynamic load tests. If load tests are performed, FS = 2 can be used with GRLWEAP.

(6) **Restriking.** Soils subject to freeze or relaxation could invalidate a wave equation analysis; therefore, installed piles should be tested by restriking while using PDA equipment after a minimum waiting period following installation such as 1 day or more as given in the specifications.

d. **Pile Driving Formulas.** Pile driving formulas, Table 5-11, although not as good as wave equation analysis, can provide useful, simple estimates of ultimate pile capacity Q_u and they can be obtained quickly. The allowable bearing capacity can be estimated from Equations 1-2 using FS in Table 5-11. Two or more of these methods should be used to provide a probable range of Q_u .

e. **Example Application.** A steel circular 1.5-ft diameter closed end pipe pile is to be driven 30 ft through a 2-layer soil of clay and fine uniform sand, Figure 5-7. The water table is 15 ft below ground surface at the clay-sand interface. The pile will be filled with concrete grout with density $\gamma_{\rm conc}$ = 150 lbs/ft³. Design load Q_d = 100 kips.

(1) Soil Parameters.

(a) The mean effective vertical stress in the sand layer adjacent to the embedded pile $\sigma_{\rm s}'$ and at the pile tip $\sigma_{\rm L}'$ is limited to 1.8 ksf for the Meyerhof and Nordlund methods. Otherwise, $\sigma_{\rm L}'$ is 2.4 ksf from Equation 5-13b.

TABLE 5-11

Method	Equation for Ultimate Bearing Capacity Q_u , kips	Factor of Safety		
Gates	$27(E_hE_r)^{1/2}(1 - \log_{10}S)$			
Pacific Coast Uniform Building Code	pz · · · p p	4		
	Initially assume $C_{p2} = 0$ and compute Q_u ; reduce Q_u by 25 percent, compute C_{p2} , then recompute Q_u ; compute a new C_{p2} , compute Q_u until Q_u used = Q_u computed			
Danish	$\frac{12E_{h}E_{r}}{S + C_{d}}, C_{d} = \left[\frac{144E_{h}E_{r}L}{2AE_{p}}\right]^{1/2}, \text{ inches}$	3 - 6		
Engineering News Record	Drop Hammers: $\frac{12W_rh}{S+1.0}$	6		
	Other Hammers: $\frac{24E_r}{S + 0.1}$	6		

Nomenclature:

- A = area of pile cross-section, ft^2
- E_{h} = hammer efficiency
- E_p = pile modulus of elasticity, ksf
- E_r = manufacturer's hammer-energy rating (or W_rh), kips-ft
- h = height of hammer fall, ft
- L = pile length, inches
- S = average penetration in inches per blow for the last 5 to 10 blows
 for drop hammers and 10 to 20 blows for other hammers
- W_r = weight of striking parts of ram, kips
- W_p = weight of pile including pile cap, driving shoe, capblock and anvil for double-acting steam hammers, kips

(b) The average undrained shear strength of the upper clay layer is $C_u = 2$ ksf. The friction angle of the lower sand layer is estimated at $\phi' = 36$ deg. Cone penetration test results shown in Figure 5-21 indicate an average cone tip resistance $q_c = 40$ ksf in the clay and 160 ksf in the sand.

(2) **End Bearing Capacity.** A suitable estimate of end bearing capacity q_{bu} for the pile tip in the sand may be evaluated from the various methods for cohesionless soil as described below.

(a) Meyerhof Method. From Figure 5-3, Rc = 10 and Lc = Rc·B = $10 \cdot 1.5$ or 15 ft for ϕ' = 36 deg. N_{gp} from Figure 5-15 is 170 for R_b = L/B = 15/1.5 = 10. From Equation 5-2c with limiting pressure q_{ℓ} from Equation 5-31c

 $\begin{array}{rcl} q_{\rm bu} = \sigma_{\rm L}^{\,\prime} \cdot {\rm N}_{\rm qp} & \leq & {\rm N}_{\rm qp} \cdot \tan \phi^{\,\prime} & {\rm if} & {\rm L} > {\rm Lc} \\ \sigma_{\rm L}^{\,\prime} \cdot {\rm N}_{\rm qp} & = & 1.8 \cdot 170 & = & 306 \ {\rm ksf} \\ {\rm N}_{\rm qp} \cdot \tan \phi^{\,\prime} = & 170 \cdot {\rm tan} & 36 = & 123.5 \ {\rm ksf} \\ q_{\rm bu} & \leq & q_{\ell} \,, \ {\rm therefore} & q_{\rm bu} & = & 123.5 \ {\rm ksf} \end{array}$

(b) Nordlund Method. The procedure in Table 5-8a may be used to estimate end bearing capacity.

Therefore, q_{bu} = 96.5 ksf \leq q_{ℓ}

(c) Hansen Method. From Table 4-5 (or calculated from Table 4-4) $N_{\rm qp}$ = 37.75 and $N_{\rm yp}$ = 40.05 for ϕ' = 36 deg. From Table 4-5,

 $\begin{array}{rcl} \zeta_{\rm qs} &=& 1 \, + \, \tan \varphi &=& 1 \, + \, \tan 36 \, = \, 1.727 \\ \zeta_{\rm qd} &=& 1 \, + \, 2 \tan \varphi (1 \, - \, \sin \varphi)^{2 \cdot} \tan^{-1} (\, {\rm L_{sand}} / {\rm B}) \\ &=& 1 \, + \, 2 \tan 36 (1 \, - \, \sin 36)^{2 \cdot} \tan^{-1} (\, 15/1.5) \cdot \pi / 180 \\ &=& 1 \, + \, 2 \cdot \, 0.727 (1 \, - \, 0.588)^{2 \cdot} 1.471 \, = \, 1.363 \\ \zeta_{\rm qp} &=& \zeta_{\rm qs} \cdot \zeta_{\rm qd} \, = \, 1.727 \cdot 1.363 &=& 2.354 \\ \zeta_{\gamma s} &=& 1 \, - \, 0.4 \, = \, 0.6 \\ \zeta_{\gamma d} &=& 1.00 \\ \zeta_{\gamma p} &=& \zeta_{\gamma s} \cdot \zeta_{\gamma d} \, = \, 0.6 \cdot 1.00 \, = \, 0.6 \end{array}$

From Equation 5-2a

$$\begin{aligned} q_{bu} &= \sigma'_{L} \cdot N_{L} \cdot \zeta_{qp} &+ (B_{b}/2) \cdot \gamma'_{s} \cdot N_{\gamma p} \cdot \zeta_{\gamma p} \\ &= 2.4 \cdot 37.75 \cdot 2.354 + (1.5/2) \cdot 0.04 \cdot 40.05 \cdot 0.6 \\ &= 213.3 &+ 0.7 &= 214 \text{ ksf} \end{aligned}$$

The $N_{\gamma_{\rm P}}$ term is negligible and could have been omitted.

(d) Vesic Method. The reduced rigidity index from Equation 5-5c is

$$I_{rr} = \frac{I_r}{1 + \epsilon_v I_r} = \frac{57.3}{1 + 0.006 \cdot 57.3} = 42.6$$

where

$$(\text{Equation 5-5e}): \quad \epsilon_{v} = \frac{1 - 2 \cdot \mu_{s}}{2(1 - \mu_{s})} \cdot \frac{\sigma'_{L}}{G_{s}} = \frac{1 - 2 \cdot 0.3}{2(1 - 0.3)} \cdot \frac{2.4}{100} = 0.006$$

$$(\text{Equation 5-5d}): \quad I_{r} = \frac{G_{s}}{\sigma'_{L} \cdot \tan \phi'} = \frac{100}{2.4 \cdot \tan 36} = 57.3$$

From Equation 5-5b

$$N_{qp} = \frac{3}{3-\sin\phi}; e^{\frac{(90-\phi')\pi}{180}\tan\phi'} \cdot \tan^{2}\left[45+\frac{\phi'}{2}\right] \cdot I_{rr}^{\frac{4\sin\phi'}{3(1+\sin\phi')}}$$

$$N_{qp} = \frac{3}{3-\sin36}; e^{\frac{(90-36)\pi}{180}\tan36} \cdot \tan^{2}\left[45+\frac{36}{2}\right] \cdot I_{rr}^{\frac{4\sin36}{3(1+\sin36)}}$$

$$N_{qp} = \frac{3}{3-0.588}; e^{0.685} \cdot 3.852 \cdot 42.6 \cdot 42$$

The shape factor from Equation 5-6a is

$$\zeta_{qp} = \frac{1 + 2K_o}{3} = \frac{1 + 2 \cdot 0.42}{3} = 0.61$$

where $K_{_{\rm O}}$ was evaluated using Equation 5-6c. From Equation 5-2c, $q_{_{\rm bu}} \mbox{ = } \sigma_{_{\rm L}} \cdot N_{_{\rm qp}} \cdot \zeta_{_{\rm qp}} \mbox{ = } 2.4 \cdot 60.7 \cdot 0.61 \mbox{ = } 88.9 \mbox{ ksf}$

(e) General Shear Method. From Equation 5-8

$$N_{qp} = \frac{\frac{270 - \phi'}{180} \cdot \pi \tan \phi'}{2\cos^2 \left[45 + \frac{\phi'}{2} \right]} = \frac{\frac{270 - 36}{180} \cdot \pi \tan 36}{2\cos^2 \left[45 + \frac{\phi'}{2} \right]} = \frac{\frac{e^{1.3\pi \cdot 0.727}}{2 \cdot 0.206}}{2 \cdot 0.206}$$
$$N_{qp} = \frac{19.475}{0.412} = 47.24$$

The shape factor ζ_{qp} = 1.00 when using Equation 5-8. From Equation 52c, $q_{bu} = \sigma'_L N_{qp} \zeta_{qp} = 2.4 \cdot 47.24 \cdot 1.00 = 113.4 \text{ ksf}$

(f) CPT Meyerhof Method. From Equation 5-34

$$q_{bu} = \frac{q_c}{10} \cdot \frac{L_{sand}}{B} < q_{\ell}$$

where $q_{\ell} = N_{qp} \cdot tan \phi' ksf$. Substituting the parameters into Equation 5-34

$$q_{bu} = \frac{160}{10} \cdot \frac{15}{1.5} = 160 \text{ ksf}$$

The limiting q_{ℓ} is 123.5 ksf, therefore $q_{\rm bu}$ = 123.5 ksf

(g) CPT B & G. From Equation 5-35

$$q_{bu} = k_c \cdot q_c$$

where $k_c = 0.375$ from Table 5-9. $q_{bu} = 0.375 \cdot 160 = 60$ ksf.

(h) CPT FHWA & Schmertmann. The data in Figure 5-21 can be used with this method to give $q_{bu} = 162.9$ ksf as in the example illustrating this method in paragraph 5-7a.

(i) Comparison of Methods. A comparison of methods is shown as follows:

Method	q _{bu} , ksf	
Meyerhof	124	
Nordlund	97	
Hansen	214	
Vesic	89	
General Shear	113	
CPT Meyerhof	124	
CPT B & G	60	
CPT FHWA & Schmertmann	163	

These calculations indicate q_{bu} from 60 to 214 ksf. Discarding the highest (Hansen) and lowest (CPT B & G) values gives an average q_{bu} = 118 ksf. Scale effects of Equations 5-37 are not significant because B < 1.64 ft.

(2) Skin Friction Capacity. A suitable estimate of skin friction f_s from the soil-shaft interface may be evaluated for both the clay and sand as illustrated below.

(a) Cohesive Soil. The average skin friction using the Alpha method from Equation 5-10 is

 $f_s = \alpha_a \cdot C_u = 0.6 \cdot 2 = 1.2 \text{ ksf}$

where $\alpha_a = 1.2 - 0.3C_u = 0.6$ from Table 5-11 and L/B < 20. The average skin friction using the Lambda method from Equation 5-38a and using L = 15 ft for the penetration of the pile only in the clay is

$$f_s = \lambda(\sigma'_m + 2C_{um}) = 0.32(0.9 + 2.2) = 1.57 \text{ ksf}$$

where

$$\lambda$$
 = L^{-0.42} = 15^{-0.42} = 0.32 from Equation 5-38b

$$\sigma_{\rm m}' = \frac{D_c}{2} \gamma_{\rm clay}' = \frac{15}{2} 0.12 = 0.9 \text{ ksf}$$

A reasonable average value of skin friction is 1.4 ksf for the clay.

(b) Cohesionless Soil. The average skin friction from Equation 5-12a using $\sigma_{\rm s}'$ limited to 1.8 ksf is

 $f_s = \beta_f \sigma'_s = 0.96 \cdot 1.8 = 1.7 \text{ ksf}$

where $\beta_{\rm f}$ is found from Figure 5-5 using ϕ' = 36 deg. The Nordlund method of Table 5-8b provides an alternative estimate

Skin friction for the sand is about 1.6 ksf.

(c) CPT Field Estimate. The driven pile is described as "steel" from Table 5-2b. Curve 1 of Clay and Silt, Figure 5-6a, and curve 1 of Sand and Gravel, Figure 5-6b, should be used. From these figures, f_s of the clay is 0.7 ksf and f_s of the sand is 0.7 ksf.

(d) Comparison of Methods. Skin friction varies from 0.7 to 1.4 ksf for the clay and 0.7 to 1.6 ksf for the sand. Skin friction is taken as 1.0 ksf in the clay and 1 ksf in the sand.

(3) **Ultimate Total Capacity.** The total bearing capacity from Equation 5-1a is

$$Q_u = Q_{bu} + Q_{su} - W_p$$

where

$$W_{p} = \frac{\pi B^{2}}{4} \cdot L \cdot \gamma_{conc} = \frac{\pi \cdot 1.5^{2}}{4} \cdot 30 \cdot \frac{150}{1000} = 8 \text{ kips for the pile weight}$$

(a) Q_{bu} may be found from Equation 5-1b

$$Q_{bu} = A_b \cdot q_{bu} = 1.77 \cdot 118 = 209 \text{ kips}$$

where A_{b} = area of the base, $\pi B^{2}/4 = \pi \cdot 1.5^{2}/4 = 1.77$ ft².

(b) Q_{su} may be found from Equation 5-1b and 5-9

$$Q_{su} = \sum_{i=1}^{n} Q_{sui} = C_s \cdot \Delta L \sum_{i=1}^{2} f_{si}$$

where $C_s = \pi B$. Therefore,

(c) Inserting end bearing and skin resistance bearing capacity values into Equation 5-1a,

$$Q_{ii} = 209 + 141 - 8 = 342$$
 kips

The minimum and maximum values of $\,q_{_{bu}}\,$ and $\,f_{_{s}}\,$ calculated above could be used to obtain a range of $\,Q_{_{u}}\,$ if desired.

(4) Allowable Bearing Capacity. The allowable bearing capacity from Equation 1-2b using FS = 3 is

$$Q_a = \frac{Q_u}{FS} = \frac{337}{3} = 112 \text{ kips}$$

5-8. Lateral Load Capacity of Single Piles. Evaluation of lateral load capacity is treated similarly to that for single drilled shafts in 5-4. Lateral load capacity may be determined by load tests, by analytical methods such as Broms' equations or p-y curves and by arbitrary values. Most piles are placed in groups where group capacity controls performance.

a. Load Tests. Lateral load tests are economically justified for large projects and may be performed as described in ASTM D 3966.

b. Analytical Methods.

(1) Program COM624G using p-y curves are recommended for complicated soil conditions.

(2) Broms' equations in Table 5-5 can give useful estimates of ultimate lateral loads for many cases.

c. Arbitrary Values.

(1) Table 5-12 provides allowable lateral loads for piles.

(2) Piles can sustain transient horizontal loads up to 10 percent of the allowable vertical load without considering design features.

5-9. <u>Capacity of Pile Groups.</u> Driven piles are normally placed in groups with spacings less than 8 times the pile diameter or width $8B_s$ and joined at the ground surface by a concrete slab referred to as a pile cap. The capacity of the pile group can be greater than the sum of the capacities of the individual piles because driving compacts the soil and can increase skin friction and end bearing capacity. FS for pile groups should be 3.

a. Axial Capacity. Deep foundations where spacings between individual piles are less than $8B_s$ cause interaction effects between adjacent piles from overlapping of stress zones in the soil, Figure 5-13. In situ soil stresses from pile loads are applied over a much larger area leading to greater settlement and bearing failure at lower total loads.

TABLE 5-12

Recommendations for Allowable Lateral Pile Loads (Data from Vanikar 1986)

Pile	Allowable Deflection, in.	Allowable Lateral Load, kips	Reference	
Timber		10	New York State	
Concrete		15	Department of	
Steel		20	Transportation 1977	
All	0.375	2	New York City Building Code 1968	
All	0.25	1 (soft clays)	Teng	
Timber	0.25	9	Feagin	
Timber	0.50	14	н	
Concrete	0.25	12	"	
Concrete	0.50	17	"	
		Medium Fine Medium		
		<u>sand</u> <u>sand</u> <u>clay</u>	McNulty	
12 inch Timber (free)	0.25	1.5 1.5 1.5		
12 inch Timber (fixed)	0.25	5.0 4.5 4.0		
16 inch Concrete	0.25	7.0 5.5 5.0		

(1) **Optimum Spacing.** Piles in a group should be spaced so that the bearing capacity of the group \geq sum of the individual piles. Pile spacings should not be less than 2.5B_s. The optimum pile spacing is 3 to 3.5B_s (Vesic 1977) or greater than 0.02L + 2.5B_s where L is the pile length in feet (Canadian Geotechnical Society 1985).

(2) **Cohesive Soils.** Group capacity may be estimated by efficiency and equivalent methods similar for drilled shafts as described in paragraph 5-5a.

(3) **Cohesionless Soil.** Group capacity should be taken as the sum of the individual piles.

b. Lateral Load Capacity. Response of pile groups to lateral load requires lateral and axial load soil-structure interaction analysis with assistance of a finite element computer program.

(1) Widely Spaced Piles. Where piles are spaced > $7B_s$ or far enough apart that stress transfer is minimal and loading is by shear, the ultimate lateral load of the group T_{ug} is the sum of individual piles. The capacity of each pile may be estimated by methodology in 5-4.

(2) **Closely Spaced Piles.** The solution of ultimate lateral load capacity of closely spaced pile groups require analysis of a nonlinear soil-pile system. Refer to Poulos (1971a), Poulos (1971b), and Reese (1986) for detailed solution of the lateral load capacity of each pile by the Poulos-Focht-Koch method.

(3) **Group Behavior as a Single Pile.** A pile group may be simulated as a single pile with diameter C_g/π where C_g is the pile circumference given as the minimum length of a line that can enclose the group of piles. The moment of inertia of the pile group is $n \cdot I_p$ where I_p is the moment of inertia of a single pile. Program COM624G may be used to evaluate lateral load-deflection behavior of the simulated single pile for given soil conditions. A comparison of results between the Poulos-Focht-Koch and simulated single pile methods was found to be good (Reese 1986).

c. **Computer Assisted Analysis.** Computer programs are available from the Waterways Experiment Station to assist in analysis and design of pile groups. Refer to EM 1110-2-2906 for further guidance on the analysis of pile groups.

(1) **Program CPGA.** Pile Group Analysis computer program CPGA is a stiffness analysis in three-dimensions assuming linear elastic pile-soil interaction and a rigid pile cap (Hartman et al 1989). Program CPGA uses matrix methods to incorporate position and batter of piles and piles of different sizes and materials. Computer program CPGG displays the geometry and results of program CPGA (Jaeger, Jobst, and Martin 1988).

(2) **Program CPGC.** Pile Group Concrete computer program CPGC develops the interaction diagrams and data required to investigate the structural capacity of prestressed concrete piles (Strom, Abraham, and Jones 1990).

APPENDIX A

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APPENDIX B

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APPENDIX C

COMPUTER PROGRAM AXILTR

C-1. Organization

Program AXILTR, AXIal Load-TRansfeR, consists of a main routine and two subroutines. The main routine feeds in the input data, calculates the effective overburden stress, and determines whether the load is axial down-directed, pullout, or if uplift/downdrag forces develop from swelling or consolidating soil. The main routine also prints out the computations. Subroutine BASEL calculates the displacement at the base for given applied down-directed loads at the base. Subroutine SHAFL evaluates the load transferred to and from the shaft for relative displacements between the shaft and soil. An iteration scheme is used to cause the calculated applied loads at the top (butt) to converge within 10 percent of the input load applied at the top of the shaft.

a. Input Data

Input data are illustrated in Table C-1 with descriptions given in Table C-2.

TABLE C-1

Line	Input Parameters	Format Statement
1	TITLE	20A4
2	NMAT NEL DX GWL LO IQ IJ	215,2F6.2,315
3	I J K SOILP DS DB	315,3F10.3
4	E50 (Omitted unless $K = 2, 5, 9$)	E13.3
5	LLL	15
6	MAT GS EO WO PS CS CC C PHI AK PM (Line 5 repeated for each material M = 1,NMAT)	I3,3F6.2,F7.0, 2F7.2,F7.0,2F6.2 F7.0
7	ALPHA (Omitted unless I = 6) (α input for each material MAT = 1,NMAT)	7F10.5
8	M IE(M) (Line 8 repeated for each element M and number of soil IE(M). Start with 1. The last line is NEL NMAT)	215
9	RFF GG (Omitted unless K = 7, 8, 9)	F6.3,E13.3
10 10a	(Omitted unless K = 3,4,5,6) NCA (<12)	15

Input Data

TABLE	C-1	(Concluded)
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Line	Input Parameters	Format Statement
10b 10c	T(M,1) T(M,11)(Input for each curve M=1,NCA)S(M)(Input on new line for eachM = 2,11; S(1)input in program as 0.00)	11F6.2 F6.3
11 11a 11b	(Omitted unless I = 5) NCC (<12) FS(N) ZEPP(N) NCUR (Input on new line for each N = 1,NCC)	I5 2F10.3,I5
12 12a 12b	<pre>(Omitted unless J = 0) NC (>1) EP(M) ZEP(M) (Input on new line for each M = 1,NC; at least a top and bottom term required)</pre>	I5 E13.3,F6.2
13	R(M) S(M) (Omitted unless K = 6; repeat on new line for each M = 1,IJ)	F10.5,F15.3
14	STRUL SOILP XA	3F15.2
15	NON (Omitted unless XA < 0.0)	15

TABLE C-2

Description of Input Parameters

Line	Parameter	Description
1	TITLE	Name of problem
2	NMAT NEL DX GWL LO	<pre>Total number of materials Total number of elements Thickness of each element, ft (usually 0.5 or 1.0 ft) Depth to groundwater level, ft Amount of output data = 0 Extensive data output used to check the program = 1 Shaft load-displacement behavior and detailed load distribution-displacement response along shaft length for input top load prior to and following soil movement (load transfer, load, shaft compression increment, and shaft movement at given depth</pre>

Line	Parameter	Description		
			t behavior and load ment response along shaft load prior to and following	
			t behavior and load ment response along shaft load on shaft following soil	
	IQ	Total number of shaft incre thickness); top of sh		
	IJ	Number of points for shaft		
3	I	Magnitude of reduction factor α applied to total (undrained) or effective (drained) shear strength for sk: friction resistance		
		= 0 α = 1 (usually used fo = 1 α = sin(π x/L), x = dep = 2 α = 0.6 = 3 α = 0.45 = 4 α = 0.3 = 5 Permits maximum skin f function of depth, ps = 6 α is input for each ma	th, ft; L = shaft length, ft riction f _s input as a f (see line 11)	
	J	Option for elastic shaft mo = 0 shaft modulus input = 1 shaft modulus set to n		
	K	Option for load-transfer fu	nctions (see Figure 5-12)	
		Base	Shaft	
		 Consolidation Vijayvergiya Reese and Wright Consolidation 	Seed and Reese Seed and Reese Seed and Reese Input (see line 10)	
		= 4 Vijayvergiya = 5 Reese and Wright	Input (see line 10) Input (see line 10)	
		= 6 Input (see line 13) = 7 Consolidation = 8 Vijayvergiya	Input (see line 10) Kraft, Ray, and Kagawa Kraft, Ray, and Kagawa	
		= 8 Vijayvergiya = 9 Reese and Wright	Krait, Ray, and Kagawa Kraft, Ray, and Kagawa	

Line	Parameter	Description
	SOILP	Pressure on top layer of soil exerted by surrounding structure, fill, etc., psf
	DS	Diameter shaft, ft
	DB	Diameter base, ft
4	E50	Strain at 1/2 maximum deviator stress, Equation 5-19
5	LLL	Option for type of shear failure at base = 0 Local shear failure, Equation 5-7 or N _c = 7 = 1 General shear failure, Equation 5-8 or N _c = 9
6	MAT GS EO WO PS CS CC	Number of material Specific gravity Initial void ratio Initial water content, percent Swell pressure, psf Swell index Compression index
	C PHI	Cohesion, psf; = undrained strength for total stress analysis; effective cohesion c' or zero for effective stress analysis Angle of shearing resistance ϕ ; = 0 for total stress
	AK	analysis Coefficient of lateral earth pressure
	PM	Maximum past pressure, psf (program sets PM = PS if PM input < PS)
7	ALPHA	Reduction factor α_a for each material MAT, Equation 5-11, Table 5-1, Table 5-10; used when option I = 6, Line 3
8	M IE(M)	Number of element Material number of soil, MAT
9	RFF	Hyperbolic reduction factor R for Kraft, Ray, and Kagawa model, Equation 5-19a; use 1.0 if not known
10	GG	Shear modulus G_s , psf, Equation 5-19b Input data for shaft load-transfer curves (K = 3,4,5,6)
10a 10b	NCA T(M,1) T(M,11)	Total number of shaft load-transfer curves (K = 3,4,5,6) Total number of shaft load-transfer curves to input, < 12 Skin friction ratio of developed shear strength/maximum mobilized shear strength of each shaft load-transfer curve; 11 values required for each load-transfer curve, the first value T(1,1) = 0.0

TABLE C-2 (Concluded)

Line	Parameter	Description
10c	S(M)	Movement in inches for all of the T(M,1)T(M,11) curves; only 10 values required from S(2)S(11); S(1) = 0.0 in code; if S(M) in the code is okay (0.0,0.05,0.1,0.15,0.2, 0.23,0.3,0.45,0.75,1.05,1.5 inches)
11	NCC	Input data for maximum skin friction as a function of depth Total number of maximum skin friction terms to input, <12; program interpolates maximum skin friction between depths
11a	FS(N)	Maximum skin friction f_{π} for point N, psf
11b	ZEPP(N)	Depth for the maximum skin friction for point N, ft
11c	NCUR	Number of the shaft load-transfer curve input M in line 10; applicable to the maximum skin friction for point N (Repeat 11a,11b,11c for each N = 1,NCC)
12	NC	Input data for shaft elastic modulus as function of depth; program interpolates the elastic modulus between depths Total number of terms of elastic modulus and depth, > 1
12a	EP(M)	Elastic modulus of shaft at point M, psf
12a 12b	ZEP(M)	Depth for the elastic modulus of shaft at point M, ft (An elastic modulus and depth term are required at least at the top and bottom of the shaft)
13		Input data for base displacements if $K = 6$ (The number of input terms or $R(M)$ and $S(M)$ equals IJ - 1, line 2)
13a	R(M)	Base displacement, in. (The first displacement is 0.0 inches and already input in the program)
13b	S(M)	Base load for displacement R(M), pounds; the base load for 0.0 displacement is approximated as the overlying soil weight and already input in the program.
14		Structural load, pressure on adjacent soil at the ground surface, and depth of the active zone for heave input for each problem for evaluation of specific load distribution-displacement computations
14a	STRUC	Structural vertical load on top of shaft, pounds
14b	SOILP	Pressure on top layer of soil exerted by surrounding structure, fill, etc., psf
14c	ХА	Depth of the active zone for heave, ft; = 0.01 yields load-displacement behavior for zero soil movement; a saturated soil profile is assumed when computing soil movement; < 0.0 program goes to line 15 below
		Execution stops if 0; program goes to line 1 if > 0

(1) The program is set to consider up to a total of 40 soil types and 100 soil elements. Figure C-1 provides an example layout of soil types and elements used in AXILTR.

(2) The program can accommodate up to 18 points of the load-displacement curve. This capacity may be altered by adjusting the PARAMETER statement in the program.

(3) The input data are placed in a file, "DATLTR.TXT". These data are printed in output file, "LTROUT.TXT" illustrated in Table C-3a.



Figure C-1. Schematic diagram of soil/pile elements

TABLE C-3

<u>Output Data</u>

a. Repeat of Input Data (See Table C-1)

Line	Output Parameters	Fortran Statement
1	TITLE	20A4
2	NMAT=NEL=DX=FTGWL=FTLO=IQ (SHAFT INC)=IJ (NO.LOADS)=	I5,I5,F6.2,F6.2 I5,I5,I5
3	I= J= K= SOILP= PSF DS= FT DB= FT	I5,I5,I5,F10.2 F10.2 F10.2
4	(If K = 2,5,9) E50	E13.3
5 6	LOCAL SHEAR FAILURE AT BASE - LLL = 0 or GENERAL SHEAR FAILURE AT BASE - LLL = 1 MAT GS EO WO(%) PS(PSF) CS CC CO(PSF) PHI K PM(PSF)	I5 I5 I3,3F6.2,F7.0, 27.2,F7.0,2F6.2, F7.0
7	(If I = 6) ALPHA =	2(7F10.5)
8	ELEMENT NO OF SOIL	I5,10X,I5
9	(If K = 7,8,9) REDUCTION FACTOR= SHEAR MODULUS=	F6.3,3X,E13.3
10	<pre>(If K = 3,4,5,6) NO. OF LOAD-TRANSFER CURVES(<12)?=</pre>	15
	For each curve 1 to NCA: CURVE	15
	RATIO SHR DEV,M=1,11 ARE MOVEMENT(IN.) FOR LOAD TRANSFER M= IS INCHES	11F6.3 I5,F6.3
11	(If I = 5) NO OF SKIN FRICTION-DEPTH TERMS(<12)? ARE SKIN FRICTION(PSF) DEPTH(FT) CURVE NO	I5 F10.3,F10.3,I5
12	(If J = 0) E SHAFT(PSF) AND DEPTH(FT):	4(E13.3,2X,F6.2)
13	<pre>(If K = 6) BASE DISPLACEMENT(IN.), BASE LOAD(LBS) > FOR POINTS</pre>	F10.2,I5

b. <u>Output Calculations</u>

Item	Program Prints	Format Statement
1	BEARING CAPACITY= POUNDS	F13.2
2	DOWNWARD DISPLACEMENT	
3	(Omitted unless LO = 0,1) POINT BEARING(LBS)=	F13.2
4	(Omitted unless LO = 0,1) DEPTH LOAD TRANS TOTAL LOAD COM OF INCR TOTAL MOV FT LBS LBS INCHES INCHES	
5	TOP LOADTOP MOVEMENTBASE LOADBASE MOVEMENTLBSINCHESLBSINCHES	4E13.5
б	NEGATIVE UPWARD DISPLACEMENT	
7	TOP LOAD TOP MOVEMENT BASE LOAD BASE MOVEMENT LBS INCHES LBS INCHES	4E13.5
8	STRUC LOAD(LBS) SOILP(PSF) ACTIVE DEPTH(FT) (Line 14 of Table C-2)	F10.0,2F10.2
9	BELL RESTRAINT(LBS)=	F13.2
10	(If STRUL < 0.0 See Line 14, Table C-2) FIRST ESTIMATE OF PULLOUT RESTRAINT(LBS)=	F13.2
11	LOAD-DISPLACEMENT BEHAVIOR	
12	(If LO <2) EFFECTS OF ADJACENT SOIL	
13	<pre>INITIAL BASE FORCE(LBS)= (If LO = 0) BASE FORCE(LBS)=</pre>	F13.2
14	DISPLACEMENT(INCHES) = FORCE = POUNDS	F8.4,F12.2
15	ITERATIONS=	15
16	DEPTH(FT) LOAD(LBS) SHAFT MVMT(IN) SOIL MVMT(IN)	F7.2,2X,E13.5, 2F15.5

TABLE 3 (Continued)

c. Description of Calculations

Item	Program Prints	Description
1	BEARING CAP	End bearing capacity, pounds
2	DOWNWARD DISPL	Load-displacment Behavior for zero soil movement in downward direction for IJ points
3	POINT BEARING	Load at bottom of shaft prior to shaft load-transfer calculation, pounds
4	DEPTH LOAD TRANS TOTAL LOAD COM OF INCR TOTAL MOVMT ITER	Depth, ft Load transferred at given depth along shaft, pounds Total load on shaft at given depth, pounds Incremental shaft compression at given depth, in. Shaft-soil relative movement at given depth, in. Number of iterations to complete calculation
5	TOP LOAD TOP MOVEMENT BASE LOAD BASE MOVEMENT	Load at top of shaft, pounds Displacement at top of shaft, in. Load at bottom of shaft, pounds Displacement at bottom of shaft, in.
6	NEGATIVE UPWARD	Load-displacement Behavior for zero soil movement in upward direction for IJ points
7	Same as item 5	
8	STRUC LOAD(LBS) SOILP(PSF) ACTIVE DEPTH	Load applied on top of shaft, pounds Pressure applied on top of adjacent soil, psf Depth of soil beneath ground surface subject to soil heave, ft
9	BELL RESTRAINT	Restraining resistance of bell, pounds
10	FIRST ESTIMATE	Initial calculation of pullout resistance prior to iterations for structural loads less than zero, pounds
11	LOAD-DISPLACE	Load-shaft movement distribution for given structural load
12	EFFECTS OF ADJ	Effects of soil movement considered in load-displacement behavior
13	INITIAL BASE	Initial calculation of force at bottom of shaft prior to iterations
14	DISPLACEMENT	Displacement at bottom of shaft after 100 iterations, in.

TABLE C-3 (Concluded)

Item	Program Prints	Description	
	FORCE=	Force at bottom of shaft, pounds after 100 iterations, pounds	
15	ITERATIONS	Total number of iterations to converge to solution	
16	DEPTH(FT) LOAD(LBS) SHAFT MVMT(IN) SOIL MVMT(IN)	Depth, ft Load at given depth, pounds Shaft displacement, in. Soil movement,in.	

b. Output Data

Results of the computations by AXILTR are printed in LTROUT.TXT illustrated in Table C-3b. Table C-3c provides a description of calculations illustrated in Table C-3b.

(1) Load-displacement data are placed in file LDCOM.DAT for plotting by graphic software.

(2) Load-depth data for a given applied load on the pile top are placed in file LDEP.DAT for plotting by graphic software.

(3) Displacement-depth data for a given applied load on the pile top are placed in file MDEP.DAT for plotting by graphic software.

C-2. Applications

The pullout, uplift and downdrag capabilities of AXILTR are illustrated by two example problems. The accuracy of these solutions can be increased by using more soil layers, which increases control over soil input parameters such as swell pressure, maximum past pressure, and shear strength.

a. Pullout and Uplift

Table C-4 illustrates input data required to determine performance of a 2 ft diameter drilled shaft 50 ft long constructed in an expansive clay soil of two layers, NMAT = 2. The shaft is underreamed with a 5-ft diameter bell. Soil beneath the shaft is nonexpansive. The shaft is subject to a pullout force of 300 kips. Refer to Figure C-1 for a schematic representation of this problem.

TABLE (2-4
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	TTP CTH3	or baca	Inpac Ioi	- 1112	andive	0011/	1 1 1 0 1	DITEDIR. IMI	
EXPANS	IVE SOIL								
	1.0 40.	2	50 16						
60		.0	2.0	5.0	00				
0									
1 2.68	.8 30.	4800.	.1	.2	2000.	.0	.7	7000.	
2 2.65	.37 13.1	6000.	.1	.2	4000.	.0	2.	10000.	
0.9	0.9								
1 1									
41 2									
50 2									
.900 1	.600E+05								
2									
4.333E	0. 80								
4.333E	08 50.0								
-300000.	.0		50.						
0.	.0		-1.0						
0									

Listing of Data Input for Expansive Soil, File DATLTR.TXT

(1) Bearing Capacity

The alpha skin friction and local shear base capacity models are selected. Option to input the reduction factor α (I = 6) was used. The selected α 's for the two soils is 0.9. A high α was selected because expansive soil increases pressure against the shaft, which may raise the skin friction.

(2) Load-Transfer Models

The Kraft, Ray, and Kagawa skin friction and the Vijayvergiya base load-transfer models (K = 8) were selected. Two points for the elastic modulus of the shaft concrete were input into the program.

(3) **Results**

The results are plotted in Figure C-2 for a pullout force of 300,000 pounds. Results of the computation placed in file "LTROUT.TXT" are shown in Table C-5.

(a) Total and base ultimate bearing capacity is about 1,200 and 550 kips, respectively, Figure C-2a. Base and total capacity is 250 and 600 kips, respectively, if settlement is limited to 0.5 inch, which is representative of a FS of approximately 2.

(b) The distribution of load with depth, Figure C-2b, is a combination of the shapes indicated in Figures 5-9 and 5-10 because both pullout and uplift forces must be resisted.

(c) The shaft will heave approximately 0.7 inch, while the soil heaves more than 11 inches at the ground surface, Figure C-2c.





b. AXIAL LOAD-DEPTH BEHAVIOR, FILE LDEP Figure C-2. Plotted output for pullout and uplift problem



c. DISPLACEMENT-DEPTH BEHAVIOR, FILE MDEP

Figure C-2. Concluded

TABLE C

Listing of Output, File LTROUT.TXT

EXPA	NSIVE SOIL
NMAT=	2 NEL= 50 DX= 1.00 FT GWL= 40.00 FT
LO=	2 IQ (SHAFT INC) = 50 IJ (NO.LOADS) = 16
I= 6	J= 0 K= 8 SOILP= 0.00 PSF
DS=	
DB=	5.00 FT
LUCAL SH	EAR FAILURE AT BASE - LLL= 0
MAT GS	EO WO(%) PS(PSF) CS CC CO(PSF) PHI K PM(PSF)
1 2.68	0.80 30.00 4800. 0.10 0.20 2000. 0.00 0.70 7000.
2 2.65	0.37 13.10 6000. 0.10 0.20 4000. 0.00 2.00 10000.
ALPHA=	0.90000 0.90000
ELEMENT	
1	1
2	1
•	1
•	1
40	1
41	2

42 2 · 2 · 2 50 2

REDUCTION FACTOR= 0.900 SHEAR MODULUS= 0.160E+06

E SHAFT(PSF) AND DEPTH(FT): 0.433E+09 0.00 0.433E+09 50.00

BEARING CAPACITY= 549778.69 POUNDS

DOWNWARD DISPLACEMENT

TOP LOAD	TOP MOVEMENT	BASE LOAD	BASE MOVEMENT
LBS	INCHES	LBS	INCHES
0.24017E+06	0.17714E+00	0.10946E+06	0.99065E-01
0.34507E+06	0.26781E+00	0.13882E+06	0.15855E+00
0.45773E+06	0.37719E+00	0.16817E+06	0.23526E+00
0.58421E+06	0.50996E+00	0.19753E+06	0.33139E+00
0.71040E+06	0.66509E+00	0.22688E+06	0.44915E+00
0.82982E+06	0.84256E+00	0.25624E+06	0.59070E+00
0.92817E+06	0.10432E+01	0.28559E+06	0.75826E+00
0.97601E+06	0.12587E+01	0.31494E+06	0.95401E+00
0.10054E+07	0.14978E+01	0.34430E+06	0.11801E+01
0.10347E+07	0.17694E+01	0.37365E+06	0.14388E+01
0.10641E+07	0.20758E+01	0.40301E+06	0.17323E+01
0.10934E+07	0.24192E+01	0.43236E+06	0.20627E+01
0.11228E+07	0.28017E+01	0.46172E+06	0.24323E+01
0.11521E+07	0.32256E+01	0.49107E+06	0.28432E+01
0.11815E+07	0.36930E+01	0.52042E+06	0.32977E+01
0.12108E+07	0.42061E+01	0.54978E+06	0.37979E+01

NEGATIVE UPWARD DISPLACEMENT

TOP LOAD	TOP MOVEMENT	BASE LOAD	BASE MOVEMENT
LBS	INCHES	LBS	INCHES
-0.18590E+05	-0.37138E-02	0.00000E+00	0.0000E+00
-0.31134E+05	-0.16708E-01	0.00000E+00	-0.10000E-01
-0.43689E+05	-0.29706E-01	0.00000E+00	-0.20000E-01
-0.68793E+05	-0.55704E-01	0.00000E+00	-0.40000E-01
-0.11899E+06	-0.10770E+00	0.00000E+00	-0.80000E-01
-0.21806E+06	-0.21160E+00	0.00000E+00	-0.16000E+00
-0.38024E+06	-0.41089E+00	0.00000E+00	-0.32000E+00
-0.61240E+06	-0.78911E+00	0.00000E+00	-0.64000E+00
-0.69610E+06	-0.14531E+01	0.00000E+00	-0.12800E+01
-0.69610E+06	-0.27331E+01	0.00000E+00	-0.25600E+01
-0.69610E+06	-0.52931E+01	0.0000E+00	-0.51200E+01

-0.69610E+06 -0.10413E+02 0.00000E+00 -0.10240E+02 -0.69610E+06 -0.20653E+02 0.00000E+00 -0.20480E+02 -0.69610E+06 -0.41133E+02 0.00000E+00 -0.40960E+02 -0.69610E+06 -0.82093E+02 0.00000E+00 -0.81920E+02 -0.69610E+06 -0.16401E+03 0.00000E+00 -0.16384E+03 STRUC LOAD(LBS) SOILP(PSF) ACTIVE DEPTH(FT) -300000. 0.00 50.00 449915.44 BELL RESTRAINT(LBS) = FIRST ESTIMATE OF PULLOUT RESTRAINT(LBS) = 541894.31 LOAD-DISPLACEMENT BEHAVIOR INITIAL BASE FORCE(LBS) = -788275.25 DISPLACEMENT(INCHES) = -0.2475 FORCE= -667768.19 POUNDS DISPLACEMENT(INCHES) = -0.4975 FORCE= -532357.44 POUNDS -0.6525 FORCE= -449443.94 POUNDS DISPLACEMENT(INCHES) = ITERATIONS= 262 DEPTH(FT) LOAD(LBS) SHAFT MVMT(IN) SOIL MVMT(IN) -11.94514 0.00 -0.32427E+06 -0.88276 1.00 -0.33520E+06 -0.87985 -10.678432.00 -0.34613E+06 -0.87685 -9.72980 3.00 -0.87375 -8.92906 -0.35706E+06 4.00 -0.36799E+06 -0.87055 -8.22575 -7.59519 5.00 -0.37892E+06 -0.86726 6.00 -0.38985E+06 -0.86387 -7.022747.00 -0.40078E+06 -0.86039 -6.49865 8.00 -0.41171E+06 -0.85681 -6.01600 9.00 -0.42264E+06 -0.85313 -5.56958 10.00 -0.43357E+06 -0.84936 -5.15537 11.00 -0.44450E+06 -0.84549 -4.7701412.00 -0.45543E+06 -0.84152-4.4112413.00 -0.46636E+06 -0.83746 -4.07648 14.00 -0.47729E+06 -0.83330 -3.76401 15.00 -0.48822E+06 -0.82904 -3.47223 16.00 -0.49915E+06 -0.82469 -3.19976 17.00 -0.51008E+06 -0.82024 -2.9453818.00 -0.52101E+06 -0.81570 -2.70805 19.00 -0.53194E+06 -0.81105 -2.4868020.00 -0.54287E+06 -0.80632 -2.28080 21.00 -0.55380E+06 -0.80148 -2.08927

22.00	-0.56473E	+06	-0.	79655		-1.91153	
23.00	-0.57566E	+06	-0.	79153		-1.74696	
24.00	-0.58613E	+06	-0.	78641		-1.59498	
25.00	-0.59556E	+06	-0.	78120		-1.45506	
26.00	-0.60381E	+06	-0.	77591		-1.32673	
27.00	-0.61073E	+06	-0.	77056		-1.20953	
28.00	-0.61621E	+06	-0.	76515		-1.10306	
29.00	-0.62027E	+06	-0.	75970		-1.00692	
30.00	-0.62304E	+06	-0.	75422		-0.92078	
31.00	-0.62444E	+06	-0.	74872		-0.84428	
32.00	-0.62465E	+06	-0.	74321		-0.77713	
33.00	-0.62386E	+06	-0.	73771		-0.71902	
34.00	-0.62223E	+06	-0.	73222		-0.66969	
35.00	-0.61992E	+06	-0.	72674		-0.62887	
36.00	-0.61710E	+06	-0.	72129		-0.59633	
37.00	-0.61390E	+06	-0.	71587		-0.57183	
38.00	-0.61049E	+06	-0.	71047		-0.55516	
39.00	-0.60701E	+06	-0.	70510		-0.54610	
40.00	-0.60360E	+06	-0.	69977		-0.54447	
41.00	-0.59487E	+06	-0.	69448		-0.46514	
42.00	-0.58401E	+06	-0.	68929		-0.39155	
43.00	-0.57119E	+06	-0.	68420		-0.32363	
44.00	-0.55675E	+06	-0.	67922		-0.26128	
45.00	-0.54103E	+06	-0.	67439		-0.20443	
46.00	-0.52416E	+06	-0.	66969		-0.15300	
47.00	-0.50642E	+06	-0.	66515		-0.10692	
48.00	-0.48799E	+06	-0.	66077		-0.06611	
49.00	-0.46897E	+06	-0.	65655		-0.03049	
50.00	-0.44944E	+06	-0.	65250		0.00000	
STRUC L	OAD(LBS)	SOILP(PSF)	ACTIVE	DEPTH	(FT)	
	0.	0.00		-1.	00		

TABLE C-5 (Concluded)

b. Downdrag

Table C-6 illustrates input data required to solve for the performance of the same drilled shaft and soil described in the previous example problem, but the soil is wetter with a much lower swell pressure. Soil shear strength is assumed not to change significantly from the previous example. This shaft is subject to a 150-kip load in addition to the downdrag forces from the settling soil.

(1) Bearing Capacity

The alpha skin friction and local shear bearing capacity models are selected similar to the previous example. Option to input the reduction factor α (I = 6) was used. The selected α 's are 0.55 and 0.3 for the surface and deeper soils, respectively.

TABLE C-6

SETTL	ING SOIL								
2 50	1.0 40.	2	50 16						
6 0	2 0.	. 0	2.0	5.0	00				
0.0	10								
0									
1 2.68	.8 30.	1200.	.05	.1	2000.	.0	.7	4000.	
2 2.65	.37 13.1	6000.	.05	.1	4000.	.0	2.	10000.	
0.55	0.3								
1 1									
41 2									
50 2									
2									
4.333E	08 .0								
4.333E	08 50.0								
150000.	.0		50.						
0.	.0		-1.0						
0									

Listing of Data Input for Settling Soil, File DATLTR.TXT

(2) Load-Transfer Models

The Seed and Reese skin friction and Reese and Wright base load-transfer models were selected (K = 2). Two points for the elastic modulus of the shaft concrete were input into the program.

(3) **Results**

The results are plotted in Figure C-3 for a downward applied load of 150 kips. Results of the computation placed in file LTROUT.TXT are illustrated in Table C-7.

(a) Total and base ultimate bearing capacity, Figure C-3a, is about 550 and 880 kips, respectively. Base and total capacity is about 200 and 500 kips, respectively, if settlement is limited to 0.5 inch. The factor of safety is approximately 1.8 relative to total bearing capacity. The program does not add the vertical plunging failure lines to the curves in Figure C-3a, which leaves the calculated displacement load relationships nearly linear.

(b) The distribution of load with depth, Figure C-3b, is representative of downdrag indicated in Figure 5-11. The load on the shaft base is nearly 300 kips or double the applied load at the ground surface.

(c) The shaft will settle approximately 1 inch, while the soil settles about 2 inches at the ground surface, Figure C-3c. The soil is heaving near the ground surface, which counters the settlement from downdrag. Maximum settlement is about 3.5 inches at 10 ft of depth.



b. AXIAL LOAD-DEPTH BEHAVIOR, FILE LDEP

Figure C-3. Plotted output for downdrag problem



c. DISPLACEMENT-DEPTH BEHAVIOR, FILE MDEP

Figure C-3. Concluded

TABLE C-7

Listing of Output, File LTROUT.TXT

SETTLING SOIL 2 NEL= 50 DX= 1.00 FT GWL= 40.00 FT NMAT= LO= 2 IQ (SHAFT INC) = 50 IJ (NO.LOADS) = 16I = 6 J= 0 K= 2 SOILP= 0.00 PSF 2.00 FT DS= 5.00 FT DB= E50= 0.100E-01 LOCAL SHEAR FAILURE AT BASE - LLL= 0 MAT GS EO WO(%) PS(PSF) CS CC CO(PSF) PHI K PM(PSF) 1 2.68 0.80 30.00 1200. 0.05 0.10 2000. 0.00 0.70 4000. 2 2.65 0.37 13.10 6000. 0.05 0.10 4000. 0.00 2.00 10000. ALPHA= 0.55000 0.30000

TABLE	C-7	(Continued)
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ELEMENT	NO OF SOIL				
1	1				
2	1				
	1				
	1				
40	1				
41	2				
42	2				
	2				
	2				
50	2				
E SHAFT(PS	SF) AND DEPTH(F	'Т):			
0.4331	E+09 0.00	0.433E+09	50.00		

BEARING CAPACITY= 549778.69 POUNDS

DOWNWARD DISPLACEMENT

TOP LOAD	TOP MOVEMENT	BASE LOAD	BASE MOVEMENT
LBS	INCHES	LBS	INCHES
0.43825E+06	0.36209E+00	0.10946E+06	0.24071E+00
0.47316E+06	0.46787E+00	0.13882E+06	0.33163E+00
0.50252E+06	0.57771E+00	0.16817E+06	0.42854E+00
0.53187E+06	0.69319E+00	0.19753E+06	0.53108E+00
0.56122E+06	0.81401E+00	0.22688E+06	0.63896E+00
0.59058E+06	0.93992E+00	0.25624E+06	0.75193E+00
0.61993E+06	0.10707E+01	0.28559E+06	0.86977E+00
0.64929E+06	0.12061E+01	0.31494E+06	0.99228E+00
0.67864E+06	0.13461E+01	0.34430E+06	0.11193E+01
0.70800E+06	0.14904E+01	0.37365E+06	0.12507E+01
0.73735E+06	0.16389E+01	0.40301E+06	0.13862E+01
0.76671E+06	0.17915E+01	0.43236E+06	0.15259E+01
0.79606E+06	0.19481E+01	0.46172E+06	0.16695E+01
0.82541E+06	0.21085E+01	0.49107E+06	0.18170E+01
0.85477E+06	0.22727E+01	0.52042E+06	0.19682E+01
0.88412E+06	0.24405E+01	0.54978E+06	0.21231E+01

NEGATIVE UPWARD DISPLACEMENT

TOP LOAD	TOP MOVEMENT	BASE LOAD	BASE MOVEMENT
LBS	INCHES	LBS	INCHES
-0.19877E+05	-0.38437E-02	0.00000E+00	0.0000E+00
-0.44463E+05	-0.18937E-01	0.00000E+00	-0.10000E-01
-0.69052E+05	-0.34038E-01	0.00000E+00	-0.20000E-01
-0.11821E+06	-0.64239E-01	0.00000E+00	-0.40000E-01
-0.21272E+06	-0.12447E+00	0.0000E+00	-0.80000E-01

```
-0.31375E+06-0.22746E+000.00000E+00-0.16000E+00-0.36937E+06-0.40225E+000.00000E+00-0.32000E+00-0.36937E+06-0.72225E+000.00000E+00-0.64000E+00-0.36937E+06-0.13623E+010.00000E+00-0.12800E+01-0.36937E+06-0.26423E+010.00000E+00-0.51200E+01-0.36937E+06-0.52023E+010.00000E+00-0.51200E+01-0.36937E+06-0.10322E+020.00000E+00-0.10240E+02-0.36937E+06-0.20562E+020.00000E+00-0.40960E+02-0.36937E+06-0.41042E+020.00000E+00-0.40960E+02-0.36937E+06-0.16392E+030.00000E+00-0.81920E+02-0.36937E+06-0.16392E+030.00000E+00-0.16384E+03STRUCLOAD(LBS)SOILP(PSF)ACTIVEDEPTH(FT)
```

0.00 50.00

BELL RESTRAINT(LBS) = 449915.44

LOAD-DISPLACEMENT BEHAVIOR

POINT BEARING(LBS) = 37465.96

150000.

DEPTH	LOAD TRANS	TOTAL LOAD	COM OF INCR	TOTAL MVMT	ITER
FT	LBS	LBS	INCHES	INCHES	
0.49500E+02	0.35018E+04	0.40968E+05	0.34571E-03	0.82732E-01	2
0.48500E+02	0.35181E+04	0.44486E+05	0.37665E-03	0.83108E-01	2
0.47500E+02	0.35358E+04	0.48022E+05	0.40775E-03	0.83516E-01	2
0.46500E+02	0.35550E+04	0.51577E+05	0.43900E-03	0.83955E-01	2
0.45500E+02	0.35756E+04	0.55152E+05	0.47043E-03	0.84425E-01	2
0.44500E+02	0.35976E+04	0.58750E+05	0.50205E-03	0.84928E-01	2
0.43500E+02	0.36210E+04	0.62371E+05	0.53386E-03	0.85461E-01	2
0.42500E+02	0.36459E+04	0.66017E+05	0.56589E-03	0.86027E-01	2
0.41500E+02	0.36722E+04	0.69689E+05	0.59815E-03	0.86625E-01	2
0.40500E+02	0.37000E+04	0.73389E+05	0.63064E-03	0.87256E-01	2
0.39500E+02	0.32524E+04	0.76641E+05	0.66129E-03	0.87917E-01	2
0.38500E+02	0.32804E+04	0.79921E+05	0.69008E-03	0.88607E-01	2
0.37500E+02	0.33096E+04	0.83231E+05	0.71913E-03	0.89327E-01	2
0.36500E+02	0.33400E+04	0.86571E+05	0.74844E-03	0.90075E-01	2
0.35500E+02	0.33717E+04	0.89943E+05	0.77802E-03	0.90853E-01	2
0.34500E+02	0.34046E+04	0.93347E+05	0.80789E-03	0.91661E-01	2
0.33500E+02	0.34387E+04	0.96786E+05	0.83805E-03	0.92499E-01	2
0.32500E+02	0.34741E+04	0.10026E+06	0.86852E-03	0.93368E-01	2
0.31500E+02	0.35107E+04	0.10377E+06	0.89931E-03	0.94267E-01	2
0.30500E+02	0.35487E+04	0.10732E+06	0.93042E-03	0.95197E-01	2
0.29500E+02	0.35879E+04	0.11091E+06	0.96188E-03	0.96159E-01	2
0.28500E+02	0.36284E+04	0.11454E+06	0.99369E-03	0.97153E-01	2
0.27500E+02	0.36703E+04	0.11821E+06	0.10259E-02	0.98179E-01	2
0.26500E+02	0.37135E+04	0.12192E+06	0.10584E-02	0.99237E-01	2
0.25500E+02	0.37581E+04	0.12568E+06	0.10913E-02	0.10033E+00	2

0.24500E+02	0.37857E+04	0.12946E+06	0.11246E-02	0.10145E+00	2	
0.23500E+02	0.38093E+04	0.13327E+06	0.11581E-02	0.10261E+00	2	
0.22500E+02	0.38337E+04	0.13711E+06	0.11918E-02	0.10380E+00	2	
0.21500E+02	0.38588E+04	0.14097E+06	0.12257E-02	0.10503E+00	2	
0.20500E+02	0.38845E+04	0.14485E+06	0.12598E-02	0.10629E+00	2	
0.19500E+02	0.39110E+04	0.14876E+06	0.12941E-02	0.10758E+00	2	
0.18500E+02	0.39382E+04	0.15270E+06	0.13287E-02	0.10891E+00	2	
0.17500E+02	0.39661E+04	0.15667E+06	0.13636E-02	0.11027E+00	2	
0.16500E+02	0.39947E+04	0.16066E+06	0.13987E-02	0.11167E+00	2	
0.15500E+02	0.40241E+04	0.16468E+06	0.14340E-02	0.11311E+00	2	
0.14500E+02	0.40542E+04	0.16874E+06	0.14696E-02	0.11458E+00	2	
0.13500E+02	0.40850E+04	0.17282E+06	0.15055E-02	0.11608E+00	2	
0.12500E+02	0.41166E+04	0.17694E+06	0.15417E-02	0.11762E+00	2	
0.11500E+02	0.41490E+04	0.18109E+06	0.15781E-02	0.11920E+00	2	
0.10500E+02	0.41821E+04	0.18527E+06	0.16148E-02	0.12082E+00	2	
0.95000E+01	0.42159E+04	0.18949E+06	0.16518E-02	0.12247E+00	2	
0.85000E+01	0.42506E+04	0.19374E+06	0.16891E-02	0.12416E+00	2	
0.75000E+01	0.42860E+04	0.19802E+06	0.17268E-02	0.12588E+00	2	
0.65000E+01	0.43222E+04	0.20235E+06	0.17647E-02	0.12765E+00	2	
0.55000E+01	0.43592E+04	0.20670E+06	0.18030E-02	0.12945E+00	2	
0.45000E+01	0.43970E+04	0.21110E+06	0.18416E-02	0.13129E+00	2	
0.35000E+01	0.44355E+04	0.21554E+06	0.18805E-02	0.13317E+00	2	
0.25000E+01	0.44749E+04	0.22001E+06	0.19198E-02	0.13509E+00	2	
0.15000E+01	0.45152E+04	0.22453E+06	0.19594E-02	0.13705E+00	2	
0.50000E+00	0.45562E+04	0.22908E+06	0.19994E-02	0.13905E+00	2	

INITIAL BASE FORCE(LBS) = 355177.69

ITERATIONS= 81

DEPTH(FT) 0.00 1.00 2.00 3.00 4.00 5.00 6.00 7.00 8.00 9.00 10.00 11.00 12.00	LOAD(LBS) 0.14992E+06 0.15721E+06 0.16451E+06 0.17180E+06 0.17909E+06 0.19367E+06 0.20096E+06 0.20825E+06 0.21554E+06 0.22283E+06 0.23013E+06 0.23742E+06	SHAFT MVMT(IN) 0.98875 0.98740 0.98598 0.98450 0.98295 0.98134 0.97967 0.97793 0.97612 0.97425 0.97232 0.97033 0.96827	SOIL MVMT(IN) 2.15238 2.58505 2.85868 3.05836 3.20933 3.32392 3.40946 3.47082 3.51146 3.53398 3.54040 3.53233 3.51109
11.00	0.23013E+06	0.97033	3.53233
12.00 13.00 14.00 15.00	0.23742E+06 0.24471E+06 0.25200E+06 0.25929E+06	0.96827 0.96614 0.96395 0.96170	3.51109 3.47778 3.43333 3.37853

TABLE C-7 (Concluded)

16.00	0.26658	3E+06	0.95938	3.31409
17.00	0.2738	7E+06	0.95700	3.24058
18.00	0.28110	5Е+Об	0.95455	3.15857
19.00	0.28845	5E+06	0.95204	3.06850
20.00	0.29575	5E+06	0.94946	2.97082
21.00	0.30304	1E+06	0.94683	2.86589
22.00	0.31033	3Е+Об	0.94412	2.75408
23.00	0.31762	2E+06	0.94135	2.63568
24.00	0.32491	LE+06	0.93852	2.51098
25.00	0.33220)E+06	0.93563	2.38025
26.00	0.33949	9E+06	0.93267	2.24373
27.00	0.34678	3E+06	0.92964	2.10165
28.00	0.3540	7E+06	0.92655	1.95420
29.00	0.3613	7E+06	0.92340	1.80157
30.00	0.36866	5E+06	0.92018	1.64396
31.00	0.37595	5E+06	0.91690	1.48152
32.00	0.38324	1E+06	0.91355	1.31441
33.00	0.39019	9E+06	0.91014	1.14278
34.00	0.39292	2E+06	0.90669	0.96503
35.00	0.38861	LE+06	0.90325	0.77876
36.00	0.38207	7E+06	0.89985	0.58423
37.00	0.37554	1E+06	0.89651	0.38165
38.00	0.36901	LE+06	0.89323	0.17124
39.00	0.36248	3E+06	0.89000	-0.04679
40.00	0.35595	5E+06	0.88684	-0.27224
41.00	0.34864	1E+06	0.88373	-0.23257
42.00	0.34133	3E+06	0.88069	-0.19578
43.00	0.33403	3E+06	0.87771	-0.16181
44.00	0.32672	2E+06	0.87480	-0.13064
45.00	0.31941	LE+06	0.87195	-0.10222
46.00	0.31211	LE+06	0.86917	-0.07650
47.00	0.30480E+06		0.86645	-0.05346
48.00	0.29749	9E+06	0.86380	-0.03305
49.00	0.29018	3E+06	0.86121	-0.01524
50.00	0.28288	3E+06	0.85868	0.00000
	_ /			
STRUC LOA		SOILP(PSF)		DEPTH(FT)
	0.	0.00	-1	.00

C-3. Listing

A Fortran listing of the computer program is provided in Table C-8 in case modifications may be required for specific applications.

TABLE C-8

Listing

```
С
      PREDICTION OF VERTICAL SHAFT MOVEMENT
С
      DEVELOPED BY LD JOHNSON
      PARAMETER (NL=40,NM=100)
      COMMON AREA, DB, DX, DS, DEL, PI, P(NM), IE(NM), SOILP, NEL, NBX, KOPT
      COMMON/BAS/FORCE, QBULT, CS(NL), CC(NL), EO(NL), PM(NL), AREAB, E50
      COMMON/SHA/ALGTH,AK(NL),B(NL),C(NL),DELT(NM),DELS(NM),
         EP(NM), TOT(NM), ZEP(NM), IOPT, JOPT, LOPT, NC, JL,
     1
     2
         NCC, FS(11), ZEPP(11), NCURVE(11), ALPHAA(NL)
      DIMENSION TL(NL), TM(NL), R(NL), S(NL), HED(20), T(11,11), Z(11,2),
     1 PS(NL)
      DATA(T(I,1),I=1,11)/.0,.3,.6,.75,.9,.95,1.,1.,1.,1.,1.,1./,
         (Z(I,1),I=1,11)/.0,.05,.1,.15,.2,.23,.3,.45,.75,1.05,1.5/
     1
    7 CONTINUE
      Z(1,2)=0.0
      JL=1
      GAW=62.43
      EP(1)=1.E35
      PI=3.1415926
    6 NNN=1
      NC=1
      OPEN(5,FILE='DATLTR.TXT')
      OPEN(6,FILE='LTROUT.TXT')
      OPEN(7, FILE='\GRAPHER\AXIC.DAT')
      OPEN(8, FILE='\GRAPHER\AXIT.DAT')
      OPEN(9,FILE='\GRAPHER\AXIL.DAT')
      READ(5,1) (HED(I), I=1,20)
      WRITE(6,1) (HED(I), I=1,20)
    1 FORMAT(20A4)
      DO 9 I=1,NM
      DELS(I)=0.0
    9 DELT(I)=0.0
      READ(5,2) NMAT,NEL,DX,GWL,LO,IQ,IJ
    2 FORMAT(215,2F6.2,415)
      WRITE(6,3)NMAT,NEL,DX,GWL,LO,IQ,IJ
    3 FORMAT(//1X,'NMAT=', I5, 3X,'NEL=', I5, 3X,'DX=', F6.2,' FT', 3X,
     1 'GWL= ', F6.2,' FT', /, 3X, 'LO=', I5, 3X, 'IQ (SHAFT INC)=', I5,
     2 3X, 'IJ (NO.LOADS) = ', I5)
      LOPT=LO
      NNP=NEL+1
      READ(5,4)IOPT, JOPT, KOPT, SOILP, DS, DB
    4 FORMAT(315,3F10.3)
      WRITE(6,5)IOPT, JOPT, KOPT, SOILP, DS, DB
    5 FORMAT(//1x,'I=',I5,3x,'J=',I5,3x,'K=',I5,10x,'SOILP=',F10.2,
     1 ' PSF',/,1X,'DS=',F10.2,' FT',/,1X,'DB=',F10.2,' FT')
      IF(KOPT.EQ.2.OR.KOPT.EQ.5.OR.KOPT.EQ.9)READ(5,11)E50
   11 FORMAT(E13.3)
```

```
IF(KOPT.EQ.2.OR.KOPT.EQ.5.OR.KOPT.EQ.9)WRITE(6,12)E50
12 FORMAT(//1X,'E50=',E13.3)
   IU=IJ
   READ(5,13)LLL
13 FORMAT(I5)
   IF(LLL.EO.0)WRITE(6,14)LLL
14 FORMAT(//1X,'LOCAL SHEAR FAILURE AT BASE - LLL=', 15)
   IF(LLL.EQ.1)WRITE(6,15)LLL
15 FORMAT(//1X,'GENERAL SHEAR FAILURE AT BASE - LLL=', I5)
  WRITE(6,10)
10 FORMAT(//1X,'MAT GS EO
                               WO(%) PS(PSF)
                                               CS CC
                                                           CO(PSF)',
 1 ' PHI K PM(PSF)',/)
 8 READ(5,16)M,TL(M),EO(M),TM(M),PS(M),CS(M),CC(M),C(M),B(M),AK(M),
  1 PM(M)
16 FORMAT(I3,3F6.2,F7.0,2F7.2,F7.0,2F6.2,F7.0)
  WRITE(6,16)M,TL(M),EO(M),TM(M),PS(M),CS(M),CC(M),C(M),B(M),AK(M),
  1 \text{PM}(M)
  B(M) = B(M) * PI / 180.
   IF(PM(M).LT.PS(M)) PM(M) = PS(M)
   IF(NMAT-M)18,20,8
18 PRINT 17,M
17 FORMAT(17HERROR IN MATERIAL, 15)
  GO TO 8
20 IF(IOPT.NE.6)GO TO 23
  READ(5,21)(ALPHAA(I),I=1,NMAT)
21 FORMAT(2(7F10.5))
  WRITE(6,22)(ALPHAA(I),I=1,NMAT)
22 FORMAT(//1X,'ALPHA=',2(7F10.5))
23 L=0
  WRITE(6, 25)
25 FORMAT(//1X,'ELEMENT',5X,'NO OF SOIL',/)
30 READ(5,26)M, IE(M)
26 FORMAT(215)
35 L=L+1
   IF(M-L)45,45,40
40 IE(L) = IE(L-1)
  GO TO 35
45 IF(NEL-L)50,50,30
50 CONTINUE
   DO 52 I=1,NEL
   WRITE(6,53)I,IE(I)
52 CONTINUE
53 FORMAT(1X, 15, 10X, 15)
  EFFECTIVE STRESS IN SOIL
  P(1) = 0.0
  DXX=DX
  DO 55 I=2,NNP
  MTYP = IE(I-1)
```

С

С

```
TABLE C-8 (Continued)
```

```
WC=TM(MTYP)/100.
   GAM=TL(MTYP)*GAW*(1.+WC)/(1.+EO(MTYP))
   IF(DXX.GT.GWL)GAM=GAM-GAW
   P(I) = P(I-1) + DX * GAM
   DXX=DXX+DX
55 CONTINUE
   IF(KOPT.LE.6)GO TO 56
   READ(5,57)RFF,GG
57 FORMAT(F6.3,E13.3)
   WRITE(6,59)RFF,GG
59 FORMAT(//1X, 'REDUCTION FACTOR=', F6.3, 3X, 'SHEAR MODULUS=', E13.3)
   HALF=FLOAT(IQ)/2.
   IJK=IFIX(HALF)
   MTYP=IE(IJK)
   PH=B(MTYP)
   SHR=C(MTYP)+AK(MTYP)*SIN(PH)*P(IJK)/COS(PH)
   CONS=SHR*DS/(2.*GG)
   D1=1.5*FLOAT(IQ)*DX/DS
   DO 58 I=1,11
   CONC=(D1-T(I,1)*RFF)/(1.-T(I,1)*RFF)
   Z(I,1)=12.*T(I,1)*CONS*ALOG(CONC)
58 CONTINUE
  LOAD-DEFLECTION BEHAVIOR OF SHAFT
56 IF(KOPT.LE.2.OR.KOPT.GT.6)GO TO 72
   READ(5, 62)NCA
62 FORMAT(15)
   WRITE(6,60)NCA
60 FORMAT(//1X,'NO. OF LOAD-TRANSFER CURVES(<12)?=', I5)
   DO 65 I=1,NCA
   WRITE(6,61)I
61 FORMAT(/1X,'CURVE ', 15,/)
   II = I + 1
   READ(5,63)(T(M,II),M=1,11)
63 FORMAT(11F6.2)
   WRITE(6,64)(T(M,II),M=1,11)
64 FORMAT(1X, 'RATIO SHR DEV, M=1,11 ARE', /1X, 11F6.3)
65 CONTINUE
   DO 67 M=2,11
   READ(5,66)S(M)
   IF(S(M).LT..000001)GO TO 68
   JL=2
   Z(M,2)=S(M)
   WRITE(6,69)M,S(M)
67 CONTINUE
68 CONTINUE
66 FORMAT(F6.3)
69 FORMAT(/1X,'MOVEMENT(IN.) FOR LOAD TRANSFER M=',15,' IS ',F6.3,
 1
     ' INCHES')
```

```
72 IF(IOPT.LE.4.OR.IOPT.EO.6)GO TO 78
    READ(5,81)NCC
 81 FORMAT(I5)
    WRITE(6,82)NCC
 82 FORMAT(//1X,'NO OF SKIN FRICTION-DEPTH TERMS(<12)? ARE', 15,/1X,
   1 'SKIN FRICTION(PSF) DEPTH(FT) CURVE NO',//)
    DO 89 M=1,NCC
    READ(5,83)FS(M), ZEPP(M), NCUR
    WRITE(6,77)FS(M),ZEPP(M),NCUR
 77 FORMAT(3X,F10.3,5X,F10.3,5X,I5)
 83 FORMAT(2F10.3, I5)
   NCURVE(M)=1+NCUR
 89 CONTINUE
 78 IF(JOPT.EQ.1)GO TO 84
    READ(5,81)NC
    READ(5,92)(EP(M), ZEP(M), M=1, NC)
 92 FORMAT(E13.3,F6.2)
    WRITE(6, 102)(EP(M), ZEP(M), M=1, NC)
102 FORMAT(//1X,'E SHAFT(PSF) AND DEPTH(FT):',/1X,4(E13.3,2X,F6.2),
   1 /1x,4(E13.3,2x,F6.2),/1x,4(E13.3,2x,F6.2),/1x,4(E13.3,2x,F6.2))
 84 UU=100.
   MM = 0
    ALGTH=DX*FLOAT(IO)
    AREA=(PI/4.)*DS**2.
    AREAB=(PI/4.)*DB**2.
    NBX=IQ+1
    IF(NBX.LT.NNP)MAT=IE(NBX)
    IF(NBX.EO.NNP)MAT=IE(NEL)
    QBU=9.*C(MAT)
    IF(LLL.LE.0.1)OBU=7.*C(MAT)
    IF(B(MAT).LT.0.001)GO TO 86
    PH=B(MAT)
   TA=SIN(PH)/COS(PH)
   XNQ=(PH/2.)+45.*PI/180.
    IF(LLL.EQ.0)GO TO 74
    TB=(1.5*PI-PH)*TA
   XNQ=EXP(TB)/(2.*(COS(XNQ))**2.)
    GO TO 76
 74 XNO=(1.+TA) * EXP(TA) * (SIN(XNO)/COS(XNO)) * 2.
 76 XNC=(XNQ-1.)/TA
    QBU=C(MAT)*XNC+(SOILP+P(NBX))*XNQ
 86 QBULT=QBU*AREAB
    NN=1
   NO=IU
    ITER=1
    S(1) = (SOILP+P(NBX)) * AREAB
    IF(KOPT.NE.6)GO TO 91
   R(1) = 0.0
```

```
IU1=IU-1
    WRITE(6,95)S(1),IU1
 95 FORMAT(//,1x,'BASE DISPLACEMENT(IN.),BASE LOAD(LBS) >',F10.2,
   1 ' FOR', 15, ' POINTS')
    DO 94 M=2,IU
    READ(5, 103)R(M), S(M)
    WRITE(6,103)R(M),S(M)
 94 CONTINUE
103 FORMAT(F10.5,F15.3)
 91 WRITE(6,90)QBULT
 90 FORMAT(/,10X,'BEARING CAPACITY=',F13.2,' POUNDS')
    WRITE(6,88)
 88 FORMAT(/,1X,'DOWNWARD DISPLACEMENT')
    IF(KOPT.NE.6)DLOAD=(QBULT-S(1))/(FLOAT(IU)-1.)
 87 IF(ITER.GT.1.AND.KOPT.NE.6)S(ITER)=S(ITER-1)+DLOAD
    FORCE=S(ITER)
    IF(KOPT.NE.6)CALL BASEL
    IF(KOPT.NE.6)R(ITER)=DEL
    IF(KOPT.EO.6)DEL=R(ITER)
 98 TOT(NBX)=FORCE
    GO TO 97
 93 WRITE(6,99)
 99 FORMAT(/,1X,'NEGATIVE UPWARD DISPLACEMENT')
 96 R(ITER)=DEL
    TOT(NBX) = 0.0
    S(ITER)=0.0
 97 CALL SHAFL(T,Z)
    TL(ITER) = TOT(1)
   TM(ITER)=DELT(1)
   IF(ITER-NO)100,101,101
100 ITER=ITER+1
    IF(MM.EQ.0)GO TO 87
    XN=FLOAT(ITER-IU-2)
   DEL=-0.01*2.**XN
    GO TO 96
101 WRITE(6,105)
105 FORMAT(/,49H
                   TOP LOAD TOP MOVEMENT BASE LOAD BASE MOVE,
      4HMENT,/,49H
                                                               INCHES)
   1
                       LBS
                                    INCHES
                                                    LBS
    DO 110 M=NN,NO
    WRITE(6,111)TL(M),TM(M),S(M),R(M)
    IF(MM.EQ.0) WRITE(7,111)TL(M), -TM(M), S(M), -R(M)
    IF(MM.EQ.1) WRITE(8,111)TL(M),-TM(M),S(M),-R(M)
110 CONTINUE
111 FORMAT(4E13.5)
112 MM=MM+1
    DEL=0.0
    IF(MM.EQ.2)GO TO 125
    ITER=IU+1
```

```
NO=2*IU
     NN=IU+1
      GO TO 93
С
      SHAFT MOVEMENT FOR STRUCTURAL LOAD
  125 WRITE(6,121)
  121 FORMAT(/,1X,'STRUC LOAD(LBS)
                                     SOILP(PSF) ACTIVE DEPTH(FT)')
      READ(5,122)STRUL,SOILP,XA
      WRITE(6,1220)STRUL,SOILP,XA
  122 FORMAT(3F15.2)
 1220 FORMAT(3X,F10.0,3X,F10.2,5X,F10.2)
     IF(XA.LT.0.0)GO TO 380
     RESTU=0.0
     DD=1000.
     DEL=0.0
     DELL=0.0
     LOPT=0
      IF(LO.EO.3)LOPT=3
     V=0.0025
      DO 123 I=1,NNP
  123 DELS(I)=0.0
      ITER=1
      STRU=STRUL
      QBR=(7./9.)*QBU
  124 RESTR=(QBR+SOILP+P(NBX-1))*PI*(DB**2.-DS**2.)/4.
      IF(DB.LE.DS)RESTR=0.0
      IF(STRU.LT.0.0)RESTU=RESTR+(QBR+ALGTH
     1
        *150.)*AREA
      WRITE(6,126)RESTR
  126 FORMAT(/,1X,'BELL RESTRAINT(LBS)=',8X,F13.2)
      IF(STRU.LT.0.0)WRITE (6,127) RESTU
  127 FORMAT(/,1X,'FIRST ESTIMATE OF PULLOUT RESTRAINT(LBS)=',F13.2)
      NN=1
      NO=IU
      WRITE(6,128)
  128 FORMAT(/,20X,26HLOAD-DISPLACEMENT BEHAVIOR,/)
      IF(STRU.GT.0.0)GO TO 135
      FORCE=STRU
      EXFOR=RESTR+FORCE
      IF(EXFOR.GT.-0.01)DEL=0.0
      IF(EXFOR.GT.-0.01)GO TO 145
      STRU=EXFOR
     NN=IU+1
      NO=2*IU
  135 DO 136 M=NN,NO
      IF(M.GT.IU)GO TO 141
      IF(TL(M)-STRU)136,137,137
  141 IF(ABS(TL(M))-ABS(STRU))136,137,137
  136 CONTINUE
```

```
TABLE C-8 (Continued)
```

```
DIFF=TL(M)-TL(M-1)
      IF(DIFF.LT.0.01)DEL=R(M)
      IF(DIFF.LT.0.01)GO TO 138
  137 DEL=R(M-1)+(R(M)-R(M-1))*(STRU-TL(M-1))/(TL(M)-TL(M-1))
  138 IF(ABS(STRU).GT.ABS(TL(M)).AND.STRU.LT.0.0)GO TO 376
      TOT(NBX) = S(M-1) + (S(M) - S(M-1)) * (STRU - TL(M-1)) / (TL(M) - TL(M-1))
      CALL SHAFL(T,Z)
      DEL=DELT(NBX)
С
      VERTICAL DISPLACEMENT OF ADJACENT SOIL
  145 IF(LO.LT.2)WRITE(6,146)
  146 FORMAT(//20X,'EFFECT OF ADJACENT SOIL'/)
      IF(LO.GE.2)LOPT=3
      DO 150 K=2,NNP
      I=NNP+1-K
      DEPTH=DX*FLOAT(I)-DX/2.
      IF(DEPTH.GT.XA)GO TO 150
      MTYP=IE(I)
      TEM = (SOILP + (P(I) + P(I+1))/2.)/PS(MTYP)
      TEA = (SOILP+(P(I)+P(I+1))/2.)/PM(MTYP)
      TEB = PM(MTYP)/PS(MTYP)
      TEC = DX*12./(1.+EO(MTYP))
      IF(TEA.LE.1.)TDEL=CS(MTYP)*TEC*ALOG10(TEM)
      IF(TEA.GT.1.)TDEL=TEC*(CS(MTYP)*ALOG10(TEB)+CC(MTYP)*ALOG10(TEA))
      DELS(I)=TDEL+DELS(I+1)
  150 CONTINUE
С
      LOAD TRANSFER TO SHAFT FROM SOIL MOVEMENT
      ITT=1
      IF(NNN.GT.1)LOPT=1
  160 TOT(NBX)=0.0
      CALL SHAFL(T,Z)
      FORCE=TOT(NBX)-TOT(1)+STRUL
      IF(ITER.EQ.1)WRITE(6,162)FORCE
  162 FORMAT(/,1X,'INITIAL BASE FORCE(LBS)=',F13.2,/)
      IF(FORCE.LT.0.0.OR.ITER.GT.1)GO TO 300
С
      DOWN FORCE, POSITIVE TIP DISPLACEMENT
      BBETA=0.0
  170 IF(KOPT.NE.6)CALL BASEL
С
      SHAFT MOVEMENT FOR DOWNDRAG
      IF(KOPT.NE.6)GO TO 200
      DO 163 M=2,IU
      IF(S(M)-FORCE)163,164,164
  163 CONTINUE
  164 DEL=R(M-1)+(R(M)-R(M-1))*(FORCE-S(M-1))/(S(M)-S(M-1))
  200 TOT(NBX)=FORCE
      LOPT=LO
      CALL SHAFL(T,Z)
      BETA=TOT(1)-STRUL
      IF(LO.LT.2)WRITE(6,309)ITER,FORCE,BETA
```

```
IF(UU-ABS(BETA))205,350,350
  205 IF(BETA.LT.0.0)GO TO 206
      IF(BBETA.LT.-50..AND.DD.LT.101.)GO TO 350
      IF(BBETA.LT.-50..AND.DD.GT.999.)DD=100.
      BBETA=BETA
      FORCE=TOT(NBX)-DD
      IF(FORCE.LT.0.0)ITER=1
      IF(FORCE.LT.0.0)GO TO 300
      ITER=ITER+1
      GO TO 170
  206 IF(BBETA.GT.50..AND.DD.LT.101.)GO TO 350
      IF(BBETA.GT.50..AND.DD.GT.999.)DD=100.
      BBETA=BETA
      FORCE=TOT(NBX)+DD
      ITER=ITER+1
      GO TO 170
С
      UPLIFT FORCE, NEGATIVE TIP DISPLACEMENT
  300 LOPT=LO
      IF(ITER.EO.1)DELL=DELT(NBX)
      IF(LOPT.GE.1)GO TO 307
  302 WRITE(6,305)FORCE
  305 FORMAT(/,1X,'BASE FORCE(LBS)=',3X,F13.2)
  307 EXFOR=RESTR+FORCE
      IF(EXFOR.GT.0.0)GO TO 340
      IF(ITT.EQ.100)WRITE(6,311)DELL,FORCE
      IF(ITT.EQ.100)ITT=0
      DELL=DELL-V
      DEL=DELL
      IF(DEL.LT.DELS(1))GO TO 375
      LOPT=LO
      ITT=ITT+1
      ITER=ITER+1
      GO TO 160
  309 FORMAT(25X, I5, 2F15.2)
  311 FORMAT(/,1x,'DISPLACEMENT(INCHES)=',3x,F8.4,4x,'FORCE=',F12.2,
     1 ' POUNDS')
С
       SHAFT MOVEMENT FOR UPLIFT
  340 TOT(NBX)=FORCE
      PRINT 311, DELL, FORCE
      DEL=DELL
      LOPT=LO
      IF(LO.EQ.1)LOPT=0
      CALL SHAFL(T,Z)
  350 FORCE=TOT(NBX)-TOT(1)+STRUL
      WRITE(6,352)ITER
  352 FORMAT(/,1X,'ITERATIONS=',110)
      IF(FORCE.GT.QBULT)WRITE(6,353)
  353 FORMAT(/,1X,'THE SOIL BEARING CAPACITY IS EXCEEDED')
```

C C

```
WRITE(6,355)
355 FORMAT(/,1X,'DEPTH(FT) LOAD(LBS)
                                           SHAFT MVMT(IN)',
   1 ' SOIL MVMT(IN)')
    DXX=0.0
    DO 360 I=1,NBX
    TOTAL=DELT(I)+DELS(I)
    IF (FORCE.GT.0.0) TOTAL=TOTAL-DELS(NBX)
    WRITE(6,370)DXX,TOT(I),TOTAL,DELS(I)
    WRITE(9,370)-DXX,TOT(I),TOTAL,DELS(I)
    DXX=DXX+DX
360 CONTINUE
370 FORMAT(F7.2,2X,E13.5,2F15.5)
    GO TO 379
376 WRITE(6,377)
377 FORMAT(/,1X,'SHAFT PULLS OUT')
    GO TO 379
375 WRITE(6,378)
378 FORMAT(//,1X,'SHAFT UNSTABLE')
    WRITE(6,311)DELL,FORCE
379 NNN=NNN+1
    GO TO 125
380 READ(5,81)NON
    IF(NON.GE.1)GO TO 7
    CLOSE(5,STATUS='KEEP')
    CLOSE(6,STATUS='KEEP')
    CLOSE(7, STATUS='KEEP')
    CLOSE(8, STATUS='KEEP')
    CLOSE(9,STATUS='KEEP')
    STOP
    END
    SUBROUTINE BASEL
    PARAMETER (NL=40,NM=100)
    COMMON AREA, DB, DX, DS, DEL, PI, P(NM), IE(NM), SOILP, NEL, NBX, KOPT
    COMMON/BAS/FORCE, QBULT, CS(NL), CC(NL), EO(NL), PM(NL), AREAB, E50
    DIMENSION Q(NM)
    DXX=DX
    NNP=NEL+1
    NA=NBX+1
    BPRES=FORCE+(DB**2.-DS**2.)*(SOILP+P(NBX))*PI/4.
    IF(DB.LT.DS)BPRES=FORCE
    BPRES=BPRES/AREAB
    IF(KOPT.EQ.1.OR.KOPT.EQ.4.OR.KOPT.EQ.8)GO TO 15
    IF(KOPT.EQ.2.OR.KOPT.EQ.5.OR.KOPT.EQ.9)GO TO 14
    Q(NBX)=BPRES
    DO 5 I=NA, NNP
    PT=1.+(DB/(2.*DXX))**2.
```
TABLE C-8 (Continued)

```
PT=PT**1.5
   Q(I) = P(I) + SOILP + (BPRES - P(NBX) - SOILP) * (1. - 1. / PT)
   DXX=DXX+DX
 5 CONTINUE
   DEL=0.0
   IF(NBX.GT.NEL)GO TO 20
   DO 10 I=NBX,NEL
  MTYP=IE(I)
   QQ=(Q(I)+Q(I+1))/2.
   PPP=SOILP+(P(I)+P(I+1))/2.
   F=OO/PPP
   CON=CC(MTYP)
   IF(QQ.LT.PM(MTYP))CON=CS(MTYP)
   IF(QQ.GT.PM(MTYP))GO TO 8
  DEL=DEL+DX*12.*CON*ALOG10(F)/(1.+EO(MTYP))
  GO TO 10
 8 AA=PM(MTYP)/PPP
  AB=QQ/PM(MTYP)
  DEL=DEL+(CS(MTYP)*ALOG10(AA)+CC(MTYP)*ALOG10(AB))*DX*12./
  1 (1.+EO(MTYP))
10 CONTINUE
   GO TO 20
14 C1=0.76
   C2=1.5
   C3=2.*E50
   GO TO 16
15 C1=1.
   C2=3.
   C3=0.04
16 DEL=((((BPRES)*AREAB)/(QBULT*C1))**C2)*C3*DB*12.
   DEL=DEL-((((P(NBX)+SOILP)*AREAB)/(QBULT*C1))**C2)*C3*DB*12.
20 CONTINUE
  RETURN
   END
   SUBROUTINE SHAFL(T,Z)
   PARAMETER (NL=40,NM=100)
   COMMON AREA, DB, DX, DS, DEL, PI, P(NM), IE(NM), SOILP, NEL, NBX, KOPT
  COMMON/SHA/ALGTH,AK(NL),B(NL),C(NL),DELT(NM),DELS(NM),
  1 EP(NM), TOT(NM), ZEP(NM), IOPT, JOPT, LOPT, NC, JL,
  1 NCC, FS(11), ZEPP(11), NCURVE(11), ALPHAA(NL)
  DIMENSION T(11,11), Z(11,2)
  U=0.0001
  DELC=0.0
   IF(JOPT.EQ.0)GO TO 5
   EPILE=EP(1)
 5 IF(LOPT.GE.1)GO TO 16
```

C C TABLE C-8 (Continued)

```
WRITE(6,10)TOT(NBX)
10 FORMAT(19HPOINT BEARING(LBS)=,F13.2,//)
  WRITE(6,15)
15 FORMAT(50H
                  DEPTH
                            LOAD TRANS
                                        TOTAL LOAD COM OF IN,
  1 20HCR TOTAL MVMT ITER,/,31H
                                                     LBS
                                        FT
                                                                  ,
  2 31H LBS
                    INCHES
                                 INCHES)
16 DELT(NBX)=DEL
  DO 50 K=2,NBX
  I=NBX+1-K
  MTYP=IE(I)
  NTER=1
  AKK = K - 2
  BSLMT=ALGTH-(AKK*DX)
  DEPTH=BSLMT-DX/2.
  IF(IOPT.LE.4.OR.IOPT.EQ.6)GO TO 17
  DO 18 JJ=2, NCC
  IF(ZEPP(JJ)-DEPTH)18,19,19
18 CONTINUE
19 JK=NCURVE(JJ)
   SKF=FS(JJ-1)+(FS(JJ)-FS(JJ-1))*(DEPTH-ZEPP(JJ-1))/(ZEPP(JJ)-ZE)
  1 PP(JJ-1))
17 IF(IOPT.LE.4.OR.IOPT.EQ.6)JK=1
  DO 20 M=2,11
   IF(Z(M,JL)-ABS(DEL))20,21,21
20 CONTINUE
  PERCP=T(11,JK)
  GO TO 25
21 PERCP=T(M-1,JK)+((T(M,JK)-T(M-1,JK))*(ABS(DEL)-Z(M-1,JL))/
 1 (Z(M,JL)-Z(M-1,JL)))
25 IF(IOPT.EQ.5)SHR=SKF*PERCP
  IF(IOPT.EQ.5)GO TO 35
26 F=BSLMT*PI/ALGTH
  PH=B(MTYP)
  TA=SIN(PH)/COS(PH)
   SHR=TA*AK(MTYP)*(SOILP+(P(I)+P(I+1))/2.)+C(MTYP)
   IF(IOPT.EQ.1)SHR=SHR*SIN(F)
  IF(IOPT.EQ.2)SHR=SHR*0.6
  IF(IOPT.EQ.3)SHR=SHR*.45
  IF(IOPT.EO.4)SHR=SHR*.3
  IF(IOPT.EQ.6)SHR=SHR*ALPHAA(MTYP)
35 TNSLD=SHR*PERCP
  IF(DEL.LT.0.0)TNSLD=-TNSLD
  ALDINC=TNSLD*PI*DS*DX-(P(I+1)-P(I))*AREA
  IF(JOPT.EQ.1.OR.NC.EQ.1)GO TO 42
  DO 40 M=2,NC
   IF(ZEP(M)-DEPTH)40,41,41
40 CONTINUE
41 EPILE=EP(M-1)+(EP(M)-EP(M-1))*(DEPTH-ZEP(M-1))/(ZEP(M)-
```

TABLE C-8 (Concluded)

```
1 ZEP(M-1))
42 TOT(I)=ALDINC+TOT(I+1)
  AVGLD=TOT(I+1)+ALDINC/2.
  IF(JOPT.EQ.1)GO TO 46
  AEPILE=AREA*EPILE
  DELC=AVGLD*DX*12./AEPILE
  DELT(I)=DELC+DELT(I+1)-(DELS(I)-DELS(I+1))
  DELAV=((((TOT(I)+TOT(I+1))/2.)+TOT(I+1))*DX*3./AEPILE)
  1 +DELT(I+1)
  ETA=DELAV-DEL
  IF(U-ABS(ETA))45,46,46
45 DEL=DELAV
  NTER=NTER+1
  GO TO 17
46 IF(LOPT.GE.1)GO TO 48
  WRITE(6,55)DEPTH,ALDINC,TOT(I),DELC,DELT(I),NTER
48 DEL=DELT(I)
50 CONTINUE
55 FORMAT(5E13.5,15)
  RETURN
  END
```

APPENDIX D

NOTATION

Symbol	Description
С	Unit soil cohesion, ksf; distance from centroid to outer fiber, ft
C _{st}	Distance from centroid of steel reinforcing rod to outer fiber, ft
с′	Effective unit soil cohesion, kips per square foot (ksf)
C _a	Adhesion of soil to base \leq c, ksf
d_r	Diameter of vane rod, inch
d_v	Vane diameter, inch
е	Void ratio
e_{max}	Reference void ratio of a soil at the minimum density
${\sf e}_{\tt min}$	Reference void ratio of a soil at the maximum density
e _B	Eccentricity parallel with B, $M_{_{\rm B}}/Q$, ft
e _w	Eccentricity parallel with W, M_w/Q , ft
f_n	Negative skin friction, ksf
f_{ni}	Mobilized negative skin friction of pile element i, ksf
f_s	Skin friction, ksf
${\tt f}_{\tt si}$	Skin friction of pile element i, ksf
$\mathtt{f}_{\mathtt{c}}'$	Concrete strength, psi
${\tt f}_{y{\tt s}}^{\prime}$	Steel yield strength, psi
f _s	Full mobilized skin friction, ksf
h	Height of hammer fall, ft
h_v	Vane height, inch

Symbol	Description
k	Constant relating elastic soil modulus with depth $E_s = kz$, kips/ft ³ Term preventing unlimited increase in bearing capacity with increasing depth for Hanson method
k _c	Point correlation factor used in CPT B & G method
n	Number of piles in a group, number of pile elements
\mathtt{p}_{o}	Internal pressure causing lift-off of dilatometer membrane, ksf
P ₁	Internal pressure required to expand central point of the dilatometer membrane by 1.1 millimeters, ksf
$p_{\rm L}$	Pressuremeter limit pressure, ksf
đ	Bearing pressure on foundation, ksf
q_1	Soil pressure per inch of settlement, ksf
q _a	Allowable unit bearing capacity, ksf
\mathbf{q}_{b}	Unit base resistance, ksf
\mathbf{q}_{bu}	Unit ultimate end bearing resistance, ksf
ď	Cone penetration resistance, ksf
q_{c1}	Average $\rm q_{c}$ over a distance of L+0.7B to L+4B below pile tip, Figure 5-21, ksf
\mathbf{q}_{c2}	Average q_c over a distance L to L-8B above pile tip, Figure 5-21, ksf
$q_{\rm cbl}$	Average cone penetration resistance from footing base to 0.5B below base, ksf
$\mathbf{q}_{\mathrm{cb2}}$	Average cone penetration resistance from 0.5B to 1.5B below base, ksf
q_{ci}	Cone penetration resistance of depth increment i, ksf
\dot{q}_{c}	Equivalent cone penetration resistance from footing base to 1.5B below base, ksf
\mathbf{q}_{d}	Design unit bearing pressure, ksf
\mathbf{q}_{load}	Area pressure applied to soil supporting pile, ksf
q _{na}	Nominal unit allowable bearing capacity, ksf

Symbol	Description
q _r	Resultant applied pressure on foundation soil, R/BW, ksf
\mathbf{q}_{u}	Ultimate unit bearing capacity, ksf
q _{ua}	Ultimate unit bearing capacity of axially loaded square or round footings with horizontal ground surface and base, kips
\mathbf{q}_{ut}	Ultimate unit bearing capacity of upper dense sand, ksf
$\mathbf{q}_{a,1}$	Allowable unit bearing capacity for 1 inch of settlement, ksf
q _{u,b}	Ultimate unit bearing capacity on a very thick bed of the bottom soft clay layer, ksf
$\mathbf{q}_{u,p}$	Ultimate unit bearing capacity of plate, ksf
$\mathtt{q}_{\boldsymbol{\ell}}$	Limiting stress for Meyerhof method $\mathtt{N}_{_{\mathrm{QP}}}\mathtt{tan}\phi\prime,$ ksf
$\mathbf{q}_{\mathrm{u}}^{\prime}$	Net ultimate bearing capacity, $~~q_{_{\rm u}}$ – $\gamma_{_{\rm D}}.{\rm D}$, ksf
r _γ	Reduction factor, 1 - 0.25log(B/6)
S	Spacing between piles, ft
u _w	Pore water pressure, ksf
Ya	Allowable lateral deflection, inch
Уо	Lateral groundline deflection, inch
Z	Depth, ft
А	Cross-section area of drilled shaft or pile, ft^2
A_{b}	Area of tip or base, ft ²
A_{bp}	Area of base resisting pullout force, ft^2
A_{e}	Effective area of foundation $B'W'$, ft ²
A_{si}	Perimeter area of pile element $\text{ i, } C_{_{\mathrm{si}}} \cdot \Delta L$
A_{st}	Area of steel, inch ²
В	Least lateral dimension of a foundation or pile diameter, ft
B _b	Base diameter, ft

Symbol	Description
B _{dia}	Diameter of circular footing, ft
B_p	Diameter or width of the plate, ft
B _r	Horizontal distance beneath center of strip footing to location of outermost rod in reinforced soil, ft
B _s	Diameter or width of pile or shaft, ft
В′	Effective foundation width, $B - 2e_B$, ft
C_{f}	Correction factor for K when $\delta eq \phi'$
Cg	Circumference of pile group, minimum length of line that can enclose pile group, ft
C_{ua}	Average undrained shear strength of cohesive soil in which the group is placed, ksf
C_{ub}	Average undrained shear strength of cohesive soil below the tip to a depth 2B _b below the tip, ksf
C_{um}	Mean undrained shear strength along pile length, ksf
C_{ov}	Overburden pressure adjustment $(\sigma_{_{\rm o}}^{}/\sigma_{_{\rm v}}^{\prime})^{_{0.5}}$
Cs	Circumference of drilled shaft or pile, ft
$C_{\rm si}$	Circumference of drilled shaft or pile element i, ft
C_u	Undrained cohesion, ksf
$C_{u,lower}$	Undrained shear strength of the soft lower clay, ksf
$C_{u,upper}$	Undrained shear strength of the stiff upper clay, ksf
C_z	Pile Perimeter at depth z, ft
$C_{_{ER}}$	Rod energy correction factor
C_{L}	Perimeter of the pile tip, ft
C_{N}	Overburden correction factor
CPT	Cone penetration test
D	Depth of the foundation base below ground surface, ft

Symbol	Description
D _c	Critical depth where increase in stress from structure is 10 percent of the vertical soil stress beneath the foundation, ft
D _e	Equivalent embedment depth using CPT procedure for estimating bearing capacity, ft
D _r	Relative density, percent
D_{R}	Relative density, fraction
D_{GWT}	Depth below ground surface to groundwater, ft
Eg	Efficiency of pile group
E _h	Hammer efficiency
E_p	Young's modulus of pile, ksf (kips/inch ²)
Es	Elastic soil modulus, ksf
E _{sl}	Lateral modulus of soil subgrade reaction, ksf
Fr	Reduction factor for drilled shaft unit end bearing capacity
FS	Factor of safety
G	Specific gravity
G_i	Initial shear modulus, ksf
G_s	Shear modulus, ksf
Н	Depth of shear zone beneath base of foundation, ft
H _b	Vertical distance from the shaft base in a group to the top of the weak layer, ft
H _r	Height of vertical reinforcement rods placed in soil supporting a strip foundation, ft
H_{t}	Depth below footing base to weak stratum or soft clay, ft
I _c	Moment of inertia of concrete section, ft^4
Ip	Moment of inertia of pile, ft^4
Ir	Rigidity index

Symbol	Description
I _{rr}	Reduced rigidity index
I _{st} I _D	Moment of inertia of steel section, ft ⁴ Material deposit index of dilatometer test
K	Lateral earth pressure coefficient
K _o	Coefficient of earth pressure at rest
K _p	Rankine coefficient of passive pressure, $tan^2(45 + \frac{\phi}{2})$ or $\frac{1 + \sin\phi}{1 - \sin\phi}$
K_{ps}	Punching shear coefficient
K _v	Constant depending on dimensions and shape of the vane, ft^3
K _D	Horizontal stress index of dilatometer test
L	Embeded length of deep foundation, ft
LC	Critical depth at which increasing pile lengths provide no increase in end bearing resistance for Meyerhof's method, ft
L_c	Critical length between long and short pile, ft
$\rm L_{cs}$	Critical length between short and intermediate pile, ft
L_{cl}	Critical length between intermediate and long pile, ft
$\mathbf{L}_{\texttt{clay}}$	Length of pile in clay, ft
L_n	Length to neutral point n, ft
\mathbf{L}_{sand}	Length of pile in sand, ft
$\rm L_{sh}$	Horizontal length of shear zone at the foundation depth, ft
M _a	Applied bending moment on pile butt (top) in clockwise direction, kips-ft
M _y	Ultimate resisting bending moment of entire pile cross-section, kips-ft
M _B	Bending moment parallel with B, kips-ft
M_{W}	Bending moment parallel with W, kips-ft
N_c	Dimensionless bearing capacity related with cohesion

Symbol	Description
N _{cp}	Pile dimensionless bearing capacity related with cohesion
N_k	Cone factor relating undrained cohesion with cone penetration resistance, often varies from 14 to 20
N _n	Standard penetration resistance correlated to n percent energy, blows/foot
N_p	Relationship between shear modulus and undrained cohesion used in pressuremeter test, 1 + $\ln(G_s/C_u)$
Nq	Dimensionless bearing capacity factor related with surcharge
N_{qp}	Pile dimensionless bearing capacity factor related with surcharge
$\rm N_{\rm SPT}$	Average blow per foot in the soil produced by a 140 pound hammer falling 30 inches to drive a standard sampler (1.42" I.D., 2.00" O.D.) one foot
N ₆₀	Penetration resistance normalized to an effective energy delivered to the drill rod at 60 percent of theoretical free-fall energy, blows/foot
N ₇₀	Penetration resistance normalized to an effective energy delivered to the drill rod at 70 percent of theoretical free-fall energy, blows/foot
N_{γ}	Dimensionless bearing capacity factor related with soil weight in the failure wedge
$N_{\gamma_{\mathcal{P}}}$	Pile dimensionless bearing capacity factor related with soil weight in the failure wedge
\mathbf{N}_{ϕ}	$\tan^2\left[45 + \frac{\phi}{2}\right]$
OCR	Overconsolidation ratio
P	Pullout load, kips
PI	Plasticity index, percent
$\mathtt{P}_{\mathtt{max}}$	Maximum tensile force in shaft, kips
\mathbf{P}_{nu}	Pullout skin resistance force, kips
$\mathbf{P}_{\mathrm{nui}}$	Pullout skin resistance for pile element i, kips
P _u	Ultimate pullout resistance, kips

Symbol	Description
Q	Vertical load on foundation, kips
Q _a	Allowable bearing capacity force, kips
$Q_{\rm b}$	Base resistance force, kips
$Q_{\rm bu}$	Base resistance capacity, kips
$Q_{\rm bur}$	Ultimate base resistance of upper portion of underream, kips (pounds)
Q _d	Design bearing force, kips
Q _e	Applied load in elastic range, kips
Qs	Soil-shaft side friction resistance, kips
$Q_{\rm su}$	Soil-shaft side friction resistance capacity or uplift thrust, kips
$Q_{\rm sub}$	Ultimate soil shear resistance of cylinder of diameter $\rm B_{b}$ and length down to underream, kips (pounds)
$Q_{\rm sud}$	Downdrag, kips (pounds)
$Q_{\mathtt{sui}}$	Ultimate skin friction resistance of pile element i, ksf
$Q_{\mathtt{sur}}$	Ultimate skin resistance, kips (pounds)
Q_u	Ultimate bearing capacity force, kips
Q_{ug}	Ultimate load capacity of pile group, kips
$Q_{\tt ug,lower}$	Bearing capacity of base at top of lower (weak) soil, kips
$Q_{ug,upper}$	Bearing capacity in the upper soil if the softer lower soil were not present, kips
$Q_{\rm up}$	Uplift force on foundation, kips
Q_w	Working load, kips (pounds)
$Q_{\rm DL}$	Dead load of structure, kips (pounds)
R	Resultant load on foundation, $(Q^2 + T^2)^{0.5}$
R_{bc}	Scale reduction factor for end bearing capacity in clay
R_{bs}	Scale reduction factor for end bearing capacity in sand

Symbol	Description
R _d	Ratio of equivalent embedment depth to footing width, D_e/B
R _e	Eccentricity adjustment factor
R_k	Bearing ratio using CPT procedure for estimating bearing capacity
R_v	Strength reduction factor of vane shear test
S	Average penetration in inches per blow for the last 5 to 10 blows for drop hammers and 10 to 20 blows for other hammers
Sr	Spacing between vertical reinforcement rods in soil, ft
Ss	Shape factor, assume 1.000
S_u	Depth of scour, ft
SPT	Standard penetration test
Т	Horizontal (lateral) load on foundation, kips
T _a	Allowable lateral load capacity, kips
T_u	Lateral load capacity, T_{us} + T_{up} , kips
T_{ug}	Lateral load capacity of pile group, kips
T_{ul}	Ultimate lateral load capacity of long pile in cohesionless soil, kips
T_{up}	Lateral load pile capacity, kips
T_{us}	Lateral load soil capacity, kips
T_v	Torque of the vane test, kips-ft
W	Lateral length of a foundation, ft
W _p	Pile weight or pile weight including pile cap, driving shoe, capblock and anvil for double-acting steam hammers, kips
W _r	Weight of striking parts of ram, kips
$W_{\rm T}'$	Total effective weight of soil and foundation resisting uplift, kips
W′	Effective lateral length of a foundation, W - $2e_w$
Z	Section modulus I_p/c , ft ³

Symbol	Description
Z _a	Depth of the active zone for heave, ft
Z _c	Concrete section modulus, ft ³
\mathbf{Z}_{st}	Steel section modulus, ft^3
α_{a}	Adhesion factor
$\alpha_{\tt f}$	Dimensionless pile depth-width relationship factor
β	Angle of ground slope, deg
$\beta_{\tt f}$	Lateral earth pressure and friction angle factor
γ	Wet unit soil weight, lbs/ft ³
γ_{c}	Moist unit weight of weak clay, kips/ft ³
γ_{conc}	Density concrete grout, kips/ft ³
$\gamma_{\rm d}$	Dry density, kips/ft ³
$\gamma_{ m p}$	Pile density, kips/ft ³
$\gamma_{\rm s}$	Unit wet weight of sand, kips/ ³
$\gamma_{ ext{sand}}$	Unit wet weight of the upper dense sand, kips/ft ³
$\gamma_{\rm w}$	Unit weight of water, 0.0625 kips/ft ³
γ_{D}	Unit wet weight of surcharge soil within depth D, kips/ft 3
$\gamma_{\rm H}$	Wet unit weight of subsurface soil, kips/ft ³
γ_{HSUB}	Submerged unit weight of subsurface soil, $\gamma_{\scriptscriptstyle H}$ - $\gamma_{\scriptscriptstyle W}$, kips/ft³
γ′	Effective wet unit weight of soil, γ - $u_w^{},\;\text{kips/ft}^3$
$\gamma_{\rm b}'$	Effective wet unit weight of soil beneath base, kips/ft ³
γ_{c}^{\prime}	Effective wet unit weight of clay, kips/ft ³
$\gamma_{\rm s}'$	Effective wet unit weight of sand, kips/ft ³
$\gamma_{\scriptscriptstyle D}'$	Effective unit weight of soil from ground surface to foundation depth, kips/ft 3

Symbol	Description
$\gamma_{\rm H}$	Effective unit weight beneath base of foundation to depth D + H below ground surface, kips/ft ³
$\gamma_{\tt L}'$	Effective wet unit weight of soil along shaft length L, kips/ft 3
Δ	Differential movement within span length L, ft
ΔL	Pile increment, ft
δ	Angle of base tilt, deg
$\delta_{\mathtt{a}}$	Soil-shaft effective friction angle, deg
ζ_{c}	Dimensionless correction factor related with cohesion accounting for foundation geometry and soil type
$\zeta_{\rm cs}$	Dimensionless correction factor related with cohesion and shape
ζ_{ci}	Dimensionless correction factor related with cohesion and inclined loading
$\zeta_{\rm cd}$	Dimensionless correction factor related with cohesion and foundation depth
$\zeta_{c\beta}$	Dimensionless correction factor related with cohesion and ground slope
$\zeta_{c\delta}$	Dimensionless correction factor related with cohesion and base tilt
$\zeta_{\rm cp}$	As above except for piles
ζ_{γ}	Dimensionless correction factor related with soil weight in the failure wedge (repeat as above for factors s, i, d, β and $\delta)$
$\zeta_{\gamma_{\rm P}}$	As above except for piles
ζ_{q}	Dimensionless correction factor related with surcharge (repeat as above for factors s, i, d, β and $\delta)$
$\zeta_{ ext{qp}}$	As above except for piles
θ	Angle of resultant load with vertical axis, $\cos^{-1} \left[\begin{array}{c} \underline{Q} \\ R \end{array} \right]$
λ	Lambda correlation factor for skin resistance of Vijayvergiya & Focht method
ρ	Settlement, inch

Symbol	Description
$\rho_{\rm b}$	Base displacement, inch
$\rho_{\tt bu}$	Ultimate base displacement, inch
$ ho_{e}$	Elastic pile settlement, inch
$\rho_{\texttt{i}}$	Immediate plate settlement, inch
ρ_{u}	Ultimate pile settlement, inch
$\rho_{\rm z}$	Vertical displacement at depth z, ft
$\sigma_{\rm d}^{\prime}$	Effective soil or surcharge pressure at foundation depth D, $\gamma_{\scriptscriptstyle D}^{\prime\cdot} D,$ ksf
σ_{ho}	Total horizontal in situ stress, ksf
σ_{i}^{\prime}	Effective vertical stress in soil in at shaft (pile) element i, ksf
$\sigma_{\rm m}^{\prime}$	Mean effective vertical stress between the ground surface and pile tip, ksf
σ_n	Normal stress on slip path, ksf
σ_{\circ}	Reference overburden pressure, 2 ksf
$\sigma_{\rm p}'$	Maximum past pressure in soil, ksf
$\sigma_{\rm v}^{\prime}$	Effective vertical stress, ksf
$\sigma_{\rm vc}$	Total vertical pressure in soil including pressure from structure loads, ksf
$\sigma_{\rm vc}^{\prime}$	Effective total vertical pressure in soil including pressure from structure loads, ksf
$\sigma_{_{vo}}$	Vertical overburden pressure, ksf
$\sigma_{\rm vo}^{\prime}$	Effective vertical overburden pressure, ksf
$\sigma_{\rm z}^{\prime}$	Effective overburden pressure at the center of depth $$ z, 0 < z \leq L, ksf
$\sigma_{\!\scriptscriptstyle L}^{\prime}$	Effective soil vertical overburden pressure at pile base, $\gamma^{\prime\cdot}L$, ksf
$\sigma_{{\rm L}/2}^{\prime}$	Effective stress at half the pile length, ksf
τ	Shear stress, ksf (psf)
τ_{max}	Shear stress at failure, ksf (psf)

Symbol	Description
τ_{s}	Soil shear strength, ksf
τ_{u}	Field vane undrained shear strength, ksf
υ_{s}	Poisson's ratio for soil
φ	Angle of internal friction of soil, deg
$\phi_{\tt sand}$	Angle of internal friction of upper dense sand, deg
ф ′	Effective angle of internal friction of soil, deg
\$ a	Friction angle between foundation base and soil, deg
ф _а	Friction angle of granular material, deg
ψ	Angle of shear zone failure with respect to foundation base, Figure 1-3, 45 + $\phi^{\prime}/2,$ deg
ω	Angle of pile taper from vertical, deg